ON THE LATTICE PROGRAMMING GAP OF THE GROUP PROBLEMS

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ABSTRACT. Given a full-dimensional lattice $\Lambda \subset \mathbb{Z}^k$ and a cost vector $l \in \mathbb{Q}^k_{>0}$, we are concerned with the family of the group problems

$$(0.1) \qquad \min\{l \cdot x : x \equiv r (\bmod \Lambda), x \geq 0\}, \quad r \in \mathbb{Z}^k.$$

The *lattice programming gap* $\mathrm{gap}(\Lambda, l)$ is the largest value of the minima in (0.1) as r varies over $\mathbb{Z}^k$. We show that computing the lattice programming gap is NP-hard when k is a part of input. We also obtain lower and upper bounds for $\mathrm{gap}(\Lambda, l)$ in terms of l and the determinant of Λ.

1. INTRODUCTION AND STATEMENT OF RESULTS

Consider the integer programming problem

$$(1.1) \qquad \min\{c \cdot x : Ax = b, x \geq 0, x \text{ is integer}\}.$$

Gomory [11] defined a group relaxation of (1.1) as follows. Let B and N be the index sets of basic and nonbasic variables for an optimal basic solution to the linear programming relaxation $\min\{c \cdot x : Ax = b, x \geq 0\}$ of (1.1). Then the problem (1.1) can be written as

$$(1.2) \quad \min\{c_B \cdot x_B + c_N \cdot x_N : A_B x_B + A_N x_N = b, x_B, x_N \geq 0,$$
$$x_B, x_N \text{ are integer}\}$$

and a relaxation of (1.2) is obtained by removing the restriction $x_B \geq 0$:

$$(1.3) \quad \min\{c_B \cdot x_B + c_N \cdot x_N : A_B x_B + A_N x_N = b, x_N \geq 0,$$
$$x_B, x_N \text{ are integer}\}.$$

Hence (1.3) is a lower bound for (1.1) and it can be used in any branch and bound procedure.

The constraints $A_B x_B + A_N x_N = b$ in (1.3) can be written in the equivalent form $x_B = A_B^{-1} b - (A_B^{-1} A_N) x_N$. Thus, given any nonnegative integral vector x_N, the vector x_B is integer if and only if $(A_B^{-1} A_N) x_N \equiv A_B^{-1} b (\bmod 1)$. Setting $c'_N = c_N - c_B A_B^{-1} A_N$, we can rewrite (1.3) as

$$(1.4) \min\{c'_N \cdot x_N : (A_B^{-1} A_N) x_N \equiv A_B^{-1} b (\bmod 1), x_N \geq 0, x_N \text{ is integer}\}.$$

The program (1.4) is called the *Gomory's group relaxation* for (1.1).

In this paper we fix a cost vector $c \in \mathbb{Q}^n$ and for a matrix $A \in \mathbb{Z}^{d \times n}$ of rank d and $b \in \mathrm{Sg}(A) = \{Au : u \in \mathbb{Z}^n_{\geq 0}\}$ consider the integer program

$$IP_c(A, b) = \min\{c \cdot x : Ax = b, x \in \mathbb{Z}^n_{\geq 0}\}.$$

For simplicity, we assume that the cone $\mathrm{cone}(A) = \{Ax : x \geq 0\}$ is pointed and that the subspace $A^{\perp} = \{x \in \mathbb{R}^n : Ax = 0\}$, the kernel of A, intersects the nonnegative orthant $\mathbb{R}^n_{\geq 0}$ only at the origin. This assumption guarantees that $IP_c(A, b)$ is bounded for all $b \in \mathrm{Sg}(A)$.

Consider the $(n-d)$-dimensional lattice $\mathcal{L}(A) = A^{\perp} \cap \mathbb{Z}^n$. The program $IP_c(A, b)$ is equivalent to the lattice program

$$(1.5) \qquad\qquad \min\{c \cdot x : x \equiv u(\,\mathrm{mod}\,\mathcal{L}(A)), x \geq 0\}\,,$$

where u is any integer solution of the equation $Ax = b$.

