A parallel algorithm for the enumeration of benzenoid hydrocarbons

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Abstract

We present an improved parallel algorithm for the enumeration of fixed benzenoids B_h containing h hexagonal cells. We can thus extend the enumeration of B_h from the previous best h = 35 up to h = 50. Analysis of the associated generating function confirms to a very high degree of certainty that $B_h \sim A\kappa^h/h$ and we estimate that the growth constant $\kappa = 5.161930154(8)$ and the amplitude A = 0.2808499(1).

Keywords: Benzenoids, hexagonal polygons, exact enumerations, parallel processing, series analysis

1 Introduction

A benzenoid or planar polyhex is a special type of hydrocarbon molecule. Its hexagonal system is obtained by deleting all carbon-hydrogen bonds, leaving clusters of hexagons joined at an edge (a carbon-carbon bond). They thus appear as clusters of identical hexagons in the plane. The interior of the clusters are filled with hexagons so there are no internal holes. These structures have appeared independently in the chemical and mathematical literature. In the mathematics literature they are discussed as self-avoiding polygons on the hexagonal lattice [1] and a distinction is made between fixed and free embeddings. Fixed polygons are considered distinct up to a translation while free polygons are considered equivalent under translations, rotations and reflections. Polygons are typically enumerated according to their perimeter or area. In the chemistry literature the number of free polygons [2] has been universally considered. The number of benzenoids or planar polyhexes is equal to the number of free hexagonal self-avoiding polygons enumerated by area.

The enumeration of the number b_h of benzenoids of h cells remains an important topic in computational and theoretical chemistry. The monograph by Gutman and Cyvin [2] provides a comprehensive review of all aspects. Until a few years ago progress was slow and incremental as calculations were based on direct counting of benzenoids. As the number of these grows as $b_h \sim \kappa^h$, where the growth constant $\kappa \simeq 5.16$, it is clear that, to obtain one further term one needs more than 5 times the computing power. Up to 1989, the number of benzenoids up to h = 12 was known [2]. Ten years later this had been improved to h = 21 [3], while more recently, the number of benzenoids up to h = 24 was obtained [4]. Thus one extra term per year was found on average, reflecting a steady 5-fold increase per annum in a combination of processor speed and resources. In 2002 [5] a major break-through was obtained using a different type of algorithm that enabled the number of *fixed* benzenoids B_h to be enumerated for $h \leq 35$ and b_h was then obtained to the same size by using direct counting algorithms to enumerate benzenoids possessing certain symmetries, e.g. they may be symmetric with respect to an axis of reflection or certain rotations. The algorithm for enumerating B_h is in fact exponentially faster than direct counting, with both time and memory growing approximately as 1.65^h . Its drawbacks are that it is much more memory intensive than direct counting, for which memory requirements are negligible, as well as being much more difficult to implement.

In [5] it was shown that there exists a growth constant κ such that

$$\lim_{h \to \infty} B_h^{1/h} = \kappa \tag{1}$$

and the universally accepted, but as yet unproved, conjecture

$$B_h \sim A \kappa^h h^\theta \text{ as } h \to \infty$$
 (2)

for the asymptotic form for B_h was confirmed to a high degree of certainty. It is widely accepted that for models such as benzenoids, other self-avoiding polygon models enumerated by area and polyominoes (or lattice animals) the exponent θ is given by the Lee-Yang edge singularity exponent [6] and thus $\theta = -1$ for benzenoids. Numerical analysis [5] confirmed this conjecture to a very high degree of certitude and yielded the estimate $\kappa = 5.16193016(8)$ for the growth constant and A = 0.2808491(1) for the critical amplitude.

