

LR-Drawings of Ordered Rooted Binary Trees and Near-Linear Area Drawings of Outerplanar Graphs ^{*}

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Abstract. We study a family of algorithms, introduced by Chan [SODA 1999], for drawing ordered rooted binary trees. Any algorithm in this family (which we name an *LR-algorithm*) takes in input an ordered rooted binary tree T with a root r_T , and recursively constructs drawings Γ_L of the left subtree L of r_T and Γ_R of the right subtree R of r_T ; then either it applies the *left rule*, i.e., it places Γ_L one unit below and to the left of r_T , and Γ_R one unit below Γ_L with the root of R vertically aligned with r_T , or it applies the *right rule*, i.e., it places Γ_R one unit below and to the right of r_T , and Γ_L one unit below Γ_R with the root of L vertically aligned with r_T . In both cases, the edges between r_T and its children are represented by straight-line segments. Different LR-algorithms result from different choices on whether the left or the right rule is applied at any non-leaf node of T . We are interested in constructing *LR-drawings* (that are drawings obtained via LR-algorithms) with small width. Chan showed three different LR-algorithms that achieve, for an ordered rooted binary tree with n nodes, width $O(n^{0.695})$, width $O(n^{0.5})$, and width $O(n^{0.48})$.

We prove that, for every n -node ordered rooted binary tree, an LR-drawing with minimum width can be constructed in $O(n^{1.48})$ time. Further, we show an infinite family of n -node ordered rooted binary trees requiring $\Omega(n^{0.418})$ width in any LR-drawing; no lower bound better than $\Omega(\log n)$ was previously known. Finally, we present the results of an experimental evaluation that allowed us to determine the minimum width of all the ordered rooted binary trees with up to 455 nodes.

Our interest in LR-drawings is mainly motivated by a result of Di Battista and Frati [Algorithmica 2009], who proved that n -vertex outerplanar graphs have outerplanar straight-line drawings in $O(n^{1.48})$ area by means of a drawing algorithm which resembles an LR-algorithm.

We deepen the connection between LR-drawings and outerplanar straight-line drawings by proving that, if n -node ordered rooted binary trees have LR-drawings with $f(n)$ width, for any function $f(n)$, then n -vertex outerplanar graphs have outerplanar straight-line drawings in $O(f(n))$ area.

Finally, we exploit a structural decomposition for ordered rooted binary trees introduced by Chan in order to prove that every n -vertex outerplanar graph has an outerplanar straight-line drawing in $O\left(n \cdot 2^{\sqrt{2 \log_2 n}} \sqrt{\log n}\right)$ area.

1 Introduction

In this paper we study algorithms for constructing geometric representations of ordered rooted binary trees. This research topic has been investigated for a long time, because of the importance and the ubiquitousness of ordered rooted binary trees in computer science. Geometric models for representing ordered rooted binary trees were already discussed almost 50 years ago in Knuth's foundational book "The Art of Computer Programming" [13]. We explicitly mention here the notorious Reingold and Tilford's algorithm [16] (counting more than 570 citations, according to Google Scholar) and invite the reader to consult the survey by Rusu [17] as a reference point for a plethora of other tree drawing algorithms.

We introduce some definitions. A *rooted tree* T is a tree with one distinguished node called *root*, which we denote by r_T . For any node $s \neq r_T$ in T , the *parent* of s is the neighbor of s in the path between s and r_T in T ; also, for any node s in T , the *children* of s are the neighbors of s different from its parent. For any node $s \neq r_T$ in T , the *subtree* of T rooted at s is defined as follows: remove from T the edge between s and its parent, thus separating T in two trees; the one containing s is the subtree of T rooted at s . A *rooted binary tree* is a rooted tree such that every node has at most two children. An *ordered rooted binary tree* T is a rooted binary tree in which any node $s \neq r_T$ is either designated as the *left child* or as the *right child* of its parent, so that a node with two children has a left and a right child. The subtree of

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T rooted at the left (right) child of a node s is the *left (right) subtree* of s ; we also call *left (right) subtree* of a path P in T any left (right) subtree of a node in P whose root is not in P .

At the Tenth Symposium on Discrete Algorithms held in 1999, Chan [2, 3] introduced a simple family of algorithms to draw ordered rooted binary trees; we name the algorithms in this family *LR-algorithms*. An LR-algorithm is defined as follows. Consider an ordered rooted binary tree T . If T has one node, then represent it as a point in the plane. Otherwise, recursively construct drawings Γ_L of the left subtree L of r_T and Γ_R of the right subtree R of r_T . Denote by $B(\Gamma)$ the *bounding box* of a drawing Γ , i.e., the smallest axis-parallel rectangle containing Γ in the closure of its interior. Then apply either:



Fig. 1: (a) Illustration for the left rule. (b) Illustration for the right rule.

- the *left rule* (see Fig. 1(a)), i.e., place Γ_L so that the top side of $B(\Gamma_L)$ is one unit below r_T and so that the right side of $B(\Gamma_L)$ is one unit to the left of r_T , and place Γ_R so that the top side of $B(\Gamma_R)$ is one unit below the bottom side of $B(\Gamma_L)$ and so that r_R is vertically aligned with r_T ; or
- the *right rule* (see Fig. 1(b)), i.e., place Γ_R so that the top side of $B(\Gamma_R)$ is one unit below r_T and so that the left side of $B(\Gamma_R)$ is one unit to the right of r_T , and place Γ_L so that the top side of $B(\Gamma_L)$ is one unit below the bottom side of $B(\Gamma_R)$ and so that r_L is vertically aligned with r_T .

By fixing different criteria for choosing whether to apply the left or the right rule at each internal node of T , one obtains different LR-algorithms. We call *LR-drawing* the output of an LR-algorithm.

LR-drawings are a special class of *ideal drawings*, which constitute the main topic of investigation in Chan’s paper [2, 3] and are a very natural drawing standard for ordered rooted binary trees. They require the drawing to be: (i) *planar*, i.e., no two curves representing edges should cross – this property helps to distinguish distinct edges; (ii) *straight-line*, i.e., each curve representing an edge is a straight-line segment – this property helps to track an edge in the drawing; (iii) *strictly upward*, i.e., each node is below its parent – this property helps to visualize the parent-child relationship between nodes; and (iv) *strongly order-preserving*, i.e., the left (right) child of a node is to the left (resp. right) or on the same vertical line of its parent – this property allows to easily distinguish the left and right child of a node.

As well-established in the graph drawing literature (see, e.g., [6, 12, 15]), an optimization objective of primary importance for a drawing algorithm is to construct drawings with a *small area*. This is usually formalized by requiring the vertices to lie *in a grid*, that is, at points with integer coordinates, by defining the *width* and *height* of Γ as the number of grid columns and rows intersecting Γ , respectively¹, and by then defining the *area* of Γ as its width times its height.

Ideal drawings of n -node ordered rooted binary trees can be easily constructed in $O(n^2)$ area. For example, the width and the height of *any* LR-drawing are at most n and exactly n , respectively. Because of the strictly-upward property, any ideal drawing of an n -node ordered rooted binary tree requires $\Omega(n)$ height if the tree contains a path with $\Omega(n)$ nodes from the root to a leaf. Thus, in order to construct ideal drawings with small area, the main goal is to minimize the width of the drawing. Chan exhibited several algorithms to construct ideal drawings. Three of them are in fact LR-algorithms that construct LR-drawings with $O(n^{0.695})$, $O(n^{0.5})$, and $O(n^{0.48})$ width, respectively. Better bounds than those resulting from LR-algorithms are however known for the width of ideal drawings. Namely, Garg and Rusu proved that every n -node ordered rooted binary tree has an ideal drawing with $O(\log n)$ width

¹ According to this definition, the width of Γ is the geometric width of $B(\Gamma)$ plus one, and similar for the height.

and $O(n \log n)$ area [10], which are the best possible bounds [5]. Nevertheless, there are several reasons to study LR-drawings with small width and area.

First, while one might design complicated schema to decide whether to apply the left or the right rule at any internal node of an ordered rooted binary tree, the geometric construction underlying an LR-algorithm is very easy to understand and implement. Second, as noted by Chan [2,3] an LR-drawing satisfies a number of additional geometric properties with respect to a general ideal drawing. For example, in an LR-drawing any two disjoint subtrees are separable by a horizontal line and any angle formed by the two edges between a node and its children is at least $\pi/4$. Third, let w_T^* denote the minimum width of any LR-drawing of an ordered rooted binary tree T ; also, let w_n^* be the maximum value of w_T^* among all the ordered rooted binary trees T with n nodes. In this paper we are interested in computing w_T^* efficiently and in determining the asymptotic behavior of w_n^* . The value of w_T^* obeys a natural recursive formula; namely $w_T^* = \min_P \{1 + \max_L \{w_L^*\} + \max_R \{w_R^*\}\}$, where the minimum is among all the paths P starting at r_T , and the first and second maxima are among all the left and right subtrees of P , respectively². Our study of LR-drawings with small width might hence find application in problems (not necessarily related to graph drawing) in which a similar recurrence appears. Fourth and most importantly for this paper, LR-drawings with small width have a strong connection with outerplanar straight-line drawings of outerplanar graphs with small area, as will be described later.

In Section 2 we prove that, for every n -node ordered rooted binary tree T , an LR-drawing of T with minimum width w_T^* (and with minimum area) can be constructed in $O(n \cdot w_T^*) \in O(n^{1.48})$ time. Chan [2,3] noted that “By dynamic programming, one can compute in polynomial time the exact minimum area of” any LR-drawing of T . Our sub-quadratic time bound is obtained by investigating the *representation sequence* of T , which is a sequence of $O(w_T^*)$ integers that conveys all the relevant information about the width of the LR-drawings of T . Further, we show that, for infinitely many values of n , there exists an n -node ordered rooted binary tree T_h requiring $\Omega\left(n^{\frac{1}{\log_2(3+\sqrt{5})}}\right) \in \Omega(n^{0.418})$ width in any LR-drawing; no lower bound better than $\Omega(\log n)$ was previously known [5]. Since the height of any LR-drawing of an n -node tree is n , T_h requires $\Omega(n^{1.418})$ area in any LR-drawing; hence near-linear area bounds cannot be achieved for LR-drawings, differently from general ideal drawings. Note that the exponents in these lower bounds are only 0.062 apart from the corresponding upper bounds. Finally, we exploited again the concept of representation sequence in order to devise an experimental evaluation that determined the minimum width of all the ordered rooted binary trees with up to 455 nodes. The most interesting outcome of this part of our research is perhaps the similarity of the trees that we have experimentally observed to require the largest width with the trees T_h we defined for the lower bound. Fig. 2 shows a minimum-width LR-drawing of a smallest tree requiring width 8 in any LR-drawing; this tree is also shown in Fig. 7(a).

Section 3 deals with small-area drawings of outerplanar graphs. An *outerplanar graph* is a graph that excludes K_4 and $K_{2,3}$ as minors or, equivalently, a graph that admits an *outerplanar drawing*, that is a planar drawing in which all the vertices are incident to the outer face. Small-area outerplanar drawings have long been investigated. Biedl proved that every n -vertex outerplanar graph admits an outerplanar polyline drawing in $O(n \log n)$ area [1], where a *polyline* drawing represents each edge as a piece-wise linear curve. Garg and Rusu proved that every n -vertex outerplanar graph with maximum degree d admits an outerplanar straight-line drawing in $O(d \cdot n^{1.48})$ area [11]. The first sub-quadratic area upper bound for outerplanar straight-line drawings of n -vertex outerplanar graphs was established by Di Battista and Frati [7]; the bound is $O(n^{1.48})$. Frati also proved an $O(d \cdot n \log n)$ area upper bound for outerplanar straight-line drawings of n -vertex outerplanar graphs with maximum degree d [9].

By looking at the $O(d \cdot n^{1.48})$ and $O(n^{1.48})$ area bounds above, it should come with no surprise that outerplanar straight-line drawings are related to LR-drawings of ordered rooted binary trees, for which the best known area upper bound is $O(n^{1.48})$ [2,3]. We briefly describe the way this relationship was established in [7]. Let G be a maximal outerplanar graph with n vertices and let T be its *dual tree* (T has

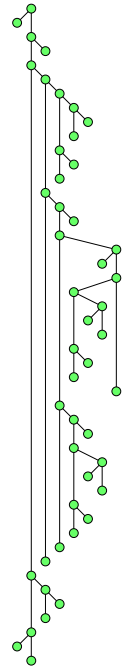


Fig. 2

² The intuition for this formula is that in any LR-drawing Γ of T a path P starting at r_T lies on a grid column ℓ ; thus the width of Γ is the number of grid columns that intersect Γ to the left of ℓ – which is the maximum, among all the left subtrees L of P , of the minimum width of an LR-drawing of L – plus the number of grid columns that intersect Γ to the right of ℓ – which is the maximum, among all the right subtrees R of P , of the minimum width of an LR-drawing of R – plus one – which corresponds to ℓ .

a node for each internal face of G and has an edge between two nodes if the corresponding faces of G are adjacent). Di Battista and Frati [7] proved that, if T has a *star-shaped* drawing (which will be defined later) in a certain area, then G has an outerplanar straight-line drawing in roughly the same area; they also showed how to construct a star-shaped drawing of T in $O(n^{1.48})$ area; this algorithm is similar to an LR-algorithm, which is the reason why the $O(n^{1.48})$ bound arises.

We prove that if an n -node ordered rooted binary tree T has an LR-drawing with width ω , then T has a star-shaped drawing with width $O(\omega)$ (and area $O(n \cdot \omega)$). Our geometric construction is very similar to the one presented in [7], however it is enhanced so that no property other than the width bound³ is required to be satisfied by the LR-drawing of T in order to ensure the existence of a star-shaped drawing of T with area $O(n \cdot \omega)$. Due to this result and to the relationship between the area requirements of star-shaped drawings and outerplanar straight-line drawings established in [7], any improvement on the $O(n^{0.48})$ width bound for LR-drawings of ordered rooted binary trees would imply an improvement on the $O(n^{1.48})$ area bound for outerplanar straight-line drawings of n -vertex outerplanar graphs. However, because of the lower bound for the width of LR-drawings proved in the first part of the paper, this approach cannot lead to the construction of outerplanar straight-line drawings of n -vertex outerplanar graphs in $o(n^{1.418})$ area.

We prove that, for any constant $\varepsilon > 0$, the n -vertex outerplanar graphs admit outerplanar straight-line drawings in $O(n^{1+\varepsilon})$ area. More precisely, our drawings have $O(n)$ height and $O(2^{\sqrt{2} \log n} \sqrt{\log n})$ width; the latter bound is smaller than any polynomial function of n . Hence, this establishes a near-linear area bound for outerplanar straight-line drawings of outerplanar graphs, improving upon the previously best known $O(n^{1.48})$ area bound [7]. In order to achieve our result we exploit a structural decomposition for ordered rooted binary trees introduced by Chan [3], together with a quite complex geometric construction for star-shaped drawings of ordered rooted binary trees.

2 LR-Drawings of Ordered Rooted Binary Trees

In this section we study LR-drawings of ordered rooted binary trees.

2.1 Representation sequences

Our investigation starts by defining a combinatorial structure, called *representation sequence*, which can be associated to any ordered rooted binary tree T and which conveys all the relevant information about the width of the LR-drawings of T . We first establish some preliminary properties and lemmata.

Consider an LR-drawing Γ of an ordered rooted binary tree T . The *left width* of Γ is the number of grid columns intersecting Γ to the left of the grid column on which r_T lies. The *right width* of Γ is defined analogously. By definition of width, we have the following.

Property 1. The width of an LR-drawing Γ is equal to its left width, plus its right width, plus one.

For any $\alpha, \beta \in \mathbb{N}_0$, we say that a pair (α, β) is *feasible* for T if T admits an LR-drawing whose left width is at most α and whose right width is at most β . This definition implies the following.