A subset τ of $\{1, \ldots, n\}$ partitions $x \in \mathbb{R}^n$ as x_{τ} and $x_{\bar{\tau}}$, where x_{τ} consists of the entries indexed by τ and $x_{\bar{\tau}}$ the entries indexed by the complimentary set $\bar{\tau}$. Similarly, the matrix A is partitioned as A_{τ} and $A_{\bar{\tau}}$. Let τ be the set of indices of the basic variables for an optimal solution to the linear relaxation $LP_c(A, b) = \min\{c \cdot x : Ax = b, x \geq 0\}$ of the integer program $IP_c(A, b)$. Let π_{τ} be the projection map from $\mathbb{R}^n$ to $\mathbb{R}^{n-d}$ that forgets all coordinates indexed by τ and let $\Lambda(A) = \pi_{\tau}(\mathcal{L}(A))$. The lattices $\mathcal{L}(A)$ and $\Lambda(A)$ are isomorphic (see e.g. Section 2 in [23]) and the Gomory's group relaxation for $IP_c(A, b)$ is equivalent to the *lattice program*

$$(1.6) \qquad\qquad \min\{c'_{\bar{\tau}} \cdot x : x \equiv u_{\bar{\tau}}(\,\mathrm{mod}\,\Lambda(A)), x \geq 0\}\,,$$

where $c'_{\bar{\tau}} = c_{\bar{\tau}} - c_{\tau} A_{\tau}^{-1} A_{\bar{\tau}}$. Note that the vector $c'_{\bar{\tau}}$ is nonnegative. For simplicity we will consider in this paper the *generic* case, when all entries of $c'_{\bar{\tau}}$ are positive.

The group relaxations can be defined for various sets of variables. Wolsey [24] introduced the *extended group relaxations* obtained by dropping nonnegativity restrictions on the variables indexed by each subset of τ. Hoşten and Thomas [16] studied the set of all group relaxations obtained by dropping nonnegativity restrictions on the variables indexed by each face of a polyhedral complex associated with A and c. For further details on the classical theory of group relaxations we refer the reader to [17] and [2].

In this paper we will consider the group relaxations in the following general form. For a fixed cost vector $l \in \mathbb{Q}^k_{>0}$, a k-dimensional lattice $\Lambda \subset \mathbb{Z}^k$ and $r \in \mathbb{Z}^k$ we are concerned with the lattice program (also referred to as the *group problem*)

$$(1.7) \qquad\qquad \min\{l \cdot x : x \equiv r(\,\mathrm{mod}\,\Lambda), x \geq 0\}\,.$$

Let $m(\Lambda, l, r)$ denote the value of the minimum in (1.7). We are interested in the *lattice programming gap* $\mathrm{gap}(\Lambda, l)$ of (1.7) defined as

$$(1.8) \qquad\qquad \mathrm{gap}(\Lambda, l) = \max_{r \in \mathbb{Z}^k} m(\Lambda, l, r)\,.$$

The lattice programming gaps were introduced and studied for sublattices of all dimensions in $\mathbb{Z}^k$ by Hoşten and Sturmfels [15]. The algebraic and algorithmic results on the lattice programming gaps obtained in [15] have applications to the statistical theory of multidimensional contingency tables.

For fixed k the value of $\mathrm{gap}(\Lambda, l)$ can be computed in polynomial time (see Section 3 in [15] and [8]). The first result of this paper shows that computing $\mathrm{gap}(\Lambda, l)$ is NP-hard when k is a part of input.

Theorem 1.1. *Computing* $\mathrm{gap}(\Lambda, l)$ *is NP-hard.*

The proof of Theorem 1.1 is based on a connection between the lattice programming gaps and the Frobenius numbers. Computing Frobenius numbers is NP-hard due to the well-known result of Ramírez Alfonsín [21].

Our next goal is to obtain the lower and upper bounds for $\mathrm{gap}(\Lambda, l)$ in terms of the parameters of the lattice program (1.7). The bounds on the lattice programming gap provide bounds on the possible objective solutions when considering Gomory's group relaxation type problems. We show that the obtained lower bound is optimal and that the upper bound has the optimal order. The proofs are based on recent results of Marklof and Strombergson [20] on the diameters of circulant graphs and on the estimates of Fukshansky and Robins [10] for the Frobenius numbers.