In this paper we describe an efficient parallel version of the algorithm used in [5] and extend the count for fixed benzenoids up to h = 50. We do not attempt to count b_h since asymptotically $B_h = 12b_h$ so any results regarding the asymptotic behaviour of B_h and b_h are essentially the same (and the ratio of the two sequences B_h/b_h converge rapidly to its asymptotic limit as evidenced by the fact that $12 - B_{35}/b_{35} \simeq 1.355 \times 10^{-10}$). Furthermore the direct counting algorithms for benzenoids with a symmetry have computational complexity λ^h where $\lambda = \kappa^{1/k}$ if enumerating benzenoids with a k-fold symmetry so that in the worst case we have $\lambda = \sqrt{\kappa} \simeq 2.27$, which is a much worse asymptotic growth than that achieved with the algorithm for fixed benzenoids. Our analysis of the extended data yields the even more precise estimates $\kappa = 5.161930154(8)$ and a revised estimate for the critical amplitude A = 0.2808499(1).

2 Computer algorithm

A detailed description of the original computer algorithm can be found in [5]. For this work we use a slightly different algorithm and we have therefore chosen to describe it in some detail below before specifying how it can be turned into an efficient parallel algorithm.

2.1 Finite lattice algorithm

We count the number of fixed benzenoids using the so-called finite lattice method pioneered by Enting [7]. In this method the number of benzenoids are obtained by calculating the



Figure 1: A snapshot of the boundary line (dashed line) during the transfer matrix calculation on the brick-work lattice. Benzenoids are enumerated by successive moves of the kink in the boundary line, as exemplified by the position given by the dotted line, so that two vertices at a time is added to the rectangle. To the left of the boundary line we have drawn (shaded cells) an example of a partially completed benzenoid.

contributions from benzenoids contained within finite sub-lattices. As in [1, 5] we embed the hexagonal lattice in the square lattice as the brick-work lattice (see Fig. 1) and our finite lattices are rectangles of width W and length L. The minimum number of cells needed to span a rectangle from top to bottom and left to right is essentially $W + \max(0, L - (W+1)/2)$ (simply note that a single 'line' of cells starting in the top-left corner and going down the diagonal contains W cells and extends (W + 1)/2 cells to the right). So benzenoids up to a maximal size h_{\max} can be counted be combining the counts from all finite $W \times L$ lattices with $W + \max(0, L - (W + 1)/2) \leq h_{\max}$.

The number of benzenoids in a given rectangle is calculated using transfer-matrix techniques. The transfer matrix (TM) technique involves drawing a boundary line through the rectangle intersecting a set of up to W + 1 edges. Benzenoids in a given rectangle are enumerated by moving the boundary line so as to add two vertices (or a single cell) at a time as shown in Fig. 1. In this fashion we build up the rectangle column by column with each column built up cell by cell. As we move the boundary line it intersects partially completed benzenoids consisting of disjoint loops that must all be connected to form a single benzenoid. This TM algorithm is used for rectangles where $L \ge W$. Note that the hexagonal lattice (or bricklayer lattice) is not symmetric with respect to rotation. So for rectangles with L < Wwe choose instead to let the boundary line from the bottom to the top of the rectangle. This ensures that the number of edges cut by the boundary line is minimal and at most $2h_{max}/3$. The TM algorithm in the two cases are essentially identical and differ only in 'surface' effects. Below we give some further details of the TM algorithm.

To avoid situations leading to graphs with more than a single component we have to forbid a loop to close on itself if the boundary line intersects any other loops. So two loop ends can



Figure 2: The two different update cases encountered in the move of the TM boundary line. Red (blue) edges indicate the kink edges before (after) the move.

only be joined if they belong to different loops or all other edges are empty. To exclude loops which close on themselves we need to label the occupied edges in such a way that we can easily determine whether or not two loop ends belong to the same loop. The most obvious choice would be to give each loop a unique label. However, on two-dimensional lattices there is a more compact scheme relying on the fact that two loops can never intertwine. Each end of a loop is assigned one of two labels depending on whether it is the lower end or the upper end of a loop. Each configuration along the boundary line can thus be represented by a set of edge states or a state vector $s = \{\sigma_i\}$, where

$$\sigma_i = \begin{cases}
0 & \text{empty edge,} \\
1 & \text{lower end of a loop,} \\
2 & \text{upper end of a loop.}
\end{cases}$$
(3)

With this encoding the state along the boundary line in Fig. 1 is $s = \{01010002212\}$. It is easy to see that this encoding uniquely describes which loop-ends are connected. In order to find the upper loop-end, matching a given lower end, we start at the lower end and work upwards in the configuration counting the number of '1's and '2's we pass (the '1' of the initial lower end is *not* included in the count). We stop when the number of '2's exceeds the number of '1's. This '2' marks the matching upper end of the loop.