Property 2. Consider an ordered rooted binary tree T . If a pair (α, β) is feasible for T , then every pair (α', β') with $\alpha', \beta' \in \mathbb{N}_0$, $\alpha' \geq \alpha$, and $\beta' \geq \beta$ is also feasible for T .

The next lemma will be used several times in the following.

Lemma 1. *The pairs $(0, w_T^*)$ and $(w_T^*, 0)$ are feasible for an ordered rooted binary tree T .*

Proof. We prove that the pair $(0, w_T^*)$ is feasible for T ; the proof for the pair $(w_T^*, 0)$ is symmetric.

The proof is by induction on the number n of nodes of T . If $n = 1$, then in any LR-drawing Γ of T both the left and the right width of Γ are 0, hence the pair $(0, 0)$ is feasible for T . By Property 2, the pair $(0, 1)$ is also feasible for T . This, together with $w_T^* = 1$, implies the statement for $n = 1$.

³ On the contrary, in order to prove the area bound for star-shaped drawings, [7] exploits a lemma from [2, 3], stating that, given any ordered rooted binary tree T , there exists a root-to-leaf path P in T such that, for any left subtree α and right subtree β of P , $|\alpha|^{0.48} + |\beta|^{0.48} \leq (1 - \delta)|T|^{0.48}$, for some constant $\delta > 0$.

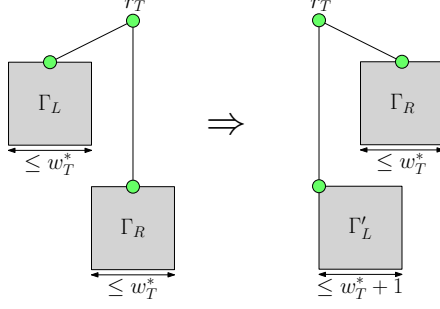


Fig. 3: Illustration for the proof of Lemma. 1.

If $n > 1$, then assume that neither the left subtree L nor the right subtree R of r_T is empty. The case in which L or R is empty is easier to handle. Refer to Fig. 3. Consider any LR-drawing Γ_T of T with width w_T^* . Denote by Γ_L and Γ_R the LR-drawings of L and R in Γ_T , respectively. The width of each of Γ_L and Γ_R is at most w_T^* , given that the width of Γ_T is w_T^* . Apply induction on L to construct an LR-drawing Γ'_L of L with left width 0 and right width at most w_T^* . Construct an LR-drawing Γ'_T of T by applying the right rule at r_T , while using Γ_R as the LR-drawing of R and Γ'_L as the LR-drawing of L . Then the left width of Γ'_T is equal to the left width of Γ'_L , hence it is 0. Further, the right width of Γ'_T is equal to the maximum between the width of Γ_R and the right width of Γ'_L , which are both at most w_T^* ; hence the pair $(0, w_T^*)$ is feasible for T . \square

Property 2 implies that there exists an infinite number of feasible pairs for T . Despite that, the set of feasible pairs for T can be succinctly described by its *Pareto frontier*, which is the set of the feasible pairs (α, β) for T such that no feasible pair (α', β') for T exists with (i) $\alpha' < \alpha$ and $\beta' \leq \beta$ or (ii) $\alpha' \leq \alpha$ and $\beta' < \beta$.

More formally, the *representation sequence* of an ordered rooted binary tree T , which we denote by \mathcal{S}_T , is an ordered list of integers (indexed by the numbers $0, 1, 2, \dots$) satisfying the following properties:

- (a) the value $\mathcal{S}_T(i)$ of the element of \mathcal{S}_T with index i is the smallest integer j such that T admits an LR-drawing with left width at most i and right width j ; and
- (b) the value of the second to last element of \mathcal{S}_T is greater than 0 and the value of the last element of \mathcal{S}_T is equal to 0.

We let k_T denote the number of elements in \mathcal{S}_T . Note that the values $\mathcal{S}_T(0), \dots, \mathcal{S}_T(k_T - 1)$ in a representation sequence \mathcal{S}_T are non-increasing, given that if a pair $(i, \mathcal{S}_T(i))$ is feasible for T , then the pair $(i + 1, \mathcal{S}_T(i))$ is also feasible for T , by Property 2. For example, the tree T_3 shown in Fig. 4(b) (which we use for the lower bound on the width of LR-drawings) has $\mathcal{S}_{T_3} = [6, 5, 5, 3, 3, 1, 0]$.

Note that, if T is a root-to-leaf path, then $\mathcal{S}_T = [0]$, since T has an LR-drawing in which all the nodes are on the same vertical line. Also, any complete binary tree T with height $h + 1$ (i.e., with $h + 1$ nodes on any root-to-leaf path) has $\mathcal{S}_T = [h, \dots, h, 0]$, where h elements are equal to h . This can be proved by induction and by the following lemma.

Lemma 2. Consider any ordered rooted binary tree T . Let T' be the tree such that the left subtree L and the right subtree R of $r_{T'}$ are two copies of T . Then $\mathcal{S}_{T'} = [\underbrace{w_T^*}_{\text{index } 0}, \dots, \underbrace{w_T^*}_{\text{index } w_T^* - 1}, \underbrace{0}_{\text{index } w_T^*}]$.

Proof. First, we prove that $\mathcal{S}_{T'}(i) = w_T^*$, for $i = 0, \dots, w_T^* - 1$.

We prove that $\mathcal{S}_{T'}(i) \geq w_T^*$. Consider any LR-drawing $\Gamma_{T'}$ of T' with left width $i \leq w_T^* - 1$. If $\Gamma_{T'}$ used the left rule at $r_{T'}$, then the LR-drawing of L in $\Gamma_{T'}$ would be entirely to the left of $r_{T'}$; hence, the left width of $\Gamma_{T'}$ would be at least w_T^* , while it is at most i , by assumption. It follows that $\Gamma_{T'}$ uses the right rule at $r_{T'}$ and the LR-drawing of R in $\Gamma_{T'}$ is entirely to the right of $r_{T'}$; hence, $\mathcal{S}_{T'}(i) \geq w_T^*$.

We prove that $\mathcal{S}_{T'}(i) \leq w_T^*$. Consider an LR-drawing Γ_R of R with width w_T^* , and an LR-drawing Γ_L of L with left width at most i and right width w_T^* ; Γ_L exists since pair $(0, w_T^*)$ is feasible for L , by Lemma 1. Construct an LR-drawing $\Gamma_{T'}$ of T' by applying the right rule at $r_{T'}$, while using Γ_L and Γ_R as LR-drawings for L and R , respectively. Since $r_{T'}$ and r_L are on the same vertical line, the left width

of $\Gamma_{T'}$ is equal to the left width of Γ_L , which is at most i , and the right width of $\Gamma_{T'}$ is the maximum between the right width of Γ_L and the width of Γ_R , which are both equal to w_T^* . Hence, $\mathcal{S}_{T'}(i) \leq w_T^*$.

Finally, we prove that $\mathcal{S}_{T'}(w_T^*) = 0$. Consider an LR-drawing Γ_L of L with width at most w_T^* , and an LR-drawing Γ_R of R with left width at most w_T^* and right width 0; the latter drawing exists by Lemma 1. Construct an LR-drawing $\Gamma_{T'}$ of T' by applying the left rule at $r_{T'}$, while using Γ_L and Γ_R as LR-drawings for L and R , respectively. Since $r_{T'}$ and r_R are on the same vertical line, the right width of $\Gamma_{T'}$ is equal to the right width of Γ_R , which is 0, and the left width of $\Gamma_{T'}$ is the maximum between the left width of Γ_R and the width of Γ_L , which are both at most w_T^* . Hence, $\mathcal{S}_{T'}(w_T^*) = 0$. \square

As a final lemma of this section we bound the number of elements in a representation sequence.

Lemma 3. *Consider any ordered rooted binary tree T . Then the length k_T of \mathcal{S}_T is either w_T^* or $w_T^* + 1$.*

Proof. First, $k_T \leq w_T^* - 1$ would imply that the last element of \mathcal{S}_T has index less than or equal to $w_T^* - 2$ and value 0. By Property 1, there would exist an LR-drawing of T with width at most $w_T^* - 2 + 0 + 1 < w_T^*$, which is not possible by definition of w_T^* . It follows that $k_T \geq w_T^*$.

Second, Lemma 1 implies that the pair $(w_T^*, 0)$ is feasible for T , hence $k_T = w_T^*$ or $k_T = w_T^* + 1$, depending on whether the pair $(w_T^* - 1, 0)$ is feasible for T or not. \square

2.2 Algorithms for Optimal LR-drawings

There are two main reasons to study the representation sequence \mathcal{S}_T of an ordered rooted binary tree T . The first one is that the minimum width among all the LR-drawings of T can be easily retrieved from \mathcal{S}_T ; the second one is that \mathcal{S}_T can be easily constructed starting from the representation sequences of the subtrees of r_T . The next lemmata formalize these claims.

Lemma 4. *For any ordered rooted binary tree T , the minimum width among all the LR-drawings of T is equal to $\min_{i=0}^{k_T-1} \{i + \mathcal{S}_T(i) + 1\}$.*

Proof. Consider any LR-drawing Γ of T with minimum width w_T^* , and let α and β be the left and right width of Γ , respectively. By Property 1, we have that $w_T^* = \alpha + \beta + 1$. By definition of \mathcal{S}_T , we have that $\mathcal{S}_T(\alpha) \leq \beta$. Finally, by the minimality of w_T^* we have $\mathcal{S}_T(\alpha) = \beta$, which proves the statement. \square

Lemma 5. *Let T be an ordered rooted binary tree. Let L and R be the (possibly empty) left and right subtrees of r_T , respectively. The following statements hold true.*

- If L and R are both empty, then $\mathcal{S}_T = [0]$.
- If L is empty and R is not, then $\mathcal{S}_T = \mathcal{S}_R$.
- If R is empty and L is not, then $\mathcal{S}_T = \mathcal{S}_L$.
- Finally, if neither L nor R is empty, then

$$\mathcal{S}_T = [\underbrace{\max\{\mathcal{S}_L(0), w_R^*\}}_{\text{index } 0}, \dots, \underbrace{\max\{\mathcal{S}_L(w_L^* - 1), w_R^*\}}_{\text{index } w_L^* - 1}, \underbrace{\mathcal{S}_R(w_L^*)}_{\text{index } w_L^*}, \dots, \underbrace{\mathcal{S}_R(k_R - 1)}_{\text{index } k_R - 1}].$$

Proof. We distinguish four cases, based on whether L and R are empty or not.

- If both L and R are empty, then T consists of a single node, hence there is only one LR-drawing Γ of T ; both the left and the right width of Γ are 0, hence $\mathcal{S}_T = [0]$.
- If L is empty and R is not, we prove that $\mathcal{S}_T(i) = \mathcal{S}_R(i)$, for any $i = 0, \dots, k_R - 1$.

First, we prove that $\mathcal{S}_T(i) \leq \mathcal{S}_R(i)$. Consider an LR-drawing Γ_R of R with left width at most i and right width $\mathcal{S}_R(i)$. Construct an LR-drawing Γ_T of T by applying the left rule at r_T , while using Γ_R as the LR-drawing of R . Since r_T and r_R are on the same vertical line, the left (right) width of Γ_T is equal to the left (resp. right) width of Γ_R , which is at most i (resp. which is $\mathcal{S}_R(i)$). Hence, $\mathcal{S}_T(i) \leq \mathcal{S}_R(i)$.

Second, we prove that $\mathcal{S}_R(i) \leq \mathcal{S}_T(i)$. Consider an LR-drawing Γ_T of T with left width at most i and right width $\mathcal{S}_T(i)$; denote by Γ_R the LR-drawing of R in Γ_T . If Γ_T uses the left rule at r_T , then r_T and r_R are on the same vertical line; then the left (right) width of Γ_R is equal to the left (resp. right) width of Γ_T , which is at most i (resp. which is $\mathcal{S}_T(i)$). Hence, $\mathcal{S}_R(i) \leq \mathcal{S}_T(i)$. If Γ_T uses the right rule at r_T , then Γ_R is entirely to the right of r_T , hence $\mathcal{S}_T(i) = w_R^*$. By Lemma 1, the pair $(0, w_R^*)$ is feasible for R , hence $\mathcal{S}_R(i) \leq w_R^*$. Hence, $\mathcal{S}_R(i) \leq \mathcal{S}_T(i)$.

- If R is empty and L is not, the discussion is symmetric to the one for the previous case.
- Finally, assume that neither L nor R is empty. In order to compute the value of $\mathcal{S}_T(i)$, we distinguish the case in which $i \leq w_L^* - 1$ from the one in which $i \geq w_L^*$.
 - Suppose first that $i \leq w_L^* - 1$; we prove that $\mathcal{S}_T(i) = \max\{\mathcal{S}_L(i), w_R^*\}$.
First, we prove that $\mathcal{S}_T(i) \leq \max\{\mathcal{S}_L(i), w_R^*\}$. Consider an LR-drawing Γ_L of L with left width at most i and right width $\mathcal{S}_L(i)$. Also, consider an LR-drawing Γ_R of R with width w_R^* . Construct an LR-drawing Γ_T of T by applying the right rule at r_T , while using Γ_L and Γ_R as LR-drawings for L and R , respectively. Since r_T and r_L are on the same vertical line, the left width of Γ_T is equal to the left width of Γ_L , which is at most i , and the right width of Γ_T is equal to the maximum between the right width of Γ_L and w_R^* . Hence, $\mathcal{S}_T(i) \leq \max\{\mathcal{S}_L(i), w_R^*\}$.
Second, we prove that $\mathcal{S}_T(i) \geq \max\{\mathcal{S}_L(i), w_R^*\}$. Consider any LR-drawing Γ_T of T with left width at most i and right width $\mathcal{S}_T(i)$. We have that Γ_T uses the right rule at r_T . Indeed, if Γ_T used the left rule at r_T , then the LR-drawing of L in Γ_T would be entirely to the left of r_T ; hence, the left width of Γ_T would be at least w_L^* , while it is at most i , by assumption. Since Γ_T uses the right rule at r_T , the LR-drawing of R in Γ_T is entirely to the right of r_T , hence $\mathcal{S}_T(i) \geq w_R^*$. Further, r_T and r_L are on the same vertical line, thus the LR-drawing of L in Γ_T has left width at most i , and hence right width at least $\mathcal{S}_L(i)$; this implies that $\mathcal{S}_T(i) \geq \mathcal{S}_L(i)$.
 - Suppose next that $i \geq w_L^*$; we prove that $\mathcal{S}_T(i) = \mathcal{S}_R(i)$.
First, we prove that $\mathcal{S}_T(i) \leq \mathcal{S}_R(i)$. Consider an LR-drawing Γ_L of L with width w_L^* . Also, consider an LR-drawing Γ_R of R with left width at most i and right width $\mathcal{S}_R(i)$. Construct an LR-drawing Γ_T of T by applying the left rule at r_T , while using Γ_L and Γ_R as LR-drawings for L and R , respectively. Since r_T and r_R are on the same vertical line, the right width of Γ_T is equal to the right width of Γ_R , which is $\mathcal{S}_R(i)$, and the left width of Γ_T is equal to the maximum between w_L^* and the left width of Γ_R ; since w_L^* and the left width of Γ_R are both at most i , we have $\mathcal{S}_T(i) \leq \mathcal{S}_R(i)$.
Second, we prove that $\mathcal{S}_R(i) \leq \mathcal{S}_T(i)$. Consider any LR-drawing Γ_T of T with left width at most i . If Γ_T uses the left rule at r_T , then r_T and r_R are on the same vertical line, thus the LR-drawing of R in Γ_T has left width at most i and right width at most $\mathcal{S}_T(i)$. It follows that $\mathcal{S}_R(i) \leq \mathcal{S}_T(i)$. If Γ_T uses the right rule at r_T , then the LR-drawing of R in Γ_T is entirely to the right of r_T , hence $\mathcal{S}_T(i) \geq w_R^*$. By Lemma 1, the pair $(0, w_R^*)$ is feasible for R , hence, $\mathcal{S}_R(i) \leq w_R^*$. It follows that $\mathcal{S}_R(i) \leq \mathcal{S}_T(i)$.