For a given closed bounded convex set K with nonempty interior in $\mathbb{R}^k$ and a k-dimensional lattice $\Lambda \subset \mathbb{R}^k$, the *covering radius* of K with respect to Λ is defined as $\rho(K, \Lambda) = \min\{r > 0 : rK + \Lambda = \mathbb{R}^k\}$. Let X_k be the set of all k-dimensional lattices $\Lambda \subset \mathbb{R}^k$ of determinant one, let $\Delta = \{x \in \mathbb{R}_{\geq 0}^k : \sum_{i=1}^k x_i \leq 1\}$ be the standard k-dimensional simplex and let $\rho_k = \inf_{\Lambda \in X_k} \rho(\Delta, \Lambda)$. We obtain the following optimal lower bound for $\mathrm{gap}(\Lambda, l)$.

Theorem 1.2.   (i) *For any $l \in \mathbb{Q}_{>0}^k$, $k \geq 2$, and any k-dimensional lattice $\Lambda \subset \mathbb{Z}^k$*

$$(1.9) \qquad \mathrm{gap}(\Lambda, l) \geq \rho_k (\det(\Lambda) l_1 \cdots l_k)^{1/k} - \sum_{i=1}^k l_i .$$

(ii) *For any $c \in \mathbb{Q}_{>0}^{k+1}$, $k \geq 2$, and any $\epsilon > 0$, there exists a matrix $A \in \mathbb{Z}^{1 \times (k+1)}$ such that for all $b \in \mathrm{Sg}(A)$ the knapsack problem $LP_c(A, b)$ has a unique solution with nonbasic variables indexed by $\sigma = \{1, \ldots, k\}$ and for $l = c'_\sigma$*

$$(1.10) \qquad \mathrm{gap}(\Lambda(A), l) < (\rho_k + \epsilon)(\det(\Lambda(A)) l_1 \cdots l_k)^{1/k} - \sum_{i=1}^k l_i .$$

Furthermore, there exists $b' \in \mathrm{Sg}(A)$ such that the optimal value of $IP_c(A, b')$ is equal to $\mathrm{gap}(\Lambda(A), l) + c_{\bar{\sigma}} A_\sigma^{-1} b'$.

The only known values of ρ_k are $\rho_1 = 1$ and $\rho_2 = \sqrt{3}$ (see [9]). It was proved in [3], that $\rho_k > (k!)^{1/k}$. Thus we obtain the following estimate.

Corollary 1.1. *For any $l \in \mathbb{Q}_{>0}^k$, $k \geq 2$, and any k-dimensional lattice $\Lambda \subset \mathbb{Z}^k$*

$$(1.11) \qquad \mathrm{gap}(\Lambda, l) > (k! \det(\Lambda) l_1 \cdots l_k)^{1/k} - \sum_{i=1}^k l_i .$$

For sufficiently large k the bound (1.11) is not far from being optimal. Indeed, $\rho_k \leq (k!)^{1/k}(1 + O(k^{-1} \log k))$ (cf. [7]).

Group relaxations provide the lower bounds for integer programs $IP_c(A, b)$. From this viewpoint, part (i) of Theorem 1.2 and Corollary 1.11 estimate the largest possible value that such a bound can take. Part (ii) of Theorem 1.2 also shows that the obtained result is optimal in the case of knapsack problems.

Let $|\cdot|$ denote the Euclidean norm and let γ_k be the k-dimensional Hermite constant (see i.e. Section IX.7 in [6]). We give the following upper bound for $\mathrm{gap}(\Lambda, l)$ (and hence for the minimum in (1.6)).

Theorem 1.3. *For any $l \in \mathbb{Q}_{>0}^k$, $k \geq 2$, and any k-dimensional lattice $\Lambda \subset \mathbb{Z}^k$*

$$(1.12) \qquad \mathrm{gap}(\Lambda, l) \leq \frac{k \gamma_k^{k/2} \det(\Lambda)(\sum_{i=1}^k l_i + |l|)}{2} - \sum_{i=1}^k l_i .$$

The known exact values of γ_k^k are 1, 4/3, 2, 4, 8, 64/3, 64, 256 (Sloan's sequence A007361 in [1]). By a result of Blichfeldt (see, e.g. [14]) $\gamma_k \leq 2 \left(\frac{k+2}{\sigma_k}\right)^{2/k}$, where σ_k is the volume of the unit k-ball; thus $\gamma_k = O(k)$. The precision of the bound (1.12) depends on the estimates for the covering radius of a simplex, associated with the cost vector l, with respect to the lattice Λ. It follows from results in [4, Section 6] that the order $\mathrm{gap}(\Lambda, l) = O_{k,l}(\det(\Lambda))$, where the constant depends on k and l, cannot be improved.