When the boundary line is moved we encounter two different cases as we add a new cell as illustrated in Fig. 2. When building up a new column we alternate between the two cases. For each configuration of occupied or empty edges along the boundary, we maintain a generating function for partially completed benzenoids. The generating function is a (truncated) polynomial $p_s(q)$, where s is the state vector specifying the 'source' configuration. When the boundary line is moved, a given state vector s is transformed into two new state 'target' vectors t_1 and t_2 and $q^{k_1}p_s(q)$ is added to $p_{t_1}(q)$ and $q^{k_2}p_s(q)$ is added to $p_{t_2}(q)$, where k_1 and k_2 are 1 or 0 depending on whether the new cell is part of the benzenoid or not. It is quite simple to determine whether a newly added unit cell belongs to a benzenoid or not. Moving through a configuration we note that as we reach the first occupied edge we pass from the outside to the inside of a benzenoid, the next occupied edge takes us to the outside again, and so on. In this fashion all unit cells intersected by the boundary line are uniquely assigned to the interior or exterior of a benzenoid.

In Fig. 3 and 4 we illustrate the possible new configurations of the edges in the kink of the boundary line as we add a new cell. The actual update rules will depend not only on the



Figure 3: The possible updates in Case 0 when the input state (left-most column) has 0, 1 or 2 occupied edges. The right-most columns shows the possible outputs.

number of occupied kink edges in the input configuration but on their states as well. The update rules are summarised in Table I and a few comments are in order. The first five rows should be self-explanatory. In rows six and nine over-lining of the output state means that we have connected two lower (upper) loop-ends and we therefore have to relabel one of the matching upper (lower) loop-ends in the target state as a lower (upper) state. The matching loop-ends are easily located as explained below (3). In row seven Acc means accumulate into final count for B_h if valid. Here we are forming a closed loop and this is only allowed if there are no other occupied edges in the state (otherwise we either produce graphs with several separate components or interior holes neither of which are permissible benzenoids). In Case 1 row seven the second output can never occur. Finally in row eight we connect upper and lower loop-ends from two different loops. This is always allowed and the outputs states need no further comments.

A major improvement to the basic method can be obtained by using the approach first adopted in [8]. As stated earlier we require valid benzenoids to span the rectangle in *both* directions. In other words we directly enumerate benzenoids of width exactly W and length L. To implement the TM algorithm efficiently we use several memory and time saving methods. The most important is what we call *pruning*. This procedure, details of which are given in [8], allows us to discard most of the possible configurations for large W because they only contribute to benzenoids of size greater than h_{max} . Briefly this works as follows. Firstly,



Figure 4: Similar to Fig. 3 but for Case 1.

for each configuration we keep track of the current minimum number of cells h_{cur} already inserted to the left of the boundary line. Secondly, we calculate the minimum number of additional cells h_{add} required to produce a valid benzenoid. There are three contributions, namely the number of cells required to close the benzenoid, the number of cells needed (if any) to ensure that the benzenoid touches both the lower and upper border, and finally the number of cells needed (if any) to extend at least W cells in the length-wise direction (remember we are looking at rectangles with $L \geq W$). If the sum $h_{cur} + h_{add} > h_{max}$ we can discard the partial generating function for that configuration, and of course the configuration itself, because it won't make a contribution to the benzenoid count up to the size we are trying to obtain.