This concludes the proof. □

We are now ready to show that the representation sequence of an ordered rooted binary tree T , and consequently the minimum width and area of any LR-drawing of T , can be computed efficiently.

Theorem 1. *The representation sequence of an n -node ordered rooted binary tree T can be computed in $O(n \cdot w_T^*) \in O(n \cdot w_n^*) \in O(n^{1.48})$ time. Further, an LR-drawing with minimum width can be constructed in the same time.*

Proof. We compute the representation sequence associated to each subtree T' of T (and the value $w_{T'}^*$) by means of a bottom-up traversal of T . If T' is a single node, then $\mathcal{S}_{T'} = [0]$ and $w_{T'}^* = 1$. If T' is not a single node, then assume that the representation sequences associated to the subtrees of $r_{T'}$ have already been computed. By Lemma 5, the value $\mathcal{S}_{T'}(i)$ can be computed in $O(1)$ time by the formula $\max\{\mathcal{S}_L(i), w_R^*\}$ if $0 \leq i \leq w_L^* - 1$, or by the formula $\mathcal{S}_R(i)$ if $w_L^* \leq i \leq k_R - 1$. Further, by Lemma 3 the representation sequence $\mathcal{S}_{T'}$ has $O(w_{T'}^*) \in O(w_T^*)$ entries, hence it can be computed in $O(w_{T'}^*) \in O(w_T^*)$ time; the value $w_{T'}^*$ can also be computed in $O(w_{T'}^*)$ time from $\mathcal{S}_{T'}$ as in Lemma 4. Summing the $O(w_{T'}^*)$ bound up over the n nodes of T gives the $O(n \cdot w_T^*)$ bound. The bounds $O(n \cdot w_n^*)$ and $O(n^{1.48})$ respectively follow from the fact that $w_T^* \leq w_n^*$, by definition, and $w_n^* \in O(n^{0.48})$, by the results of Chan [3].

Once the representation sequence for each subtree of T has been computed, an LR-drawing Γ_T of T with width w_T^* can be constructed in $O(n \cdot w_T^*)$ time by means of a top-down traversal of T . First, find a pair (α_T, β_T) such that $\alpha_T + \beta_T + 1 = w_T^*$ and such that $\mathcal{S}_T(\alpha_T) = \beta_T$. This pair exists and can be found in $O(w_T^*)$ time by Lemma 4. Further, let $x(r_T) = 0$ and $y(r_T) = 0$.

Now assume that, for some subtree T' of T (initially $T' = T$), a quadruple $(\alpha_{T'}, \beta_{T'}, x(r_{T'}), y(r_{T'}))$ has been associated to T' , where $\alpha_{T'}$ and $\beta_{T'}$ represent the left and right width of an LR-drawing $\Gamma_{T'}$

of T' we aim to construct, respectively, and $x(r_{T'})$ and $y(r_{T'})$ are the coordinates of $r_{T'}$ in $\Gamma_{T'}$. Let L and R be the left and right subtrees of $r_{T'}$, respectively.

- If $w_L^* \leq \alpha_{T'}$, then the left rule is used at $r_{T'}$ to construct $\Gamma_{T'}$. Find a pair (α_L, β_L) satisfying $\alpha_L + \beta_L + 1 = w_L^*$ and $\mathcal{S}_L(\alpha_L) = \beta_L$. This pair exists and can be found in $O(w_L^*) \in O(w_T^*)$ time by Lemma 4. Let $x(r_L) = x(r_{T'}) - \beta_L - 1$ and $y(r_L) = y(r_{T'}) - 1$. Visit L with quadruple $(\alpha_L, \beta_L, x(r_L), y(r_L))$ associated to it; also, let $\alpha_R = \alpha_{T'}$, $\beta_R = \beta_{T'}$, $x(r_R) = x(r_{T'})$, and $y(r_R) = y(r_{T'}) - |L| - 1$. Visit R with quadruple $(\alpha_R, \beta_R, x(r_R), y(r_R))$ associated to it.
- If $w_L^* > \alpha_{T'}$, then the right rule is used at $r_{T'}$ to construct $\Gamma_{T'}$. Find a pair (α_R, β_R) satisfying $\alpha_R + \beta_R + 1 = w_R^*$ and $\mathcal{S}_R(\alpha_R) = \beta_R$. This pair exists and can be found in $O(w_R^*) \in O(w_T^*)$ time by Lemma 4. Let $x(r_R) = x(r_{T'}) + \alpha_R + 1$ and $y(r_R) = y(r_{T'}) - 1$. Visit R with quadruple $(\alpha_R, \beta_R, x(r_R), y(r_R))$ associated to it; also, let $\alpha_L = \alpha_{T'}$, $\beta_L = \beta_{T'}$, $x(r_L) = x(r_{T'})$, and $y(r_L) = y(r_{T'}) - |R| - 1$. Visit L with quadruple $(\alpha_L, \beta_L, x(r_L), y(r_L))$ associated to it.

The correctness of the algorithm comes from Lemma 5 (and its proof). The $O(n \cdot w_T^*)$ running time comes from the fact that the algorithm uses $O(w_T^*)$ time at each node of T . \square

Corollary 1. *A minimum-area LR-drawing of an n -node ordered rooted binary tree T can be constructed in $O(n \cdot w_T^*) \in O(n \cdot w_n^*) \in O(n^{1.48})$ time.*

Proof. Since any LR-drawing has height exactly n , the statement follows from Theorem 1. \square

2.3 A Polynomial Lower Bound for the Width of LR-drawings

We describe an infinite family of ordered rooted binary trees T_h that require large width in any LR-drawing. In order to do that, we first define an infinite family of sequences of integers. Sequence σ_1 consists of the integer 1 only; for any $\ell > 1$, sequence σ_ℓ is composed of two copies of $\sigma_{\ell-1}$ separated by the integer ℓ , that is, $\sigma_\ell = \sigma_{\ell-1}, \ell, \sigma_{\ell-1}$. Thus, for example, $\sigma_4 = 1, 2, 1, 3, 1, 2, 1, 4, 1, 2, 1, 3, 1, 2, 1$. For $i = 1, \dots, 2^\ell - 1$, we denote by $\sigma_\ell(i)$ the i -th term of σ_ℓ . While here we defined σ_ℓ as a finite sequence with length $2^\ell - 1$, the infinite sequence σ_ℓ with $\ell \rightarrow \infty$ is well-known and called *ruler function*: The i -th term of the sequence is the exponent of the largest power of 2 which divides $2i$. See entry A001511 in the Encyclopedia of Integer Sequences [18].

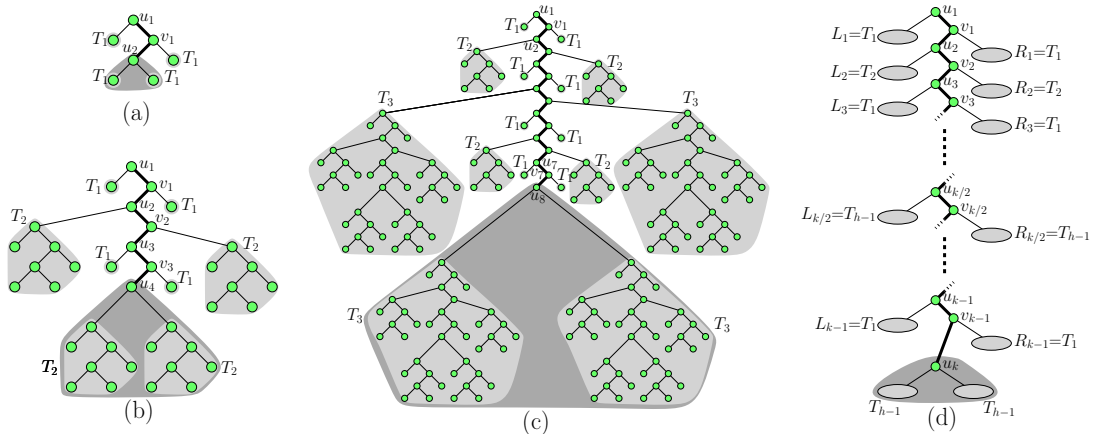


Fig. 4: Illustration for Theorem 2. (a) T_2 . (b) T_3 . (c) T_4 . (d) T_h .

We now describe the recursive construction of T_h . Tree T_1 consists of a single node. If $h > 1$, tree T_h is defined as follows (refer to Fig. 4). First, T_h contains a path $(u_1, v_1, u_2, v_2, \dots, u_{k-1}, v_{k-1}, u_k)$ with

$2^h - 1$ nodes (note that $k = 2^{h-1}$), where u_1 is the root of T_h ; for $i = 1, \dots, k - 1$, node v_i is the right child of u_i and node u_{i+1} is the left child of v_i . Further, take two copies of T_{h-1} and let them be the left and right subtrees of u_k , respectively. Finally, for $i = 1, \dots, k - 1$, take two copies of $T_{\sigma_{h-1}(i)}$ and let them be the left subtree L_i of u_i and the right subtree R_i of v_i , respectively. In the next two lemmata, we prove that tree T_h requires a “large width” in any LR-drawing and that it has “few” nodes.

Lemma 6. *The width of any LR-drawing of T_h is at least $2^h - 1$.*

Proof. The proof is by induction on h . The base case $h = 1$ is trivial.

In order to discuss the inductive case, we define another infinite family of sequences of integers, which we denote by π_ℓ . Sequence π_1 consists of the integer 1 only; for any $\ell > 1$, we have $\pi_\ell = \pi_{\ell-1}, 2^\ell - 1, \pi_{\ell-1}$. Thus, for example, $\pi_4 = 1, 3, 1, 7, 1, 3, 1, 15, 1, 3, 1, 7, 1, 3, 1$. For $i = 1, \dots, 2^\ell - 1$, we denote by $\pi_\ell(i)$ the i -th element of π_ℓ . The infinite sequence π_ℓ with $\ell \rightarrow \infty$ is well-known: The i -th term of the sequence is equal to $2^{x+1} - 1$, where x is the exponent of the largest power of 2 which divides i . See entry A038712 in the Encyclopedia of Integer Sequences [18].

While sequence σ_{h-1} was used for the construction of T_h (recall that L_i and R_i are two copies of $T_{\sigma_{h-1}(i)}$), sequence π_{h-1} is useful for the study of the minimum width of an LR-drawing of T_h . Indeed, by induction any LR-drawing of L_i requires width $2^{\sigma_{h-1}(i)} - 1$, which is equal to $\pi_{h-1}(i)$. Hence, the widths required by L_1, \dots, L_{k-1} are $\pi_{h-1}(1), \dots, \pi_{h-1}(k-1)$, respectively; that is, they form the sequence π_{h-1} . A similar statement holds true for R_1, \dots, R_{k-1} . We are going to exploit the following.

Property 3. Let ℓ and x be integers such that $\ell \geq 1$ and $1 \leq x \leq 2^\ell - 1$. For any x consecutive elements in π_ℓ , there exists one whose value is at least x .

Proof. We prove the statement by induction on ℓ . If $\ell = 1$, then $x = 1$ and the statement follows since $\pi_1(1) = 1$. Now assume that $\ell > 1$ and consider any x consecutive elements in π_ℓ . Recall that $\pi_\ell = \pi_{\ell-1}, 2^\ell - 1, \pi_{\ell-1}$. If all the x elements belong to the first repetition of $\pi_{\ell-1}$ in π_ℓ , or if all the x elements belong to the second repetition of $\pi_{\ell-1}$ in π_ℓ , then $x \leq 2^{\ell-1} - 1$ and the statement follows by induction. Otherwise, since the x elements are consecutive, the “central” element whose value is $2^\ell - 1$ is among them. Then the statement follows since $x \leq 2^\ell - 1$. \square

We are now ready to discuss the inductive case of the lemma. Consider the subtrees $T(u_1), \dots, T(u_k)$ of T_h rooted at u_1, \dots, u_k , respectively (note that $T(u_1) = T_h$). We claim that $T(u_j)$ requires width $2^{h-1} + k - j$ in any LR-drawing, for $j = 1, \dots, k$. The lemma follows from the claim, as the latter (with $j = 1$) implies that T_h requires width $2^{h-1} + k - 1 = 2^h - 1$ in any LR-drawing.

Assume, for a contradiction, that the claim is not true, and let $j \in \{1, \dots, k\}$ be the maximum index such that there exists an LR-drawing Γ of $T(u_j)$ whose width is less than $2^{h-1} + k - j$. First, since the subtrees of u_k are two copies of T_{h-1} and since by the inductive hypothesis T_{h-1} requires width $2^{h-1} - 1$ in any LR-drawing, by Lemma 2 the representation sequence of $T(u_k)$ is

$$\mathcal{S}_{T(u_k)} = \left[\underbrace{2^{h-1} - 1, \dots, 2^{h-1} - 1}_{\text{index } 0}, \underbrace{2^{h-1} - 1}_{\text{index } 2^{h-1}-2}, \underbrace{0}_{\text{index } 2^{h-1}-1} \right].$$

Hence, $T(u_k)$ requires width 2^{h-1} in any LR-drawing, which implies that $j < k$. Let α and β be the left and right width of Γ , respectively. In order to derive a contradiction, we prove that $\alpha + \beta + 1 \geq 2^{h-1} + k - j$.

Suppose first (refer to Fig. 5(a)) that Γ is constructed by using the left rule at u_j, \dots, u_{k-1} and the right rule at v_j, \dots, v_{k-1} , hence nodes u_j, \dots, u_{k-1}, u_k and v_j, \dots, v_{k-1} are all aligned on the same vertical line. Then α (β) is larger than or equal to the widths of L_j, \dots, L_{k-1} (resp. of R_j, \dots, R_{k-1}) in Γ . We prove that $\alpha \geq 2^{h-1} - 1$ or $\beta \geq 2^{h-1} - 1$. If Γ has left width $\alpha \leq 2^{h-1} - 2$, then the LR-drawing of $T(u_k)$ in Γ also has left width at most $2^{h-1} - 2$, given that u_j and u_k are vertically aligned; since $\mathcal{S}_{T(u_k)}(2^{h-1} - 2) = 2^{h-1} - 1$, it follows that the right width of the LR-drawing of $T(u_k)$ in Γ is at least $2^{h-1} - 1$, and Γ has right width $\beta \geq 2^{h-1} - 1$. This proves that $\alpha \geq 2^{h-1} - 1$ or $\beta \geq 2^{h-1} - 1$. Assume that $\alpha \geq 2^{h-1} - 1$, as the case $\beta \geq 2^{h-1} - 1$ is symmetric. By induction, the width of the drawing of R_i in Γ is at least $\pi_{h-1}(i)$. Hence, the widths of the subtrees R_j, \dots, R_{k-1} form a sequence of $k - j \geq 1$ consecutive elements of π_{h-1} . By Property 3, there exists an element $\pi_{h-1}(i)$ whose value is at least $k - j$. Then $\beta \geq k - j$ and $\alpha + \beta + 1 \geq (2^{h-1} - 1) + (k - j) + 1 = 2^{h-1} + k - j$, a contradiction.