A widely used approach (see e.g. [5]) is to consider a group relaxation induced by a single row i: $\sum_{j \in N} \hat{a}_{ij} x_j \equiv \hat{b}_i (\mathrm{mod}\ 1)$ of the matrix constraint in (1.4). Here we may assume that all $\hat{a}_{ij}$ and $\hat{b}_i$ are rational numbers from $[0, 1)$ with common denominator $D = |\det(B)|$. Thus, multiplying by D, we get the constraint $\sum_{j \in N}(D\hat{a}_{ij})x_j \equiv D\hat{b}_i (\mathrm{mod}\ D)$. Set $k = |N|$, $A = (D\hat{a}_{i1}, \ldots, D\hat{a}_{ik}, D) \in \mathbb{Z}^{1 \times (k+1)}$ and $\Lambda = \pi_{\{k+1\}}(\mathcal{L}(A))$. We may assume that $l = c'_{\bar{\tau}} \in \mathbb{Q}_{>0}^k$, where τ is the set of indices of basic variables. Then for any integer solution $r \in \mathbb{Z}^k$ of $r \cdot \pi_{\{k+1\}}(A) \equiv D\hat{b}_i (\mathrm{mod}\ D)$ the group relaxation induced by the row i can be written in the form (1.7). Thus all bounds derived in this paper can be applied to the group relaxation induced by a selected row of (1.4). Note that in this special case the lattice programming gap $\mathrm{gap}(\Lambda, l)$ can be associated with the diameter of a directed circulant graph (see [20] for details). Furthermore, the results of [20] show that the lower bound (1.9) is a good predictor for the value of $\mathrm{gap}(\Lambda, l)$ for a 'typical' Λ.

2. $\mathrm{gap}(\Lambda, l)$ AND DIAMETERS OF QUOTIENT LATTICE GRAPHS

Assume for the rest of the paper $k \geq 2$. Following notation from [20], let $LG_k^+ = (\mathbb{Z}^k, E)$ be the standard directed lattice graph with vertex set $\mathbb{Z}^k$. The edge set E consists of all directed edges $(x, x + e_j)$, where $x \in \mathbb{Z}^k$ and $e_1, \ldots, e_k$ are the standard basis vectors. Let Λ be a k-dimensional sublattice of $\mathbb{Z}^k$. We define the quotient lattice graph LG_k^+/Λ as the digraph with vertex set $\mathbb{Z}^k/\Lambda$ and the edge set $\{(x + \Lambda, x + e_j + \Lambda) : x \in \mathbb{Z}^k, j = 1, \ldots, k\}$. Given cost vector $l \in \mathbb{Q}_{>0}^k$, we define the distance from vertex $x + \Lambda$ to $y + \Lambda$ in LG_k^+/Λ as

$$d_{LG_k^+/\Lambda}(x + \Lambda, y + \Lambda) = \min_{z \in (y-x+\Lambda) \cap \mathbb{Z}_{\geq 0}^k} l \cdot z.$$

The diameter of LG_k^+/Λ is given by $\mathrm{diam}\,(LG_k^+/\Lambda) = \max_{y \in \mathbb{Z}^k/\Lambda} d_{LG_k^+/\Lambda}(0 + \Lambda, y + \Lambda)$. Since for any $y \in \mathbb{Z}^k$

$$d_{LG_k^+/\Lambda}(0 + \Lambda, y + \Lambda) = \min\{l \cdot x : x \equiv y (\mathrm{mod}\ \Lambda), x \geq 0\},$$

we obtain the following expression (cf. [11]).

Lemma 2.1. $\mathrm{gap}(\Lambda, l) = \mathrm{diam}\,(LG_k^+/\Lambda)$.

3. $\mathrm{gap}(\Lambda, l)$ AND THE COVERING RADIUS OF A SIMPLEX

Given cost vector $l \in \mathbb{Q}_{>0}^k$, let $\Delta_l = \left\{x \in \mathbb{R}_{\geq 0}^k : l \cdot x \leq 1\right\}$. Then the following result holds.

Lemma 3.1. $\mathrm{gap}(\Lambda, l) = \rho(\Delta_l, \Lambda) - \sum_{i=1}^k l_i$.

Proof. The result follows from Lemma 2.1 and results of [20]. For completeness we give here a detailed proof. Where possible, we keep the notation from [20] for convenience of the reader.