Those familiar with algebraic languages will recognize that each configuration of labeled loop-ends forms a Motzkin word [9]. It is known that the number of Motzkin words of length m grows like 3^m . The maximal number of bonds intersected by the boundary line grows as $2h_{\text{max}}/3$. This implies that the complexity of enumerating benzenoids of size h grows as $3^{2h/3} \simeq 2.08^h$, multiplied by some polynomial in h. Thus the basic transfer-matrix approach already provides a dramatic improvement over direct enumeration algorithms, which have complexity 5.16^h . With the further improvements outlined above, it is not possible to give a theoretical analysis of the computational complexity of the algorithm, but an empirical analysis in [5] suggested that the improvements reduce the complexity to λ^h with $\lambda \simeq 1.65$. For this work a slight further improvement has been obtained reducing λ to 1.56 or so. In

Case 0			Case 1			
Input	Output		Input	Out	tput	
·00'	<i>`</i> 00'	'12'	,00,	<i>`</i> 00'	`'12'	
'01'	'01'	'10'	'01'	'01'	'10'	
<i>`</i> 02'	<i>`</i> 02'	<i>`20'</i>	' 02'	<i>`</i> 02'	<i>`20'</i>	
'10'	'01'	'10'	'10'	'01'	'10'	
'20'	<i>`</i> 02'	<i>`</i> 20'	'20'	` 02 `	<i>'20'</i>	
'11'	$\overline{00}$	'11'	'11'	$\overline{00}$	$(\overline{12})$	
'12'	Acc	'12'	'12'	Acc		
'21'	<i>`</i> 00'	<i>'21'</i>	'21'	<i>`</i> 00'	'12'	
<i>`22'</i>	$\overline{00}$	'22'	'22'	· <u>00</u> ,	· <u>12</u> ,	

Table I: Update rules for Case 0 and Case 1

addition some further memory saving strategies were adopted. The effectiveness of these can be gauged by noting that in [5] the calculation of B_h up to h = 35 required some 5Gb of memory and we can now achieve a similar task using only some 250Mb of memory.

The integers B_h become very large and exceed 2^{64} which causes overflow when using 64bit integers. The solution to this problem is use modular arithmetic and do the calculation modulo several numbers p_i and then reconstruct the true B_h using the Chinese remainder theorem [10]. In our case it sufficed to do the calculations modulo $p_0 = 2^{62}$ and $p_1 = 2^{62} - 1$. It should be noted that the computationally expensive part of our algorithm is pruning. Compared to this the time taken to perform the modular calculations updating the partial generating functions is insignificant. Since the calculations were done on a shared facility CPU time was more of a premium than memory and we did the calculation using both p_0 and p_1 in a single run. Total CPU time expended on the calculations was approximately 22000 CPU hours.

In Table II we list the additional 15 terms for B_h with $h \ge 36$ obtained in this work, the original 35 terms can be found in [5] or down-loaded from our web-site [13].

2.2 Parallelisation

The computational complexity of the FLM grows exponentially with the number of terms one wishes to calculate. It is therefore little wonder that implementations of the algorithms have always been geared towards using the most powerful computers available. By now parallel computing is well established as the paradigm for high performance computing and in particular cluster computing has emerged as the dominant platform for large scale computing facilities. The transfer-matrix algorithms used in the calculations of the finite lattice contributions are eminently suited for parallel computations.

The most basic concerns in any efficient parallel algorithm is to minimise the communication between processors and ensure that each processor does roughly the same amount of work and use similar amounts of memory. In practice one naturally has to strike some compromise and accept a certain degree of variation across the processors.

Table II: Number of fixed benzenoids B_h of size $h \ge 36$.

h	B_h
36	352506828543839738006802
37	1771125269041561567830953
38	8905113919188230264955009
39	44804571829235959198699855
40	225570974088699920561748746
41	1136340745302289809680018862
42	5727773558054438208070950886
43	28887056504374868913302241736
44	145763914212751560334802981991
45	735894997233174457602406978869
46	3716988842355112053567240722854
47	18783102592560998779533576292617
48	94958908613774943408509332060260
49	480273434248924455452231252618009
50	2430068453031180290203185942420933