Suppose next (refer to Fig. 5(b)) that, for some integer m with $j \leq m \leq k - 1$, drawing Γ is constructed by using the left rule at u_j, \dots, u_{m-1} , the right rule at v_j, \dots, v_{m-1} , and the right rule at

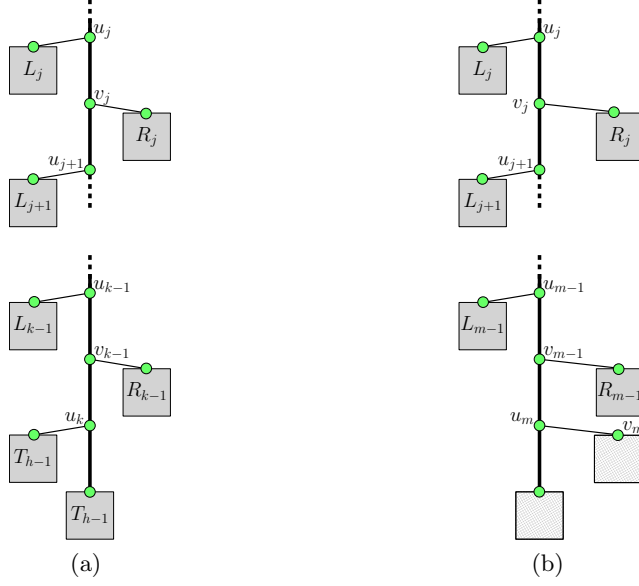


Fig. 5: Illustration for the proof of Lemma 6. (a) Γ uses the left rule at u_j, \dots, u_{k-1} and the right rule at v_j, \dots, v_{k-1} . (b) Γ uses the left rule at u_j, \dots, u_{m-1} and the right rule at v_j, \dots, v_{m-1}, u_m .

u_m . Hence, nodes u_j, \dots, u_m and v_j, \dots, v_{m-1} are all aligned on the same vertical line d , however v_m is to the right of d . Since L_j, \dots, L_{m-1} lie to the left of d in Γ , we have that α is larger than or equal to the widths of L_j, \dots, L_{m-1} . By the maximality of j , we have that $T(u_{m+1})$ requires width $2^{h-1} + k - (m+1)$ in any LR-drawing. Since the drawing of the subtree of T_h rooted at v_m is to the right of d in Γ , it follows that the drawing of $T(u_{m+1})$ is also to the right of d in Γ , hence $\beta \geq 2^{h-1} + k - (m+1)$. Now, if $m = j$, we have that $\alpha + \beta + 1 \geq (2^{h-1} + k - j - 1) + 1 = 2^{h-1} + k - j$, a contradiction. Hence, we can assume that $m > j$. By induction, the width of the drawing of L_i in Γ is at least $\pi_{h-1}(i)$. Hence, the widths of the subtrees L_j, \dots, L_{m-1} form a sequence of $m - j \geq 1$ consecutive elements of π_{h-1} . By Property 3, there exists an element $\pi_{h-1}(i)$ whose value is at least $m - j$. Then $\alpha \geq m - j$ and $\alpha + \beta + 1 \geq (m - j) + (2^{h-1} + k - m - 1) + 1 = 2^{h-1} + k - j$, a contradiction.

Finally, the case in which, for some integer m with $j \leq m \leq k - 1$, drawing Γ is constructed by using the left rule at u_j, \dots, u_m , the right rule at v_j, \dots, v_{m-1} , and the left rule at v_m is symmetric to the previous one. This concludes the proof of the lemma. \square

Lemma 7. *The number of nodes of T_h is at most $(3 + \sqrt{5})^h$.*

Proof. Denote by n_h the number of nodes of tree T_h . By the way T_h is recursively defined and since, for $i = 0, \dots, h - 2$, sequence σ_{h-1} contains 2^i integers equal to $h - i - 1$ (i.e., it contains one integer equal to $h - 1$, two integers equal to $h - 2$, \dots , 2^{h-2} integers equal to 1), we have:

$$\begin{aligned} n_h &= \underbrace{(2n_{h-1} + 1)}_{\text{subtree rooted at } u_k} + \underbrace{(2(2^{h-1} - 1))}_{\text{nodes } u_1, v_1, \dots, u_{k-1}, v_{k-1}} + \underbrace{2(n_{h-1} + 2n_{h-2} + \dots + 2^{h-2}n_1)}_{\text{subtrees of } u_1, v_1, \dots, u_{k-1}, v_{k-1}} \\ &= 2n_{h-1} + 2^h - 1 + \sum_{i=1}^{h-1} 2^i n_{h-i} < 2n_{h-1} + 2^h + \sum_{i=1}^{h-1} 2^i n_{h-i}. \end{aligned}$$

We now prove that $n_h \leq c^h$, for some constant c to be determined later, by induction on h . The statement trivially holds for $h = 1$, as long as $c \geq 1$, given that $n_1 = 1$. Now assume that $n_j \leq c^j$, for every $j \leq h - 1$. Substituting $n_j \leq c^j$ into the upper bound for n_h we get

$$n_h \leq 2c^{h-1} + 2^h + \sum_{i=1}^{h-1} 2^i c^{h-i} = 2c^{h-1} + \sum_{i=1}^h 2^i c^{h-i}.$$

By the factoring rule $c^{h+1} - 2^{h+1} = (c - 2)(c^h + 2c^{h-1} + \dots + 2^{h-1}c + 2^h)$ we get

$$\sum_{i=1}^h 2^i c^{h-i} = \frac{c^{h+1} - 2^{h+1}}{c - 2} - c^h = \frac{2c^h}{c - 2} - \frac{2^{h+1}}{c - 2}.$$

Substituting that into the upper bound for n_h we get

$$n_h \leq 2c^{h-1} + \frac{2c^h}{c-2} - \frac{2^{h+1}}{c-2} < 2c^{h-1} + \frac{2c^h}{c-2} = \frac{4c^h - 4c^{h-1}}{c-2},$$

where the second inequality holds as long as $c > 2$.

Thus, we want c to satisfy $\frac{4c^h - 4c^{h-1}}{c-2} \leq c^h$; dividing by c^{h-1} and simplifying, the latter becomes $c^2 - 6c + 4 \geq 0$. The associated second degree equation has two solutions $c = 3 \pm \sqrt{5}$. Hence, $n_h \leq c^h$ holds true for $c \geq 3 + \sqrt{5}$. This concludes the proof of the lemma. \square

Finally, we get the main result of this section.

Theorem 2. *For infinitely many values of n , there exists an n -node ordered rooted binary tree that requires width $\Omega(n^\delta)$ and area $\Omega(n^{1+\delta})$ in any LR-drawing, with $\delta = 1/\log_2(3 + \sqrt{5}) \geq 0.418$.*

Proof. By Lemma 6 the width of any LR-drawing of T_h is $w_h \geq 2^h - 1$. Also, by Lemma 7 tree T_h has $n_h \leq (3 + \sqrt{5})^h$ nodes, which taking the logarithms becomes $h \geq \log_{(3+\sqrt{5})} n_h$. Substituting this formula into the lower bound for the width, we get $w_h \geq 2^{\log_{(3+\sqrt{5})} n_h} - 1$. Changing the base of the logarithm provides the statement about the width. Since any LR-drawing has height exactly n , the statement about the area follows. \square

2.4 Experimental Evaluation

It is tempting to evaluate w_n^* by computing, for every n -node ordered rooted binary tree T , the minimum width w_T^* of any LR-drawing of T and by then taking the maximum among all such values. Although Theorem 1 ensures that w_T^* can be computed efficiently, this evaluation is not practically possible, because of the large number of n -node ordered rooted binary trees, which is the n -th Catalan number $\binom{2n}{n} \frac{1}{n+1} \approx 4^n$; see, e.g., [14].

We overcame this problem as follows. We say that a tree T' *dominates* a tree T if: (i) $n_{T'} \leq n_T$; (ii) $k_{T'} \geq k_T$; and (iii) for $i = 0, \dots, k_T - 1$, it holds $\mathcal{S}_{T'}(i) \geq \mathcal{S}_T(i)$. In order to perform an experimental evaluation of w_n^* , we construct a set \mathcal{T}_n of ordered rooted binary trees with at most n nodes such that every ordered rooted binary tree with at most n nodes is dominated by a tree in \mathcal{T}_n .

First, the dominance relationship ensures that, if an n -node ordered rooted binary tree exists requiring a certain width in any LR-drawing, then a tree in \mathcal{T}_n also requires (at least) the same width in any LR-drawing (in a sense, the trees in \mathcal{T}_n are the “worst case” trees for the width of an LR-drawing).

Second, the size of \mathcal{T}_n can be kept “small” by ensuring that no tree in \mathcal{T}_n dominates another tree in \mathcal{T}_n . We could construct \mathcal{T}_n for n up to 455, with \mathcal{T}_{455} containing more than two million trees.

Third, \mathcal{T}_n can be constructed so that, for every $T \in \mathcal{T}_n$, the left and right subtrees of r_T are also in \mathcal{T}_n . This is proved by induction on $|T|$. The base case $|T| = 1$ is trivial. Further, if a tree T in \mathcal{T}_n has the left subtree L of r_T that is not in \mathcal{T}_n , then L can be replaced with a tree in \mathcal{T}_n that dominates L ; this tree exists since $|L| < |T|$. This results in a tree T' that dominates T . A similar replacement of the right subtree of r_T results in a tree T'' that dominates T and such that the left and right subtrees of $r_{T''}$ are both in \mathcal{T}_n ; then we replace T with T'' in \mathcal{T}_n . Replacing all the trees with $|T|$ nodes in \mathcal{T}_n completes the induction. Consequently, \mathcal{T}_n can be constructed starting from \mathcal{T}_{n-1} by considering a number of n -node trees whose size is quadratic in $|\mathcal{T}_{n-1}|$. Every time a tree T is considered, its dominance relationship with every tree currently in \mathcal{T}_n is tested. If a tree in \mathcal{T}_n dominates T , then T is discarded; otherwise, T enters \mathcal{T}_n and every tree in \mathcal{T}_n that is dominated by T is discarded. Note that the dominance relationship between two trees T and T' can be tested in time proportional to the size of \mathcal{S}_T and $\mathcal{S}_{T'}$.

By means of this approach, we were able to compute the value of w_n^* for n up to 455. Table 1 shows the minimum integer n such that there exists an n -node ordered rooted binary tree requiring a certain width

w ; for example, all the trees with up to 455 nodes have LR-drawings with width at most 22, and all the trees with up to 426 nodes have LR-drawings with width at most 21. Our experiments were performed with a monothread Java implementation on a machine with two 4-core 3.16GHz Intel(R) Xeon(R) CPU X5460 processors, with 48GB of RAM, running Ubuntu 14.04.2 LTS. The computation of the trees with 455 nodes in \mathcal{T}_{455} took more than one month.

w	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22
n	1	3	7	11	19	27	35	47	61	77	95	111	135	159	185	215	243	275	311	343	383	427

Table 1: The table shows, for every integer w between 1 and 22, the minimum number n of nodes of a tree requiring w width in any LR-drawing.

We used the Mathematica software [21] in order to find a function of the form $w = a \cdot n^b + c$ that better fits the values of Table 1, according to the *least squares* optimization method (see, e.g., [19]). Recall that by Theorem 2 and by Chan results [3], w_n^* is asymptotically between $\Omega(n^{0.418})$ and $O(n^{0.48})$. We obtained $w = 1.54002 \cdot n^{0.443216} - 0.549577$ as an optimal function; see Fig. 6. This seems to indicate that the best known upper and lower bounds are not tight.

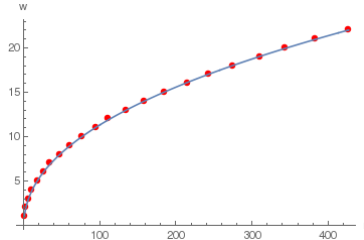


Fig. 6: Function $w = 1.54002 \cdot n^{0.443216} - 0.549577$ (blue line) and data from Table 1 (red dots).

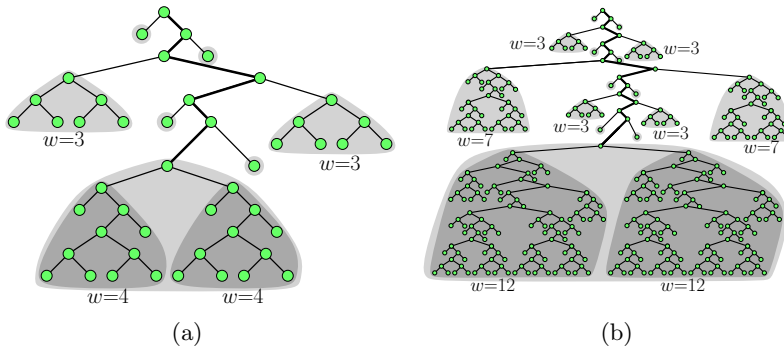


Fig. 7: (a) A tree with $n = 47$ nodes requiring width 8 in any LR-drawing. (b) A tree with $n = 343$ nodes requiring width 20 in any LR-drawing.

As a final remark, we note that the structure of the trees corresponding to the pairs (n, w) in Table 1 (see Fig. 7) is similar to the structure of the trees that provide the lower bound of Theorem 2, which might indicate that the lower bound is close to be tight: In particular, the left (and right) subtrees of the thick path in Fig. 7(b) require width 1, 3, 1, 7, 1, 3, 1 from top to bottom, as in the lower bound tree T_4

from Theorem 2; also, the subtrees of the last node of the thick path are isomorphic, as in T_4 (although these subtrees require width 7 in T_4 , while they require width 12 in Fig. 7(b)).

3 Straight-Line Drawings of Outerplanar Graphs

In this section we study outerplanar straight-line drawings of outerplanar graphs.

3.1 From Outerplanar Drawings to Star-Shaped Drawings

Let G be a maximal outerplanar graph, that is, a graph to which no edge can be added without violating its outerplanarity. We assume that G is associated with any (not necessarily straight-line) outerplanar drawing. This allows us to talk about the faces of G , rather than about the faces of a drawing of G . We denote by f^* the outer face of G . The *dual tree* T of G has a node for each face $f \neq f^*$ of G (we denote by f both the face of G and the corresponding node of T); further, T has an edge (f_1, f_2) if the faces f_1 and f_2 of G share an edge e along their boundaries; we say that e and (f_1, f_2) are *dual* to each other.

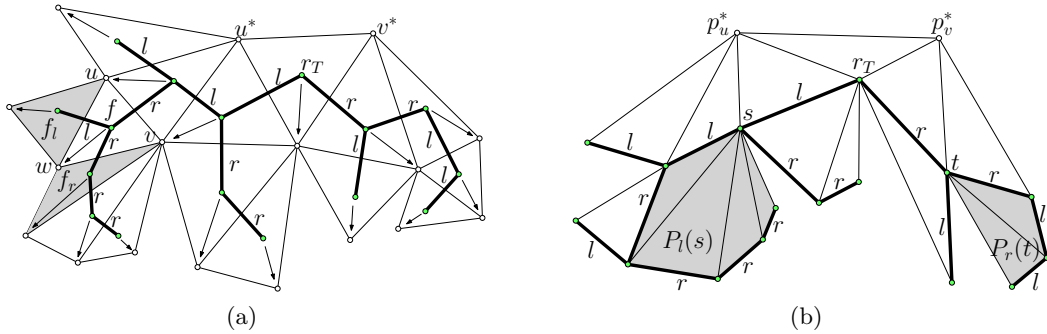


Fig. 8: (a) A maximal outerplanar graph G (shown with white circles and thin line segments) and its dual tree T (shown with green circles and thick line segments). The labels l and r on the edges of T show whether a node is the left or the right child of its parent, respectively. The gray faces f_l and f_r are the left and the right child of the face f . The arrows show a bijective mapping γ from the nodes of T to the vertices of G' such that an edge (s, t) belongs to T if and only if the edge $(\gamma(s), \gamma(t))$ belongs to G' . (b) A star-shaped drawing Γ_T of T (shown with green circles and thick line segments). The gray regions show the polygons $P_l(s)$ and $P_r(t)$ for two nodes s and t of T . Adding the thin edges and the white vertices at p_u^* and p_v^* turns Γ_T into an outerplanar straight-line drawing Γ_G of G .