Let Λ be a k-dimensional sublattice of $\mathbb{Z}^k$. Consider the continuous torus $\mathbb{R}^k/\Lambda$. We can define the distance $d_{\mathbb{R}^k/\Lambda}$ between any two points $x + \Lambda$ and $y + \Lambda$ on $\mathbb{R}^k/\Lambda$ as

$$d_{\mathbb{R}^k/\Lambda}(x + \Lambda, y + \Lambda) = \min_{z \in (y-x+\Lambda) \cap \mathbb{R}^k_{\geq 0}} l \cdot z .$$

By the directed diameter of $\mathbb{R}^k/\Lambda$ we understand $\operatorname{diam}_l^+(\mathbb{R}^k/\Lambda) = \sup_{y \in \mathbb{R}^k/\Lambda} d_{\mathbb{R}^k/\Lambda}(0 + \Lambda, y + \Lambda)$. It follows from the proof of Lemma 3 in [20] that $\operatorname{diam}(LG_k^+/\Lambda) = \operatorname{diam}_l^+(\mathbb{R}^k/\Lambda) - \sum_{i=1}^k l_i$. Then by Lemma 2.1 we can express $\operatorname{gap}(\Lambda, l)$ as

$$(3.1) \qquad \operatorname{gap}(\Lambda, l) = \operatorname{diam}_l^+(\mathbb{R}^k/\Lambda) - \sum_{i=1}^k l_i .$$

Next, define the lattice $\Gamma(\Lambda, l) = \Lambda \operatorname{diag}(\Pi^{-1/k} l_1, \ldots, \Pi^{-1/k} l_k)$, where $\Pi = \det(\Lambda) l_1 \cdots l_k$. Then for $e = (1, \ldots, 1) \in \mathbb{Z}^k$ we have

$$(3.2) \qquad \operatorname{diam}_l^+(\mathbb{R}^k/\Lambda) = \Pi^{1/k} \operatorname{diam}_e^+(\mathbb{R}^k/\Gamma(\Lambda, l)) .$$

By Lemma 4 in [20],

$$(3.3) \qquad \operatorname{diam}_e^+(\mathbb{R}^k/\Gamma(\Lambda, l)) = \rho(\Delta, \Gamma(\Lambda, l)) .$$

Since the linear transform defined by the matrix $\operatorname{diag}(\Pi^{-1/k} l_1, \ldots, \Pi^{-1/k} l_k)$ maps Δ_l to $\Pi^{-1/k} \Delta$, we have

$$(3.4) \qquad \rho(\Delta, \Gamma(\Lambda, l)) = \Pi^{-1/k} \rho(\Delta_l, \Lambda) .$$

Combining (3.1), (3.2), (3.3) and (3.4), we complete the proof of the lemma. $\square$

4. Proof of Theorem 1.1

We are concerned with the following problem:

(4.1) Given a k-dimensional lattice $\Lambda \subset \mathbb{Z}^k$ and $l \in \mathbb{Q}^k$, compute $\operatorname{gap}(\Lambda, l)$.

Here we suppose that the lattice Λ is given by its basis.

Let a be a positive integral n-dimensional primitive vector with $n = k + 1$, i.e., $a = (a_1, \ldots, a_{k+1})^t \in \mathbb{Z}^{k+1}_{>0}$ with $\gcd(a_1, \ldots, a_{k+1}) = 1$. The *Frobenius number* $F(a)$ is the largest number which cannot be represented as a nonnegative integral combination of the a_i's. The problem of computing $F(a)$ has been traditionally referred to as the *Frobenius problem*. This problem is NP-hard when n is a part of input (Ramírez Alfonsín [21]).

Set $l_a = (a_1, \ldots, a_k)^t$ and $\Lambda_a = \{x \in \mathbb{Z}^k : a_1 x_1 + \cdots + a_k x_k \equiv 0 \,(\operatorname{mod} a_{k+1})\}$. By a celebrated result of Kannan [18] the Frobenius number can be expressed as $F(a) = \rho(\Delta_{l_a}, \Lambda_a) - \sum_{i=1}^{k+1} a_i$. Hence, Lemma 3.1 with $l = l_a$ implies

$$(4.2) \qquad F(a) = \operatorname{gap}(\Lambda_a, l_a) - a_{k+1} .$$

By Corollary 5.4.10 in [13], given integer vector a, a basis of Λ_a can be computed in polynomial time. Therefore, the formula (4.2) provides a polynomial time Turing reduction from the Frobenius problem to (4.1).