One of the main ways of achieving a good parallel algorithm using data decomposition is to try to find an invariant under the operation of the updating rules. That is we seek to find some property about the configurations along the boundary line which does not alter in a single iteration. The algorithm for the enumeration of benzenoids is quite complicated since not all possible configurations occur due to pruning and an update at a given set of edges might change the state of an edge far removed, e.g., when two lower loop-ends are joined we have to relabel one of the associated upper loop-ends as a lower loop-end in the new configuration. However, there still is an invariant since any edge not directly involved in the update cannot change from being empty to being occupied and vice versa. That is only the edges at the kink of the boundary line can change their occupation status. This invariant allows us to parallelise the algorithm in such a way that we can do the calculation completely independently on each processor with just two redistributions of the data set each time an extra column is added to the lattice.

The main points of the algorithm are summarized below:

- 1. With the boundary line straight (having no kinks) distribute the configurations and their generating functions across processors so that configurations with the same occupation pattern along the *lower* half of the boundary line are placed on the same processor.
- 2. Do the TM update inserting the top-half of a new column. This can be done *independently* by each processor because the occupation pattern in the lower half remains unchanged.
- 3. Upon reaching the half-way mark redistribute the data so that configurations with the same occupation pattern along the *upper* half of the boundary line are placed on the same processor.

0

Proc.	Total time	Run time	Max Conf	Min Conf	Max Term	Min Term
1	60:13	60:20:16	107350066		207111142	
2	61:53	30:59:09	52982622	52435395	102711198	102666398
4	62:28	15:38:07	26389619	26183924	51559593	51025667
8	63:17	7:55:17	13289367	13078219	26179885	25492182
16	69:28	4:21:40	6725270	6486246	13245615	12717598
32	69:05	2:10:17	3440269	3274193	6871820	6347966
64	71:33	1:07:51	1768626	1616220	3839775	3191842

Table III: CPU-time and memory use for the parallel algorithm for enumerating benzenoids of maximal size 43 at width 22.

- 4. Do the TM update inserting the bottom-half of a new column.
- 5. Go back to 1.

The redistribution among processors was done as follows:

- 1. On each processor run through the configurations to establish the occupation pattern (in the lower or upper half of the boundary) c of each configuration and calculate, n(c), the number of configurations with a given pattern.
- 2. Calculate the global sum of n(c).
- 3. Sort the global sum n(c).
- 4. Assign each pattern to a processor p_i as follows:
 - (a) Set $p_i = 0$.
 - (b) Assign the most frequent unassigned pattern c to processor p_i .
 - (c) If the number of configurations assigned to p_i is less than the number of configurations assigned to processor 0 then assign the *least* frequent unassigned patterns to p_i until the desired inequality is achieved.
 - (d) Set $p_i = (p_i + 1) \mod N_p$, where N_p is the number of processors.
 - (e) Repeat from (b) until all patterns have been assigned.
- 5. On each processor run through the configurations sending each configuration to its assigned processor.

The bulk of the calculations were performed on the facilities of the Australian Partnership for Advanced Computing (APAC). The APAC facility is an SGI Altix cluster with 1920 1.6 Ghz Itanium2 processors grouped into 30 partitions with 64 processors each. The cluster has a total peak speed over 11Tflops. Nodes are connected via a SGI's NUMAlink with a latency < 2 us (MPI) and bandwidth of 3.2 Gb/sec bidirectional. We used up to 128 processors per run using a maximum of 230Gb of memory and 22000 CPU hours.