We now turn T into an ordered rooted binary tree. Refer to Fig. 8(a). First, pick any edge (u^*, v^*) incident to f^* , where v^* is encountered right after u^* when walking in clockwise direction along the boundary of f^* ; root T at the node corresponding to the internal face of G incident to (u^*, v^*) . Second, since G is maximal, all its internal faces are delimited by cycles with 3 vertices, hence T is binary. Third, an outerplanar drawing of G naturally defines whether a child of a node of T is a left or right child. Namely, consider any non-leaf node f of T . If $f \neq f^*$, then let g be the parent of f and let (u, v) be the edge of G dual to (f, g) . If $f = f^*$, then let $u = u^*$ and $v = v^*$. In both cases, let $w \neq u, v$ be the third vertex of G incident to f ; assume, w.l.o.g. that u, v , and w appear in this clockwise order along the boundary of f . Let (f, f_l) and (f, f_r) be the edges of T dual to (u, w) and (v, w) , respectively. Then f_l and f_r are the left and right child of f , respectively; note that one of these children might not exist (if (u, w) or (v, w) is incident to f^*). Henceforth, we regard T as an ordered rooted binary tree.

We introduce some definitions. The *leftmost (rightmost) path* of T is the maximal path s_0, \dots, s_m such that $s_0 = r_T$ and s_i is the left (resp. right) child of s_{i-1} , for $i = 1, \dots, m$. For a node s of T , the *left-right (right-left) path* of s is the maximal path s_0, \dots, s_m such that $s_0 = s$, s_1 is the left (resp. right) child of s_0 , and s_i is the right (resp. left) child of s_{i-1} , for $i = 2, \dots, m$. For a node s of T , let $C_l(s)$ (resp. $C_r(s)$) denote the cycle composed of the left-right (resp. right-left) path s_0, \dots, s_m of s plus edge

(s_0, s_m) – this cycle degenerates into a vertex or an edge if $m = 0$ or $m = 1$, respectively. Finally, a drawing of T is *star-shaped* if it satisfies the following properties (refer to Fig. 8(b)):

1. The drawing is planar, straight-line, and *order-preserving* (that is, for every degree-3 node s of T , the edge between s and its parent, the edge between s and its left child, and the edge between s and its right child appear in this counter-clockwise order around s).
2. For each node s of T , draw the edge of $C_l(s)$ not in T (if such an edge exists) as a straight-line segment and let $P_l(s)$ be the polygon representing $C_l(s)$. Then $P_l(s)$ is simple (that is, not self-intersecting) and every straight-line segment between s and a non-adjacent vertex of $P_l(s)$ lies inside $P_l(s)$. A similar condition is required for the polygon $P_r(s)$ representing $C_r(s)$.
3. For any node s of T , the polygons $P_l(s)$ and $P_r(s)$ lie one outside the other, except at s ; also, for any two distinct nodes s and t of T , the polygons $P_l(s)$ and $P_r(s)$ lie outside polygons $P_l(t)$ and $P_r(t)$, and vice versa, except at common vertices and edges along their boundaries.
4. There exist two points p_u^* and p_v^* such that the straight-line segments connecting p_u^* with the nodes of the leftmost path of T , connecting p_v^* with the nodes of the rightmost path of T , and connecting p_u^* with p_v^* do not intersect each other and, for any node s of T , they lie outside polygons $P_l(s)$ and $P_r(s)$, except at common vertices.

We now describe the key ideas developed in [7] in order to relate outerplanar straight-line drawings of outerplanar graphs to star-shaped drawings of their dual trees. Let G be a maximal outerplanar graph and T be its dual tree; also, let G' be the graph obtained from G by removing vertices u^* and v^* and their incident edges. Then T is a subgraph of G' ; in fact, there exists a bijective mapping γ from the nodes of T to the vertices of G' such that an edge (s, t) belongs to T if and only if the edge $(\gamma(s), \gamma(t))$ belongs to G' (see Fig. 8(a)). Further, the graph obtained by adding to T , for every node s in T , edges connecting s with all the (not already adjacent) nodes on the left-right and on the right-left path of s is G' . Properties 1–3 of a star-shaped drawing ensure that, in order to obtain an outerplanar straight-line drawing of G' , one can start from a star-shaped drawing of T and just draw the edges of G' not in T as straight-line segments. Finally, an outerplanar straight-line drawing of G is obtained by mapping u^* and v^* to p_u^* and p_v^* (defined as in Property 4 of a star-shaped drawing), respectively, and by drawing their incident edges as straight-line segments (see Fig. 8(b)).

If one starts from a star-shaped drawing Γ_T of T in a certain area A , an outerplanar straight-line drawing Γ_G of G can be constructed as described above; then the area of Γ_G might be larger than A , since points p_u^* and p_v^* might lie outside the bounding box of Γ_T . However, Γ_G is equal to the area of the smallest axis-parallel rectangle⁴ containing p_u^* , p_v^* , and Γ_T . We formalize this in the following.

Lemma 8. (*Di Battista and Frati [7]*) *If T admits a star-shaped drawing Γ_T , then G admits an outerplanar straight-line drawing Γ_G whose area is equal to the area of the smallest axis-parallel rectangle containing p_u^* , p_v^* , and Γ_T .*

In the next sections we will show algorithms for constructing star-shaped drawings Γ_T of ordered rooted binary trees T in which the smallest axis-parallel rectangle containing Γ_T , p_u^* , and p_v^* has asymptotically the same area as Γ_T .

3.2 Star-Shaped Drawings with $O(\omega)$ Width

In this section we show that, if an ordered rooted binary tree admits an LR-drawing with width ω , then it admits a star-shaped drawing with width $O(\omega)$. In fact, we will prove the existence of two star-shaped drawings with that width, each satisfying some additional geometric properties. Because of the similarity of our constructions with the ones in [7], we will not prove formally that the constructed drawings are star-shaped, and we will only provide the main intuition for that. Further, the illustrations of our constructions will show the points p_u^* and p_v^* (represented by white disks) and the straight-line segments (represented by gray lines) to be added to the star-shaped drawings according to Properties 2 and 4 from Section 3.1. Given a drawing Γ of a tree, we often say that a vertex u *sees* another vertex v if the straight-line segment between u and v does not cross Γ .

Consider a star-shaped drawing Γ of an ordered rooted binary tree T . Denote by $B_l(\Gamma)$, $B_t(\Gamma)$, $B_r(\Gamma)$, and $B_b(\Gamma)$ the left, top, right, and bottom side of $B(\Gamma)$, respectively.

⁴ By the *width* and the *height* of a rectangle we mean the number of grid columns and rows intersecting it, respectively. By the *area* of a rectangle we mean its width times its height.

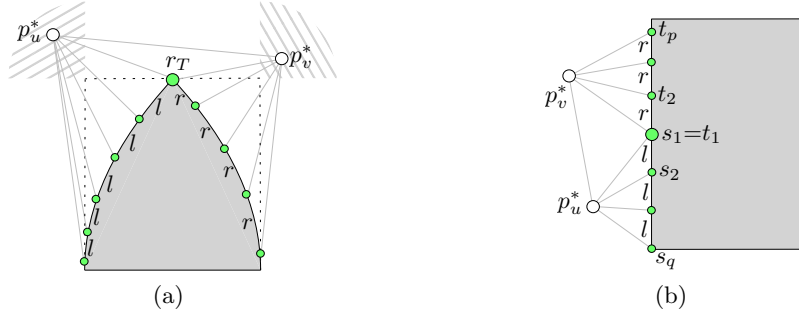


Fig. 9: (a) A schematization of the shape of a bell-like star-shaped drawing. (b) A schematization of the shape of a flat star-shaped drawing.

We say that Γ is *bell-like* (see Fig. 9(a)) if: (i) r_T lies on $B_t(\Gamma)$; and (ii) any point p_u^* above $B_l(\Gamma)$ and to the left of $B_l(\Gamma)$ and any point p_v^* above $B_r(\Gamma)$ and to the right of $B_r(\Gamma)$ satisfy Property 4 of a star-shaped drawing.

We say that Γ is *flat* (see Fig. 9(b)) if: (i) the leftmost path ($s_1 = r_T, \dots, s_q$) and the rightmost path ($t_1 = r_T, \dots, t_p$) of T lie on $B_l(\Gamma)$; and (ii) $y(s_{i-1}) > y(s_i)$, for $i = 2, \dots, q$, and $y(t_{i-1}) < y(t_i)$, for $i = 2, \dots, p$.

We now present the main lemma of this section.

Lemma 9. *Consider an n -node ordered rooted binary tree T and suppose that T admits an LR-drawing with width ω . Then T admits a bell-like star-shaped drawing with width at most $4\omega - 2$ and height at most n , and a flat star-shaped drawing with width at most 4ω and height at most n .*

In the remainder of the section we prove Lemma 9 by exhibiting two algorithms, called *bell-like algorithm* and *flat algorithm*, that construct bell-like and flat star-shaped drawings of trees, respectively. Both algorithms use induction on ω ; each of them is defined in terms of the other one. The base case of both algorithms is $\omega = 1$. This implies that T is a root-to-leaf path ($v_1 = r_T, \dots, v_n$), as in Fig. 10(a).

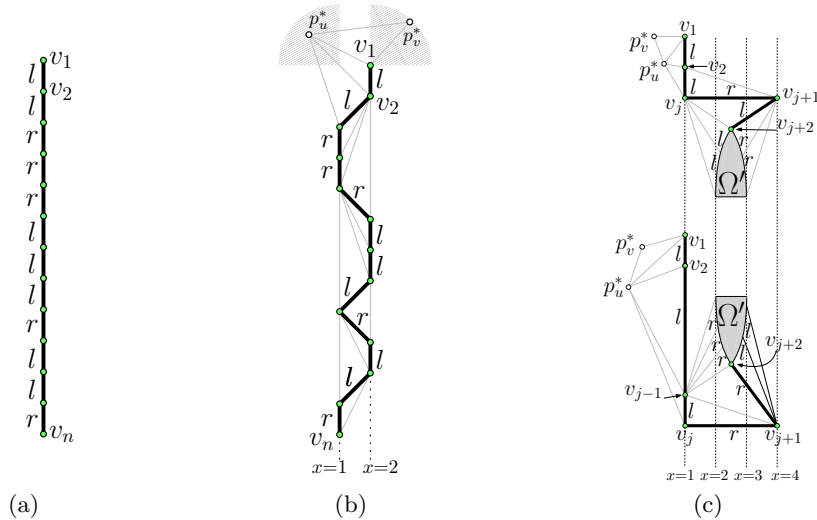


Fig. 10: (a) An LR-drawing with width 1 of a tree T . (b) A bell-like star-shaped drawing with width 2 of T . Any points p_u^* and p_v^* in the shaded regions see all the nodes of the leftmost and rightmost path of T , respectively. (c) A flat star-shaped drawing with width 4 of T , if v_{j+2} is the left (see top) or right (see bottom) child of v_{j+1} .

The bell-like algorithm constructs a bell-like star-shaped drawing Ω of T as follows (refer to Fig. 10(b)). For $i = 1, \dots, m$, set $y(v_i) = -i$. Also, set $x(v_i) = 2$ for every node v_i such that $i < n$ and such that v_{i+1} is the left child of v_i , and set $x(v_i) = 1$ for every other node v_i . Then Ω has width at most $2 = 4\omega - 2$ and height n . Further, Ω is readily seen to be a bell-like star-shaped drawing. In particular, the left-right path of each node v_i is either a single node, or is a single edge, or is represented by the legs and the base with smaller length of an isosceles trapezoid (which possibly degenerates to a triangle); thus v_i sees its left-right path. Similarly v_i sees its right-left path, and hence Ω satisfies Property 2 of a star-shaped drawing. Moreover, the leftmost path of T is either a single node (if v_2 is the right child of v_1) or is a polygonal line that is strictly decreasing in the y -direction and non-increasing in the x -direction from r_T to its last node. A similar argument for the rightmost path, together with the fact that r_T lies on Ω_t , implies that Ω satisfies the bell-like property.

The flat algorithm constructs a flat star-shaped drawing Π of T as follows (refer to Fig. 10(c)). Assume that v_2 is the left child of v_1 ; the other case is symmetric. Let (v_1, \dots, v_j) be the leftmost path of T , where $j \geq 2$. If $j = n$, then Π is constructed by setting $x(v_i) = 1$ and $y(v_i) = -i$, for $i = 1, \dots, n$ (then Π has width $1 < 4\omega$ and height n). Otherwise, v_{j+1} is the right child of v_j . Use the bell-like algorithm to construct a bell-like star-shaped drawing Ω' with width at most 2 of the subtree of T rooted at v_{j+2} (note that this subtree has an LR-drawing with width 1 since T does). We distinguish two cases.

- If v_{j+2} is the left child of v_{j+1} (as in Fig. 10(c) top), then set $x(v_i) = 1$ and $y(v_i) = -i$, for $i = 1, \dots, j$, $x(v_{j+1}) = 4$, and $y(v_{j+1}) = -j$. Place Ω' so that $B_t(\Omega')$ is on the line $y = -j - 1$, and so that $B_l(\Omega')$ is on the line $x = 2$. Since v_j is above $B_t(\Omega')$ and to the left of $B_l(\Omega')$, it sees all the nodes of its right-left path, given that Ω' satisfies the bell-like property; since v_{j+1} is above $B_t(\Omega')$ and to the right of $B_r(\Omega')$, it sees all the nodes of its left-right path; hence Π satisfies Property 2 of a star-shaped drawing.
- If v_{j+2} is the right child of v_{j+1} (as in Fig. 10(c) bottom), then set $x(v_j) = 1$, $y(v_j) = 0$, $x(v_{j-1}) = 1$, and $y(v_i) = 1$; rotate Ω' by 180° and place it so that $B_b(\Omega')$ is on the line $y = 2$, and so that $B_l(\Omega')$ is on the line $x = 2$; finally, place vertices v_1, \dots, v_{j-2} , if any, on the line $x = 1$, so that v_{j-2} is one unit above $B_t(\Omega')$, and so that $y(v_i) = y(v_{i+1}) + 1$, for $i = 1, \dots, j - 3$. Since v_{j-1} is below $B_b(\Omega')$ and to the left of $B_l(\Omega')$, it sees all the nodes of its left-right path, given that Ω' is rotated by 180° and satisfies the bell-like property; since v_{j+1} is below $B_b(\Omega')$ and to the right of $B_r(\Omega')$, it sees all the nodes of its right-left path; hence Π satisfies Property 2 of a star-shaped drawing.

In both cases the leftmost path of T lies on $B_l(\Pi)$, with $r_T = v_1$ as the vertex with largest y -coordinate; hence Π satisfies the flat property. This concludes the description of the base case.

We now discuss the inductive case, in which $\omega > 1$. Refer to Fig. 11(a). Let Γ be an LR-drawing of T with width ω ; let ω_l and ω_r be the left and right width of Γ , respectively; we are going to use $\omega_l + \omega_r + 1 = \omega$, which holds by Property 1 of an LR-drawing; in particular, $\omega_l, \omega_r < \omega$. Define a path $P = (v_1, \dots, v_m)$ as follows. First, let $v_1 = r_T$; for $i = 1, \dots, m - 1$, node v_{i+1} is the left or right child of v_i , depending on whether Γ uses the right or the left rule at v_i , respectively; finally, v_m is either a leaf, or a node with no left child at which Γ uses the right rule, or a node with no right child at which Γ uses the left rule. Note that P lies on a single vertical line in Γ . Denote by l_i or r_i the child not in P of v_i , depending on whether that node is a left or right child of v_i , respectively; denote by L_i (by R_i) the subtree of T rooted at l_i (resp. r_i). Note that L_i (R_i) admits an LR-drawing with width at most ω_l (resp. ω_r), hence by induction it also admits a bell-like star-shaped drawing with width at most $4\omega_l - 2$ (resp. $4\omega_r - 2$), and a flat star-shaped drawing with width at most $4\omega_l$ (resp. $4\omega_r$).