5. Proof of Theorem 1.2

Part (i). By Lemma 3.1 and (3.4) we can write

$$(5.1) \qquad \mathrm{gap}(\Lambda, l) = \rho(\Delta, \Gamma(\Lambda, l)) \Pi^{1/k} - \sum_{i=1}^{k} l_i \,.$$

Since $\Gamma(\Lambda, l) \in X_k$, the inequality (1.9) now follows from the definition of ρ_k.

Part (ii). There exists $u = (p_1/q, \ldots, p_{k+1}/q) \in \mathbb{Q}_{>0}^{k+1}$ with $p_1, \ldots, p_{k+1}, q \in \mathbb{Z}_{>0}$, such that for any $b \in \mathrm{Sg}(qu^t)$ the linear relaxation $LP_c(qu^t, b)$ has a unique optimal solution with nonbasic variables indexed by $\sigma = \{1, \ldots, k\}$. Let $\mathfrak{F} = \{x \in \mathbb{R}^{k+1} : 0 < x_1 < \ldots < x_{k+1}\}$. Changing the order of coordinates and perturbing u, if needed, we may assume that $u \in \mathfrak{F}$. For $\epsilon > 0$ let $\mathcal{C}_\epsilon = \{x \in \mathbb{R}^{k+1} : |u/|u| - x/|x|| < \epsilon\}$. One can choose sufficiently small $\epsilon_0 > 0$ such that $\mathcal{C}_{\epsilon_0} \subset \mathfrak{F}$ and for any $v \in \mathcal{C}_{\epsilon_0} \cap \mathbb{Z}^{k+1}$ the linear relaxation $LP_c(v^t, b)$ has a unique optimal solution with nonbasic variables indexed by σ for any $b \in \mathrm{Sg}(v^t)$.

Set $\mathcal{D} = \mathcal{C}_{\epsilon_0} \cap [0,1]^{k+1}$, $l = c'_\sigma$ and $\widehat{\mathbb{N}}^{k+1}$ be the set of integral vectors in $\mathbb{R}^{k+1}$ with positive coprime coefficients (i.e., the greatest common divisor of all coefficients is one). We can view $\Gamma(\Lambda(a^t), l)$ as an X_k-valued random variable defined by taking a uniformly at random in $\widehat{\mathbb{N}}^{k+1} \cap T\mathcal{D}$ for some $T > 0$. Let μ_0 be the $SL(k, \mathbb{R})$ invariant probability measure on X_k. It was shown in Section 2.5 of [20] that, as $T \to \infty$, $\Gamma(\Lambda(a^t), l)$ converges in distribution to a random variable $L \in X_k$, taken according to μ_0 (note that in notation of [20], $\Gamma(\Lambda(a^t), l)$ corresponds to $L_{n,\boldsymbol{a},\boldsymbol{l}}$). Furthermore, following Section 2.5 of [20], the function $L \to \rho(\Delta, L)$ is continuous on X_k and hence, by the continuous mapping theorem,

$$(5.2) \qquad \rho(\Delta, \Gamma(\Lambda(a^t), l)) \xrightarrow{d} \rho(\Delta, L) \ \text{ as } \ T \to \infty \,,$$

where $X \xrightarrow{d} Y$ denotes convergence in distribution.

Consider the complementary distribution function $P_k(R) = \mu_0(\{\Lambda \in X_k : \rho(\Delta, \Lambda) > R\})$ of $\rho(\Delta, L)$. Then (5.2) is equivalent with the statement that for any $R \geq 0$ we have

$$(5.3) \qquad \lim_{T \to \infty} \frac{1}{\#(\widehat{\mathbb{N}}^{k+1} \cap T\mathcal{D})} \#\{a \in \widehat{\mathbb{N}}^{k+1} \cap T\mathcal{D} : \rho(\Delta, \Gamma(\Lambda(a^t), l)) < R\}$$
$$= 1 - P_k(R) \,.$$

It was proved in [19] that $P_k(R)$ is continuous for any fixed $k \geq 2$. It was also noticed in [20], Remark 1.2 (see also [22], p. 86) that

$$(5.4) \qquad P_k(R) = 1 \text{ for } 0 \leq R \leq \rho_k, \text{ and } P_k(R) < 1 \text{ for } R > \rho_k.$$