In Table III we have listed the time and memory use of the algorithm for $h_{\rm max} = 43$ at W = 22 using from 1 to 64 processors. The memory use of the single processor job was about 3Gb. Firstly, we look at the issue of balancing the memory use of the parallel algorithm. By design we are attempting to balance this to the greatest extend possible since in a cluster environment memory is often the most crucially constrained resource. This aspect is examined via the numbers in columns 4-7. At any given time during the calculation each processor handles a subset of the total number of configurations. For each processor we monitor the maximal number of configurations and terms retained in the generating functions. The balancing can be roughly gauged by looking at the largest (Max Conf) and smallest (Min Conf) maximum number of configurations handled by individual processors during the execution of the program. In columns 6 and 7 are listed the largest (Max Term) and smallest (Min Term) number of terms retained in the generating functions associated with the subset of configurations. As can be seen the algorithm is quite well balanced. Even with 64 processors, where each processor uses only about 50Mb of memory, the difference between the processor handling the maximal and minimal number of configurations is less than 10%. For the total number of terms retained in the generating functions the difference is less than 20%. So our aim of balancing memory use has clearly been met.

The next issue is that of balancing the CPU time used by the algorithm. As can be seen the algorithm scales reasonable well from 1 to 64 processors since the total combined CPU time (column 2, format is hours: minutes) used by all processors increase only by about 10%. Likewise the run time (column 3, format is hours:minutes: seconds) of the program is approximately halved when the number of processors is doubled. This is not quite as good a scaling as achieved for some previous algorithms [11, 12] where the total CPU time stayed constant. The main reason for the discrepancy is that the time consuming part of our algorithm is the pruning. For "simpler" problems on the square lattice it turned out that the time consumption was fairly constant irrespective of the occupation pattern. Pruning benzenoid configurations is more complicated¹. In our previous work [11, 12] the CPU time used in communication tasks never exceeded 10% of the total. However, for benzenoids a simple timing of the various routines show that as much as 30% of the time was used in communication task. We believe most of the additional time use is due to 'latency'. That is the task of redistributing the data among processors must complete before further processing can be done. The redistribution is thus blocking. If certain subsets of configurations sitting on processor p_i take long to process they can thus lead to imbalances where other processors must wait for the completion of the calculation on processor p_i . Unfortunately it is not possible to determine a priory if a certain set of configurations with a particular occupation pattern are 'slow'. However, it does suggest that there is some room for improvement to the redistribution, perhaps by including additional information (say which borders have been touched or the total number of occupied edges) so as to further sub-divide the set of configurations thus making it easier to balance the workload. Another option would be to monitor the time used to process each configuration and use this as part of the information used in the redistribution. However, this should not come at the cost of unbalanced memory use. These possibilities remain to be explored in future work.

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¹We won't give details here but just note that on the square lattice the three contributions to h_{add} essentially de-couple and can be determined more or less independently. This is no longer the case on the hexagonal lattice vastly complicating the pruning.

Table IV: Estimates for the critical point $q_c = 1/\kappa$ and critical exponent $-1 - \theta$ as obtained from 2nd and 3rd order differential approximants with L being the degree of the inhomogeneous polynomial.

	2nd order app	proximants	3rd order approximants		
L	$q_c = 1/\kappa$	$-1-\theta$	$q_c = 1/\kappa$	-1- heta	
0	0.19372598474(16)	-0.00000136(87)	0.19372598440(23)	-0.00000055(37)	
2	0.19372598448(24)	-0.00000077(43)	0.193725984286(90)	-0.00000036(16)	
4	0.19372598440(11)	-0.00000056(42)	0.19372598436(22)	-0.00000051(39)	
6	0.19372598443(27)	-0.00000068(51)	0.19372598416(16)	-0.00000009(41)	
8	0.19372598441(32)	-0.00000052(93)	0.193725984182(83)	-0.00000013(21)	
10	0.19372598444(19)	-0.00000069(38)	0.193725984205(94)	-0.0000020(23)	

3 Numerical analysis

From the coefficients B_h we have the first 50 terms in the respective generating function,

$$G(q) = \sum_{h} B_{h}q^{h} \sim A(q)\log(1-\kappa q)$$
(4)

where the leading asymptotic behaviour follows from (2) with the radius of convergence of the generating function given by $q_c = 1/\kappa$. In order to obtain the singularity structure of the generating function we used the numerical method of differential approximants [14]. Very briefly, in this method we approximate the generating function by the solution of a linear, inhomogeneous, ordinary differential equation (ODE) with polynomial coefficients. That is to say, we insist that the power series expansion of the solution of the ODE agrees, term by term, with the known coefficients of the generating function. One can increase the degree of the polynomials and the order of the underlying differential equation until there are no more known coefficients. One then solves the ODE in the standard manner, the critical point being given by the first zero on the positive real axis of the polynomial multiplying the highest derivative, while the corresponding exponent is obtained from the solution of the appropriate indicial equation [15]. A substantial number of such differential approximants are constructed, and a statistical procedure is used to estimate the critical point and critical exponent.