The bell-like algorithm constructs a bell-like star-shaped drawing Ω of T as follows. Refer to Fig. 11(b). Let $j \geq 1$ ($h \geq 1$) be the smallest index such that Γ uses the left (resp. right) rule at v_j . Index j (h) might be undefined if Γ uses the right (resp. left) rule at every node of P . Inductively construct a bell-like star-shaped drawing Ω_j of L_j (if this subtree exists) and a bell-like star-shaped drawing Ω_h of R_h (if this subtree exists); inductively construct a flat star-shaped drawing Π_i of every other subtree L_i or R_i of P . Similarly to the base case, set $x(v_i) = 2$ or $x(v_i) = 1$, depending on whether the left child of v_i is v_{i+1} or not, respectively. Next, we define the placement of Ω_j , of Ω_h , and of each Π_i with respect to v_j , v_h , and v_i , respectively. Drawing Ω_j (Ω_h) is placed so that $B_r(\Omega_j)$ ($B_l(\Omega_h)$) lies on the line $x = 0$ (resp. $x = 3$) and so that $B_t(\Omega_j)$ ($B_t(\Omega_h)$) is one unit below v_j (resp. v_h). For every right subtree $R_i \neq R_h$ of P , drawing Π_i is placed so that $B_l(\Pi_i)$ lies on the line $x = 3$ and so that $y(r_i) = y(v_i)$; further, for every left subtree $L_i \neq L_j$ of P , drawing Π_i is first rotated by 180° , and then it is placed so that $B_r(\Pi_i)$ lies

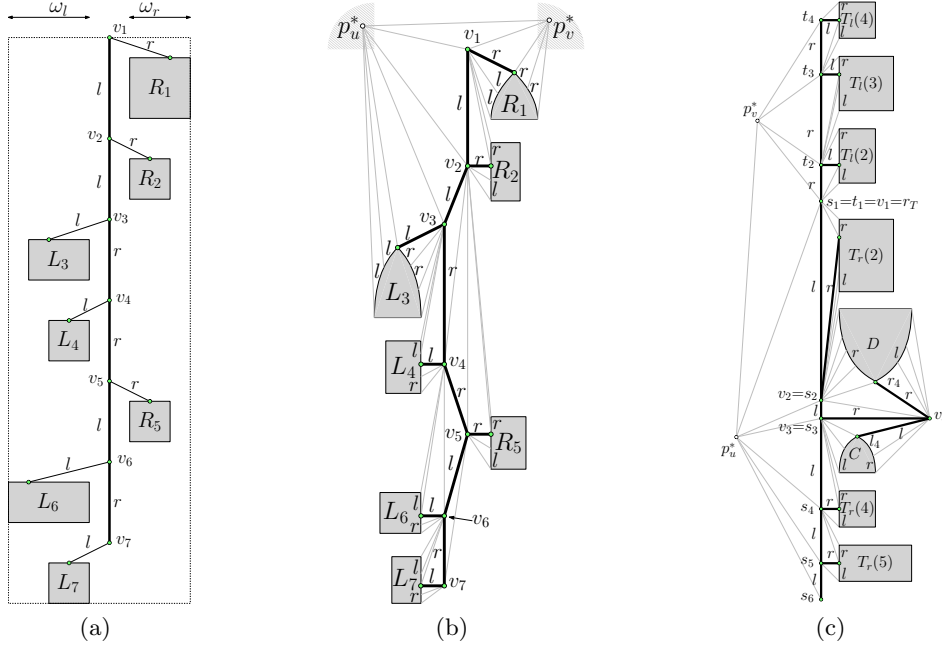


Fig. 11: (a) An LR-drawing Γ of T . (b) A bell-like star-shaped drawing Ω of T . In this example $j = 3$ and $h = 1$. (c) A flat star-shaped drawing Π of T . In this example $j = 3$, $p = 4$, and $q = 6$.

on the line $x = 0$ and so that $y(l_i) = y(v_i)$. Finally, for $i = 1, \dots, m - 1$, set $y(v_i)$ so that the bottom side of the smallest axis-parallel rectangle containing v_i and the drawing of its subtree L_i or R_i is one unit above the top side of the smallest axis-parallel rectangle containing v_{i+1} and the drawing of its subtree L_{i+1} or R_{i+1} . This completes the construction of Ω . The height of Ω is at most n , since every grid row intersecting Ω contains a node of P or intersects a subtree of P . Further, the width of Ω is equal to the maximum width of the drawing of a subtree L_i , which is at most $4\omega_l$ by induction, plus the maximum width of the drawing of a subtree R_i , which is at most $4\omega_r$ by induction, plus two, since the nodes of P lie on two grid columns. Hence the width of Ω is at most $4\omega_l + 4\omega_r + 2 = 4\omega - 2$. The leftmost path of T is composed of the path (v_1, \dots, v_j, l_j) and of the leftmost path of L_j . Since (v_1, \dots, v_j, l_j) is represented in Ω by a polygonal line that is strictly decreasing in the y -direction and non-increasing in the x -direction from v_1 to l_j , and since every point to the left of $B_l(\Omega_j)$ and above $B_t(\Omega_j)$ sees all the nodes of the leftmost path of L_j , by induction, we get that every point to the left of $B_l(\Omega)$ and above $B_t(\Omega)$ sees all the nodes of the leftmost path of T . A similar argument for the rightmost path, together with the fact that r_T lies on $B_t(\Omega)$, implies that Ω satisfies the bell-like property. Concerning Property 2 of a star-shaped drawing, we note that v_j sees all the nodes of its left-right path since it is above $B_t(\Omega_j)$ and to the right of $B_r(\Omega_j)$, and since Ω_j satisfies the bell-like property. Also, if v_{i+1} is the left child of v_i and v_{i+2} is the right child of v_{i+1} , as with $i = 2$ in Fig. 11(b), then the representation of the left-right path of v_i in Ω consists of the legs and of the base with smaller length of a trapezoid, of a horizontal segment between the lines $x = 2$ and $x = 3$, and of a vertical segment on the line $x = 3$; hence v_i sees all the nodes of its left-right path.

The flat algorithm constructs a flat star-shaped drawing Π of T as follows. Refer to Fig. 11(c). Assume that v_2 is the left child of v_1 ; the other case is symmetric.

First, we construct a drawing Π_R of the right subtree R_1 of r_T . Let $(t_1 = r_T, \dots, t_p)$ be the rightmost path of T . For $i = 2, \dots, p$, let $T_l(i)$ be the left subtree of t_i . Since v_2 is the left child of v_1 , drawing Γ uses the right rule at v_1 , hence R_1 admits an LR-drawing with width at most ω_r . Tree $T_l(i)$ also admits an LR-drawing with width at most ω_r , given that it is a subtree of R_1 . By induction $T_l(i)$ admits a flat star-shaped drawing $\Pi_l(i)$ with width at most $4\omega_r \leq 4\omega - 4$. Set $x(t_i) = 1$ for $i = 2, \dots, p$. Next, we define the placement of each $\Pi_l(i)$ with respect to t_i . Drawing $\Pi_l(i)$ is placed so that $B_l(\Pi_l(i))$ is on the line $x = 2$ and so that the root of $T_l(i)$ is on the same horizontal line as t_i . Finally, set $y(t_i)$ so that, for $i = 3, \dots, p$, the bottom side of the smallest axis-parallel rectangle containing t_i and $\Pi_l(i)$ is one unit

above the top side of the smallest axis-parallel rectangle containing t_{i-1} and $\Pi_l(i-1)$. This completes the construction of Π_R .

Second, we construct a drawing Π_L of the left subtree L_1 of r_T . Let $(s_1 = r_T, \dots, s_q)$ be the leftmost path of T and, for $i = 2, \dots, q$, let $T_r(i)$ be the right subtree of s_i . Further, let $j \geq 2$ be the largest integer for which (s_1, \dots, s_j) belongs to P ; that is, $s_i = v_i$ holds true for $i = 1, \dots, j$. Although v_j might be the last node of P , we assume that v_{j+1} exists; the construction for the case in which v_{j+1} does not exist is much simpler. By the maximality of j , we have that v_{j+1} is the right child of v_j . Let C and D be the left and right subtrees of v_{j+1} , respectively (possibly one or both of these subtrees are empty). Each of C and D admits an LR-drawing with width ω , given that Γ has width ω . Construct bell-like star-shaped drawings Ω_C of C and Ω_D of D with width at most $4\omega - 2$. Note that, for $i = 2, \dots, j-1$, drawing Γ uses the right rule at v_i , hence the LR-drawing of $T_r(i)$ in Γ has width at most $\omega_r \leq \omega - 1$. Further, since Γ uses the left rule at v_j , the LR-drawing of L_j in Γ has width at most $\omega_l \leq \omega - 1$; since tree $T_r(i)$ is a subtree of L_j , for $i = j+2, \dots, q$, it also admits an LR-drawing with width at most ω_l . Hence, for $i = 2, \dots, q$ with $i \neq j, j+1$, tree $T_r(i)$ admits a flat star-shaped drawing $\Pi_r(i)$ with width at most $4\omega - 4$. We now place all these drawings together.

- For $i = 2, \dots, j-2$, set $x(s_i) = 1$ and place $\Pi_r(i)$ so that $B_l(\Pi_r(i))$ is on the line $x = 2$ and so that the root of $T_r(i)$ is on the same horizontal line as s_i ; for $i = 2, \dots, j-3$, set $y(s_i)$ so that the bottom side of the smallest axis-parallel rectangle containing s_i and $\Pi_r(i)$ is one unit above the top side of the smallest axis-parallel rectangle containing s_{i+1} and $\Pi_r(i+1)$. This part of the construction is vacuous if $j \leq 3$ as in Fig. 11(c).
- Place $\Pi_r(j-1)$ so that $B_l(\Pi_r(j-1))$ is on the line $x = 2$ and, if $j \geq 4$, so that the bottom side of the smallest axis-parallel rectangle containing s_{j-2} and $\Pi_r(j-2)$ is one unit above $B_t(\Pi_r(j-1))$.
- Rotate Ω_D by 180° and place it so that $B_l(\Omega_D)$ is on the line $x = 2$ and $B_t(\Omega_D)$ is one unit below the smallest axis-parallel rectangle containing s_{j-2} , $\Pi_r(j-2)$, and $\Pi_r(j-1)$.
- Set $x(v_{j-1}) = 1$ and place v_{j-1} one unit below the bottom side of the smallest axis-parallel rectangle containing s_{j-2} , $\Pi_r(j-2)$, $\Pi_r(j-1)$, and Ω_D ; further, set $x(v_j) = 1$, $y(v_j) = y(v_{j-1}) - 1$, $x(v_{j+1}) = 4\omega$, and $y(v_{j+1}) = y(v_j)$.
- Place Ω_C so that $B_l(\Omega_C)$ is on the line $x = 2$ and $B_t(\Omega_C)$ is one unit below v_j .
- Finally, for $i = j+1, \dots, q$, set $x(s_i) = 1$ and place $\Pi_r(i)$ so that $B_l(\Pi_r(i))$ is on the line $x = 2$ with the root of $T_r(i)$ on the same horizontal line as s_i ; also, set $y(s_i)$ so that the bottom side of the smallest axis-parallel rectangle containing s_{i-1} and $\Pi_r(i-1)$ (or containing v_j and Ω_C if $i = j+1$) is one unit above the top side of the smallest axis-parallel rectangle containing s_i and $\Pi_r(i)$.

This completes the construction of Π_L . If $j = 2$, then r_T has been drawn in Π_L ; hence, we obtain a drawing Π of T by placing Π_R and Π_L so that $B_b(\Pi_R)$ is one unit above $B_t(\Pi_L)$. If $j \geq 3$, then r_T has not been drawn in Π_L ; hence, we obtain Π by placing r_T , Π_R , and Π_L so that $x(r_T) = 1$ and so that r_T is one unit below $B_b(\Pi_R)$ and one unit above $B_t(\Pi_L)$.

The only grid columns intersecting Π are the lines $x = i$ with $i = 1, \dots, 4\omega$. Indeed, the nodes of the leftmost and rightmost path of T lie on the line $x = 1$, while v_{j+1} lies on the line $x = 4\omega$. Drawings $\Pi_l(i)$ and $\Pi_r(i)$ have the left sides of their bounding boxes on the line $x = 2$ and have width at most $4\omega - 4$; finally, drawings Ω_C and Ω_D have the left sides of their bounding boxes on the line $x = 2$ and have width at most $4\omega - 2$. It follows that the width of Π is 4ω .

The flat property is clearly satisfied by Π . That Π is a star-shaped drawing can be proved by exploiting the same arguments as in the proof that Ω is a star-shaped drawing. In particular, v_{j-1} sees all the nodes of its left-right path since it is placed below $B_b(\Omega_D)$ and to the left of $B_l(\Omega_D)$, since Ω_D is rotated by 180° , and since Ω_D satisfies the bell-like property. This concludes the proof of Lemma 9.

Since points p_u^* and p_v^* can be chosen in any bell-like or flat star-shaped drawing Γ so that the smallest axis-parallel rectangle containing p_u^* , p_v^* , and Γ has asymptotically the same area as Γ , it follows by Lemmata 8 and 9 that, if an ordered rooted binary tree T admits an LR-drawing with width ω , then the outerplanar graph T is the dual tree of admits an outerplanar straight-line drawing with width $O(\omega)$ and area $O(n \cdot \omega)$.

3.3 Star-Shaped Drawings with $O\left(2\sqrt{2^{\log_2 n}}\sqrt{\log n}\right)$ Width

In this section we show that every n -node ordered rooted binary tree T admits a star-shaped drawing with height $O(n)$ and width $O\left(2\sqrt{2^{\log_2 n}}\sqrt{\log n}\right)$. Similarly to the previous section, we show two different

algorithms to construct star-shaped drawings of T . The first one, which is called *strong bell-like algorithm*, constructs a bell-like star-shaped drawing of T . The second one, which is called *strong flat algorithm*, constructs a flat star-shaped drawing of T . Throughout the section, we denote by $f(n)$ the maximum width of a drawing of an n -node ordered rooted binary tree constructed by means of any of these algorithms. Both algorithms are parametric, with respect to a parameter $A < n$ to be fixed later. Further, both algorithms work by induction on n and exploit a structural decomposition of T due to Chan et al. [2–4], for which we include a proof, for the sake of completeness. See Fig. 12.

Lemma 10. (Chan et al. [2–4]) *There exists a path $P = (v_1, \dots, v_k)$ in T such that: (i) $v_1 = r_T$; (ii) the subtree of T rooted at v_k has at least $n - A$ nodes; and (iii) each subtree of v_k has less than $n - A$ nodes.*

Proof. Let $v_1 = r_T$. Suppose that P has been constructed up to a node v_j , for some $j \geq 1$, such that the subtree of T rooted at v_j has at least $n - A$ nodes. If a child of v_j is the root of a subtree of T with at least $n - A$ nodes, then let v_{j+1} be that child. Otherwise, $k = j$ terminates the definition of P . \square

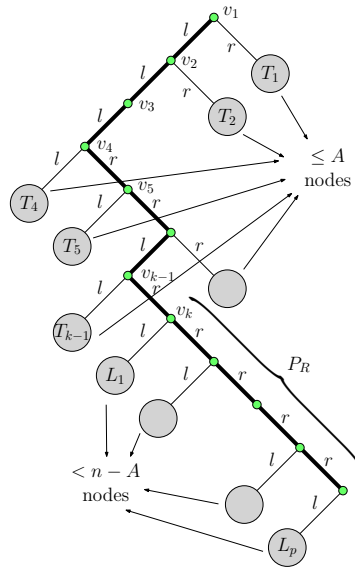


Fig. 12: An illustration for the structural decomposition of T exploited in Section 3.3. The tree in this example has 3 switches, the first of which is triple (v_3, v_4, v_5) .