By (5.4) for any $\epsilon > 0$ we have $P_k(\rho_k + \epsilon) < 1$. Hence, by (5.3), for sufficiently large T there exists a vector $a \in \widehat{\mathbb{N}}^{k+1} \cap T\mathcal{D}$ such that $\rho(\Delta, \Gamma(\Lambda(a^t), l)) < \rho_k + \epsilon$. As $T\mathcal{D} \subset \mathcal{C}_{\epsilon_0}$, the linear relaxation $LP_c(a^t, b)$ has a unique optimal solution with nonbasic variables indexed by σ for any $b \in \mathrm{Sg}(a^t)$. By (5.1), the inequality (1.10) holds for $A = a^t$.

Finally, we will show that for some $b' \in \mathrm{Sg}(A)$ the optimal value of $IP_c(A, b')$ is equal to $\mathrm{gap}(\Lambda(A), l) + c_{\bar\sigma} A_{\bar\sigma}^{-1} b'$. Suppose $\mathrm{gap}(\Lambda(A), l) = m(\Lambda(A), l, r_0)$ and the latter minimum is attained at some $x_0 \in \mathbb{Z}_{\geq 0}^k$. Then we can equivalently write $\mathrm{gap}(\Lambda(A), l) = m(\Lambda(A), l, x_0)$. Let us take any vector $u \in \mathbb{Z}_{\geq 0}^{k+1}$ with $u_\sigma = x_0$. By Theorem 3 in [12], $b' = Au$ satisfies the desired property.

6. Proof of Theorem 1.3

Let us find the inradius of the simplex Δ_l. The volume $\mathrm{vol}_k(\Delta_l) = 1/(k! \prod_{i=1}^{k} l_i)$ and the surface area

$$A_{k-1}(\Delta_l) = \sum_{i=1}^{k} \frac{1}{(k-1)! \prod_{j=1, j\neq i}^{k} l_j} + \frac{|l|}{(k-1)! \prod_{i=1}^{k} l_i} = \frac{\sum_{i=1}^{k} l_i + |l|}{(k-1)! \prod_{i=1}^{k} l_i}.$$

All facets of Δ_l are touched by the insphere. Hence, the inradius $r(\Delta_l)$ of the simplex Δ_l is given by

$$(6.1) \qquad r(\Delta_l) = \frac{k \, \mathrm{vol}_k(\Delta_l)}{A_k(\Delta_l)} = \frac{1}{\sum_{i=1}^{k} l_i + |l|}.$$

Let $B^k(r, x)$ denote the ball in $\mathbb{R}^k$ of radius r centered at x. Then, as the covering radius is independent of translation, we have

$$(6.2) \qquad \rho(\Delta_l, \Lambda) \leq \rho(B^k(r(\Delta_l), 0), \Lambda) = (r(\Delta_l))^{-1} \rho(B^k(1, 0), \Lambda).$$

Let $\lambda_1, \ldots, \lambda_k$ be Minkowski's successive minima of $B^k(1, 0)$ with respect to the lattice Λ. Since $\Lambda \subset \mathbb{Z}^k$, we have $\lambda_i \geq 1$ for each i. By Jarnik's inequalities (see e.g. [14])

$$(6.3) \qquad \rho(B^k(1, 0), \Lambda) \leq \frac{k \lambda_k}{2}.$$

In the geometry of numbers it is customary to use the Hermite constant γ_k defined as the lower bound of the constants γ'_k such that every positive definite quadratic form $\sum f_{ij} x_i x_j$ in k variables represents a number $\leq \gamma'_k |\det(f_{ij})|^{1/k}$. It is known (see e.g. Section IX.7. in [6]) that the *critical determinant* of $B^k(1, 0)$ is equal to $\gamma_k^{-k/2}$. Therefore, by Minkowski's second theorem for spheres (cf. [14, §18.4, Theorem 3]), we get

$$(6.4) \qquad \lambda_k \leq \lambda_1 \cdots \lambda_{k-1} \lambda_k \leq \gamma_k^{k/2} \det(\Lambda).$$

By Lemma 3.1, $\mathrm{gap}(\Lambda, l) = \rho(\Delta_l, \Lambda) - \sum_{i=1}^{k} l_i$. Therefore, combining (6.2), (6.1), (6.3) and (6.4) we obtain the upper bound (1.12).

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