In Table IV we have listed estimates for the critical point $q_c = 1/\kappa$ and critical exponent $-1-\theta$ obtained from a differential approximant analysis [14]. The estimates were obtained by averaging over many individual approximants using a procedure (see [16] for details) which automatically discard any spurious outlying approximants. Each approximant used at least 42 terms of the series and the degree of the inhomogeneous polynomial was varied from L = 0 to 10. Taken together the estimates are consistent with the conjectured exact value $\theta = -1$ for the critical exponent, while for the critical point we obtain $q_c = 0.1937259843(3)$ or for the growth constant $\kappa = 5.161930154(8)$.

While the estimates listed in Table IV are very accurate one issue which always arises in a differential approximant analysis is the possibility of systematic bias. In particular it is possible that the estimates have not yet converged to their true asymptotic values. In order to address this possibility we plot in Fig. 5 individual estimates for the critical point q_c and



Figure 5: Estimates for the critical point q_c (top panels) and critical exponent $-1-\theta$ (bottom panels) vs the maximal size h (or number of terms) used in the differential approximant analysis. Each dot represents a data point obtained from a 3rd order approximant with L = 0, 2, ..., 10. The left panels show a view of most approximants while the right panels are a more detailed view at the data for high values of h.

critical exponent $-1 - \theta$ as a function of the maximal size or number of terms h used to form the differential approximant. From this figure it is clear that the estimates do settle down to very well defined values. There is no sign of any systematic drift in the estimates for h > 40 or so. In particular the conclusion that $\theta = -1$ exactly appear to be completely safe. Likewise the estimates for q_c settle down to a value in full agreement with the estimate q_c :



Figure 6: Estimates for the leading amplitude $a_1 vs 1/h$ where h is the maximal size used in the fit to the asymptotic for () for the coefficients B_h . The plot in the right panel is a more detailed view of the data in the left panel.

Now that the exact value of θ has been confirmed and an accurate estimate for κ obtained we turn our attention to the "fine structure" of the asymptotic form of the coefficients. In particular we are interested in obtaining accurate estimates for the leading critical amplitude A. Our method of analysis consists in fitting the coefficients to an assumed asymptotic form. The asymptotic form (2) for the coefficients B_h only explicitly gives the leading contribution. In general one would expect corrections to scaling given by a set of correction-to-scaling exponents. However, as argued elsewhere [17] and confirmed in the previous study [5] there is no sign of non-analytic correction-to-scaling exponents. The up shot of this is that B_h follows the asymptotic form

$$B_h = \kappa^h \left[a_1/h + a_2/h^2 + a_3/h^3 + \dots + \mathcal{O}(\exp(-h)) \right].$$
(5)

We then obtain estimates for $a_1 = A$ by fitting B_h to this form. That is we truncate (5) after m terms, take a sub-sequence of coefficients $\{B_h, B_{h-1}, \ldots, B_{h-m+1}\}$, plug into the formula above and solve the resulting m linear equations to obtain estimates for the amplitudes. It is then advantageous to plot estimates for the leading amplitude a_1 against 1/h for several values of m. The results are plotted in the left panel of figure 6. We clearly have very well behaved estimates. In the right panel we take a more detailed look at the data and from the plot we estimate that $a_1 = 0.2808499(1)$. We notice that as more and more correction terms are added (m is increased) the plots of the amplitude estimates exhibits less curvature and the slope become less steep. This is very strong evidence that (5) indeed is the correct asymptotic form for B_h .

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