We will say that the path P is the *spine* of T . For the sake of the simplicity of the algorithm's description, we will assume that $k > 1$ (the case in which $k = 1$ is easy to handle) and that v_k is the right child of v_{k-1} (the case in which v_k is the left child of v_{k-1} is symmetric). For $i = 1, \dots, k - 1$, denote by T_i the subtree of T rooted at the child of v_i not in P . Let P_R be the rightmost path of the subtree of T rooted at v_k and let L_1, \dots, L_p be the subtrees of P_R . Notice that each tree T_i has at most A nodes (by condition (ii) of Lemma 10) and each tree L_i has less than $n - A$ nodes (by condition (iii) of Lemma 10). Let a *switch* of the spine P be a triple (v_i, v_{i+1}, v_{i+2}) with $i \leq k - 2$ such that: (i) v_{i+1} is the left child of v_i and v_{i+2} is the right child of v_{i+1} ; or (ii) v_{i+1} is the right child of v_i and v_{i+2} is the left child of v_{i+1} . Let s be number of switches of P . For $i = 1, \dots, s$, let $\pi(i)$ be such that $(v_{\pi(i)}, v_{\pi(i)+1}, v_{\pi(i)+2})$ is the i -th switch of P . Note that $\pi(i + 1) \geq \pi(i) + 1$, for $i = 1, \dots, s - 1$.

The strong flat algorithm uses different constructions for the case in which $s \leq 7$ and the case in which $s \geq 8$. Further, the strong bell-like algorithm uses different constructions for the case in which $s \leq 4$ and the case in which $s \geq 5$. We start by describing the construction which is used by the strong flat algorithm if $s \leq 7$.

Strong flat algorithm with $s \leq 7$. This is the easiest case of the recursive algorithm. The spine P , together with the leftmost and rightmost paths of T and of certain subtrees of T , is going to be drawn on a set of at most $s + 1$ grid columns. In fact, the first vertices of the spine (up to $v_{\pi(1)+1}$) are drawn

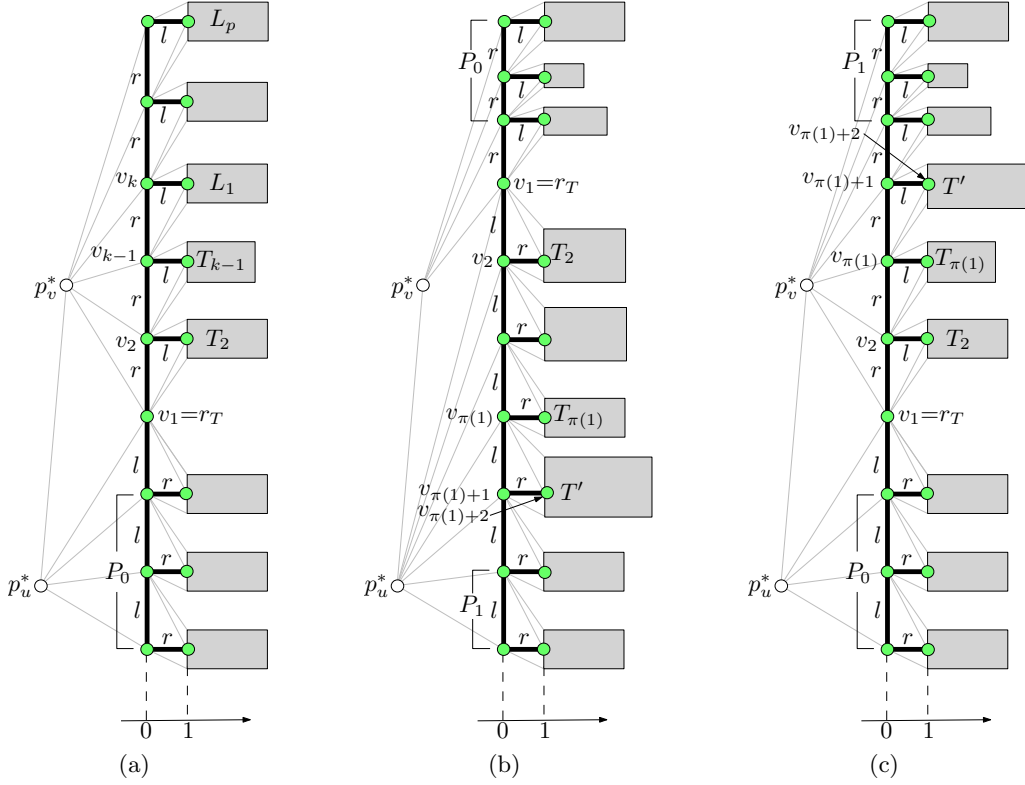


Fig. 13: Illustration for the strong flat algorithm when $s \leq 7$. (a) The case $s = 0$. (b) The case $1 \leq s \leq 7$ with s odd. (c) The case $1 \leq s \leq 7$ with s even.

on the line $x = 0$; then the drawing moves at most one grid column to the right at every switch of the spine. The resulting drawing of the spine P has a “zig-zag” shape, where each part of this zig-zag is a subpath of P drawn on a single grid column from top to bottom or vice versa. We now formally describe this construction; the description uses induction on s .

In the base case we have $\mathbf{s} = \mathbf{0}$; refer to Fig. 13(a). Since $s = 0$, it follows that P has no switches, hence v_{i+1} is the right child of v_i , for $i = 1, \dots, k-1$, given that v_k is the right child of v_{k-1} by hypothesis. Let P_0 be the leftmost path of the left subtree of T . Recursively construct a flat star-shaped drawing of the trees T_2, \dots, T_{k-1} , of the trees L_1, \dots, L_p , and of the subtrees of P_0 .

For $i = 2, \dots, k-1$, augment the recursively constructed drawing of T_i by placing the parent of r_{T_i} one unit to the left of r_{T_i} ; similarly augment the recursively constructed drawings of the trees L_1, \dots, L_p , and of the subtrees of P_0 . Further, construct a drawing (consisting of a single point) of every node that has not been drawn yet (these are the nodes of the leftmost path of T with no right child and the nodes of the rightmost path of T with no left child). We now place all these drawings together.

First, set the x -coordinate of every node in the leftmost and rightmost path of T to be 0. Since each tree that has been individually drawn contains a node in the leftmost or rightmost path of T (due to the above described augmentation of each recursively constructed drawing), this assignment determines the x -coordinate of every node of T .

Second, we assign a y -coordinate to every node of T . This is done so that every grid row contains a node or intersects a subtree. Rather than providing explicit y -coordinates, we establish a total order σ for a set that contains one node for each individually drawn tree; then a y -coordinate assignment is obtained by forcing, for any two nodes u_j and u_{j+1} that are consecutive in σ , the top side of the bounding box of the drawing comprising u_j to be one unit below the bottom side of the bounding box of the drawing comprising u_{j+1} . Order σ consists of the nodes of the leftmost path of T in *reverse order* (that is, from the unique leaf to r_T) followed by the nodes of the rightmost path of the right subtree of T in *straight order* (that is, from the root to the unique leaf). This completes the construction of a drawing Γ of T .

In the inductive case we have $1 \leq s \leq 7$. By hypothesis, we have that v_k is the right child of v_{k-1} ; hence, if s is odd then v_{i+1} is the left child of v_i , for $i = 1, \dots, \pi(1)$, otherwise v_{i+1} is the right child of v_i , for $i = 1, \dots, \pi(1)$. We formally describe the construction for the case in which s is odd, which is illustrated in Fig. 13(b). The construction for the other case is symmetric (see Fig. 13(c)).

Let P_0 be the rightmost path of the right subtree of T , let P_1 be the leftmost path of the left subtree of $v_{\pi(1)+1}$, and let T' be the subtree of T rooted at $v_{\pi(1)+2}$. Recursively construct a flat star-shaped drawing of trees $T_2, \dots, T_{\pi(1)}$, of the subtrees of P_0 , and of the subtrees of P_1 . Further, notice that the subpath of P contained in T' has either $s - 1$ or $s - 2$ switches (indeed, it has $s - 2$ switches if $v_{\pi(2)} = v_{\pi(1)+1}$ and it has $s - 1$ switches otherwise). Then the drawing of T' can be constructed inductively. We stress the fact that the spine is not recomputed for T' according to Lemma 10, but rather the construction of the drawing of T' is completed by using the subpath of P between $v_{\pi(1)+2}$ and v_k as the spine for T' .

For $i = 2, \dots, \pi(1)$, augment the recursively constructed drawing of T_i by placing the parent of r_{T_i} one unit to the left of r_{T_i} ; similarly augment the drawings of T' and of the subtrees of P_0 and P_1 . Further, construct a drawing (consisting of a single point) of every node that has not been drawn yet. We now place all these drawings together.

First, set the x -coordinate of every node in the leftmost and rightmost paths of T to be 0. This determines the x -coordinate of every node of T . Second, we establish a total order σ for a set that contains one node for each individually drawn tree; then a y -coordinate assignment is obtained by forcing, for any two nodes u_j and u_{j+1} that are consecutive in σ , the top side of the bounding box of the drawing comprising u_j to be one unit below the bottom side of the bounding box of the drawing comprising u_{j+1} . Order σ consists of the nodes of P_1 in reverse order, then of the nodes $v_{\pi(1)+1}, v_{\pi(1)}, v_{\pi(1)-1}, \dots, v_1$, and then of the nodes of P_0 in straight order. This completes the construction of a drawing Γ of T . We get the following.

Lemma 11. *Suppose that $s \leq 7$. Then the strong flat algorithm constructs a flat star-shaped drawing whose height is at most n and whose width is at most $8 + \max\{f(A), f(n - A)\}$.*

Proof. It is readily seen that Γ is star-shaped and flat. In particular, consider any node u in the leftmost or rightmost path of T . By construction, u is on the line $x = 0$. Further, all the nodes that are not adjacent to u and that are in the left-right path or in the right-left path of u lie on the line $x = 1$ (indeed, all such nodes are in the leftmost or rightmost paths of some subtrees of T for which flat star-shaped drawings have been recursively constructed and embedded with the left sides of their bounding boxes on the line $x = 1$); hence u sees all such nodes. That any node that is not in the leftmost or rightmost path of T sees all the non-adjacent nodes in its left-right path and in its right-left path comes from induction. Drawing Γ has height at most n since any horizontal grid line intersecting Γ passes through a node in the leftmost or rightmost path of T or intersects a recursively constructed drawing. Further, it can be proved by induction on s that the width of Γ is at most $s + 1 + \max\{f(A), f(n - A)\}$. Indeed, if $s = 0$ then all the subtrees that are drawn by a recursive application of the strong flat algorithm have either at most A nodes or at most $n - A$ nodes and have the left side of their bounding boxes on the line $x = 1$; this suffices to prove the statement, since no node has an x -coordinate that is smaller than 0. If $s > 0$, then the statement follows inductively, given that the spine of T' has at most $s - 1$ switches and no node of T' has an x -coordinate that is smaller than 1. \square

We now describe the strong bell-like algorithm for the case in which $s \leq 4$.

Strong bell-like algorithm with $s \leq 4$. In this case the leftmost or the rightmost path of T , depending on whether s is odd or even, respectively, is going to be drawn on a single grid column; in particular, this grid column is the leftmost or the rightmost grid column intersecting the drawing, depending on whether s is odd or even, respectively. Similarly to the strong flat algorithm, the spine P , together with the leftmost and rightmost paths of T and of certain subtrees of T , is going to be drawn on a set of $s + 1$ grid columns; also, P is going to have a “zig-zag” shape. We now formally describe this construction; the description uses induction on s .

In the base case we have $s = 0$; refer to Fig. 14(a). Then v_{i+1} is the right child of v_i , for $i = 1, \dots, k - 1$, given that v_k is the right child of v_{k-1} by hypothesis. Recursively construct a bell-like drawing T_1 of T_1 ; also, by means of the strong flat algorithm, construct a flat star-shaped drawing of the trees T_2, \dots, T_{k-1} and of the trees L_1, \dots, L_p . Rotate each of the constructed flat star-shaped drawings by 180° .

For $i = 2, \dots, k - 1$, augment the drawing of T_i by placing the parent of r_{T_i} one unit to the right of r_{T_i} ; similarly augment the drawings of the trees L_1, \dots, L_p . Augment T_1 by placing v_1 one unit above

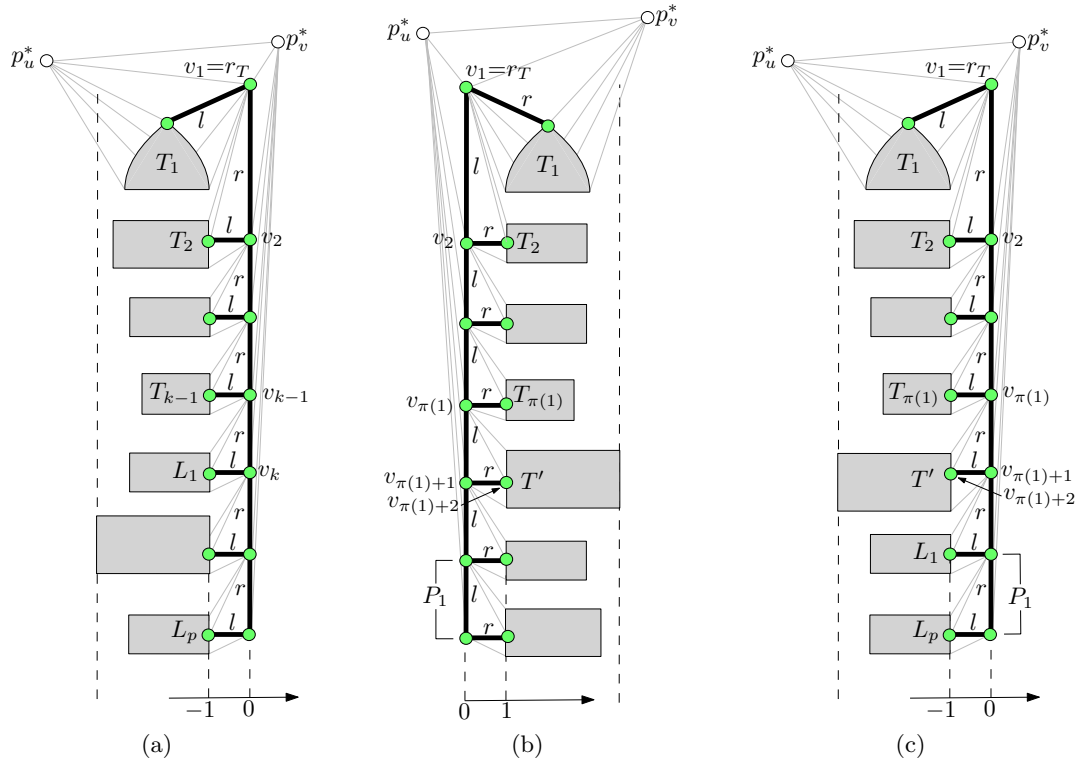


Fig. 14: Illustration for the strong bell-like algorithm when $s \leq 4$. (a) The case $s = 0$. (b) The case $1 \leq s \leq 4$ with s odd. (c) The case $1 \leq s \leq 4$ with s even.

$B_t(I_1)$ and one unit to the right of $B_r(I_1)$. Further, construct a drawing (consisting of a single point) of every node that has not been drawn yet (these are the nodes of the rightmost path of T with no left child). We now place all these drawings together.

First, set the x -coordinate of every node in the rightmost path of T to be 0. This determines the x -coordinate of every node of T . Second, we establish a total order σ for a set that contains one node for each individually drawn tree; then a y -coordinate assignment is obtained by forcing, for any two nodes u_j and u_{j+1} that are consecutive in σ , the top side of the bounding box of the drawing comprising u_j to be one unit below the bottom side of the bounding box of the drawing comprising u_{j+1} . Order σ consists of the nodes of the rightmost path of T in reverse order. This completes the construction of a drawing Γ of T .

In the inductive case we have $1 \leq s \leq 4$. By hypothesis, we have that v_k is the right child of v_{k-1} ; hence, if s is odd (even) then v_{i+1} is the left (resp. right) child of v_i , for $i = 1, \dots, \pi(1)$. We first describe the construction for the case in which s is odd, which is illustrated in Fig. 14(b).

Let P_1 be the leftmost path of the left subtree of $v_{\pi(1)+1}$ and let T' be the subtree of T rooted at $v_{\pi(1)+2}$. Recursively construct a bell-like drawing Γ_1 of T_1 ; also, by means of the strong flat algorithm, construct a flat star-shaped drawing of the trees $T_2, \dots, T_{\pi(1)}$ and of the subtrees of P_1 . Further, notice that the part of P contained in T' has either $s - 1$ or $s - 2$ switches (indeed, it has $s - 2$ switches if $v_{\pi(2)} = v_{\pi(1)+1}$ and it has $s - 1$ switches otherwise). Then a flat star-shaped drawing of T' is constructed by means of the strong flat algorithm; we stress the fact that the spine is not recomputed for T' according to Lemma 10, but rather the construction of the drawing of T' is completed by using the subpath of P between $v_{\pi(1)+2}$ and v_k as the spine for T' .

For $i = 2, \dots, \pi(1)$, augment the drawing of T_i by placing the parent of r_{T_i} one unit to the left of r_{T_i} ; similarly augment the drawings of T' and of the subtrees of P_1 . Augment Γ_1 by placing v_1 one unit above $B_t(I_1)$ and one unit to the left of $B_l(I_1)$. Further, construct a drawing (consisting of a single point) of every node that has not been drawn yet (these are the nodes of the leftmost path of T with no right child). These drawings are placed together as in the case in which $s = 0$. In particular, set the

x -coordinate of every node in the leftmost path of T to be 0, thus determining the x -coordinate of every node of T . Further, the y -coordinate assignment is such that the top side of the bounding box of the drawing comprising a node of the leftmost path of T is one unit below the bottom side of the bounding box of the drawing comprising the parent of that node. This completes the construction of a drawing Γ of T .

The case in which s is even, which is illustrated in Fig. 14(c), is symmetric to the previous one and very similar to the case $s = 0$. In particular, the rightmost path of T is drawn on the rightmost grid column intersecting the drawing. Further, each recursively constructed flat star-shaped drawing of a subtree of the rightmost path of T has to be rotated by 180° and placed so that its root is one unit to the left of its parent. We get the following.

Lemma 12. *Suppose that $s \leq 4$. Then the strong bell-like algorithm constructs a bell-like star-shaped drawing whose height is at most n and whose width is at most $5 + \max\{f(A), f(n - A)\}$.*

Proof. Assume that s is odd; the case in which s is even is symmetric.

It is readily seen that Γ is star-shaped. In particular, it can be proved similarly to the proof of Lemma 11 that every node different from r_T sees all the nodes in its left-right path and in its right-left path that are not adjacent to it, and that r_T sees all the nodes in its left-right path that are not adjacent to it. Further, r_T sees all the nodes in its right-left path that are not adjacent to it, since all such nodes are in the leftmost path of T_1 , since the drawing Γ_1 of T_1 is bell-like, and since r_T is one unit above $B_t(\Gamma_1)$ and one unit to the left of $B_l(\Gamma_1)$.

Drawing Γ is also bell-like. Indeed: (i) r_T lies on $B_t(\Gamma)$ by construction; (ii) the nodes of the leftmost path of T lie on the line $x = 0$ in decreasing order of y -coordinates from r_T to the unique leaf, and no other node of T has an x -coordinate smaller than 1; (iii) the drawing Γ_1 of T_1 is bell-like, r_T is one unit above and at least one unit to the left of r_{T_1} , and every node of T different from r_T and not in T_1 is below $B_b(\Gamma_1)$. These statements imply that any point p_u^* above $B_t(\Gamma)$ and to the left of $B_l(\Gamma)$ and any point p_v^* above $B_t(\Gamma)$ and to the right of $B_r(\Gamma)$ satisfy Property 4 of a star-shaped drawing.

Drawing Γ has height at most n since any horizontal grid line intersecting Γ passes through a node on the leftmost path of T or intersects a recursively constructed drawing. Concerning the width of Γ , note that the only subtree T_1 that is drawn by a recursive application of the strong bell-like algorithm has at most A nodes (or at most $n - A$ nodes if k were equal to 1) and has the left side of its bounding box on the line $x = 1$, while no node of T has an x -coordinate that is smaller than 0. The argument for the subtrees that are recursively drawn by means of the strong flat algorithm is analogous to the one in the proof of Lemma 11. \square

In general, it might hold that $s = \Omega(A)$; hence, if the strong flat algorithm and the strong bell-like algorithm used the constructions described above for every value of s , then recurring over the trees L_1, \dots, L_p one would get a drawing with $\Omega(n)$ width. For this reason, the strong flat algorithm and the strong bell-like algorithm exploit different geometric constructions when $s \geq 8$ and when $s \geq 5$, respectively. We now describe the strong bell-like algorithm in the case in which $s \geq 5$.

Strong bell-like algorithm with $s \geq 5$. The general idea of the upcoming construction is the following. We would like to construct a bell-like star-shaped drawing Γ whose width is given by either (i) a constant plus the width of a recursively constructed drawing of a tree with at most $n - A$ nodes, or (ii) a constant plus the widths of the recursively constructed drawings of two trees, each with at most A nodes. Part of the construction we are going to show is very similar to the construction of the (non-strong) bell-like algorithm from Section 3.2: Starting from r_T , we draw the spine P of T on two adjacent grid columns, with the left subtrees of P to the left of P and with the right subtrees of P to the right of P (note that the width of this part of Γ is a constant plus the widths of the recursively constructed drawings of two trees, each with at most A nodes). Before reaching v_k , however, the construction changes significantly. In particular, the drawing of P touches $B_r(\Gamma)$ and then continues on the grid column one unit to the left of $B_r(\Gamma)$. The remainder of P , including v_k and together with the rightmost path P_R of the subtree of T rooted at v_k , is drawn entirely on that grid column, with its subtrees to the left of it (note that the width of this part of Γ is a constant plus the width of a recursively constructed drawing of a tree with at most $n - A$ nodes).

In order to guarantee that Γ is a bell-like star-shaped drawing, it is vital that the drawings of T_1 and $T_{\pi(1)+1}$ are bell-like. This requirement can be easily met if the parents v_1 and $v_{\pi(1)+1}$ of the roots of these subtrees occur in the first part of P , which is drawn on two adjacent grid columns. On the other

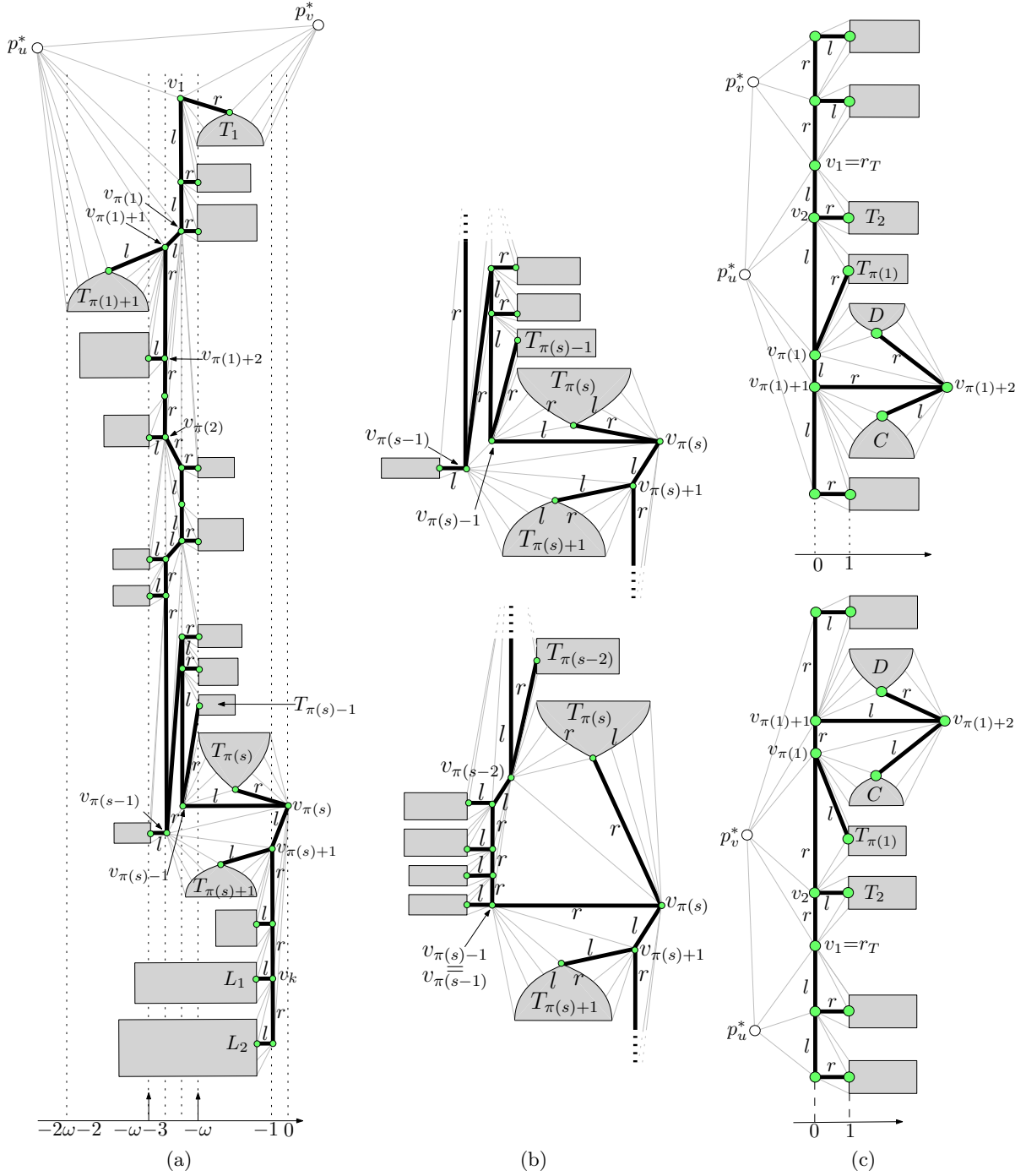


Fig. 15: (a) Illustration for the strong bell-like algorithm when $s \geq 5$. (b) A closer look at the cases in which $\pi(s - 1) < \pi(s) - 1$ (top) or $\pi(s - 1) = \pi(s) - 1$ (bottom). (c) Illustration for the strong flat algorithm when $s \geq 8$, in the case in which v_2 is the left child of v_1 (top) or the right child of v_1 (bottom).

hand, if v_1 and $v_{\pi(1)+1}$ occurred in the second part of P , then the requirement on T_1 and $T_{\pi(1)+1}$ would conflict with the geometric constraints our construction needs to satisfy in order to place the final part of P , together with P_R , on the grid column one unit to the left of $B_r(I)$. This is the reason why we need the spine to have some number of switches (in fact at least 5 switches).

We now detail our construction. Refer to Fig. 15(a). First, we draw some subtrees recursively. We use the strong bell-like algorithm to construct a bell-like star-shaped drawing of T_1 , of $T_{\pi(1)+1}$, of $T_{\pi(s)}$, and of $T_{\pi(s)+1}$. Further, we use the strong flat algorithm to construct a flat star-shaped drawing of every subtree T_j of P such that $2 \leq j \leq k-1$ with $j \notin \{\pi(1)+1, \pi(s), \pi(s)+1\}$. Let ω denote the maximum width among the constructed drawings of the trees T_j , with $1 \leq j \leq k-1$; notice that any such a subtree has at most A nodes. Finally, we use the strong flat algorithm to construct flat star-shaped drawings of the trees L_1, \dots, L_p , which have at most $n-A$ nodes.

We now describe an x -coordinate assignment for the nodes of T ; for the part of P up to $v_{\pi(s)-1}$ (that is, up to one node before the last switch of P), this assignment is done similarly to the (non-strong) bell-like algorithm from Section 3.2 (for technical reasons, however, the nodes of T are here assigned non-positive x -coordinates). For $i = 1, \dots, \pi(s)-1$, node v_i is placed on the line $x = -\omega - 2$ or $x = -\omega - 1$, depending on whether v_{i+1} is the right or the left child of v_i , respectively. Further, for $i = 1, \dots, \pi(s)-1$, the recursively constructed drawing of T_i is assigned x -coordinates such that the left side of its bounding box is on the line $x = -\omega$ if T_i is the right subtree of v_i , or it is first rotated by 180° and then assigned x -coordinates so that the right side of its bounding box is on the line $x = -\omega - 3$ if T_i is the left subtree of v_i . Note that the part of T to which x -coordinates have been assigned so far lies in the closed vertical strip $-2\omega - 2 \leq x \leq -1$, given that the width of the drawing of T_i is at most ω , for $i = 1, \dots, \pi(s)-1$. Set $x(v_{\pi(s)}) = 0$; also set the x -coordinate of every node v_i , with $i = \pi(s)+1, \dots, k-1$, and of every node in P_R to be -1 . Rotate the drawing of $T_{\pi(s)}$ by 180° and assign x -coordinates to it so that the left side of its bounding box is on the line $x = -\omega$. Finally, assign x -coordinates to the drawings of $T_{\pi(s)+1}, \dots, T_{k-1}, L_1, \dots, L_p$ so that the right sides of their bounding boxes are on the line $x = -2$.

We now describe a y -coordinate assignment for the nodes of T . Part of this assignment varies depending on whether $\pi(s-1) < \pi(s)-1$ (see Figs. 15(a) and 15(b) top) or $\pi(s-1) = \pi(s)-1$ (see Fig. 15(b) bottom). First, we define the y -coordinates of certain nodes with respect to the ones of their subtrees. We let node v_1 (node $v_{\pi(1)+1}$, node $v_{\pi(s)+1}$) have y -coordinate equal to 1 plus the y -coordinate of the root of T_1 (resp. of $T_{\pi(1)+1}$, resp. of $T_{\pi(s)+1}$). Further, for $j = 1, \dots, p$, we let the root of L_j have the same y -coordinate as its parent. Also:

- If $\pi(s-1) < \pi(s)-1$, then we let the root of T_j have the same y -coordinate as its parent for $j = 2, \dots, k-1$ with $j \notin \{\pi(1)+1, \pi(s)-1, \pi(s), \pi(s)+1\}$.
- If $\pi(s-1) = \pi(s)-1$, then we let the root of T_j have the same y -coordinate as its parent for $j = 2, \dots, k-1$ with $j \notin \{\pi(1)+1, \pi(s-2), \pi(s), \pi(s)+1\}$.

We construct a drawing (consisting of a single point) of every node that has not yet been drawn, including $v_{\pi(s)}$, including $v_{\pi(s)-1}$ (if $\pi(s-1) < \pi(s)-1$), and including $v_{\pi(s-2)}$ (if $\pi(s-1) = \pi(s)-1$). Note that the y -coordinates of $T_{\pi(s)}$ have not been defined relatively to the one of $v_{\pi(s)}$; analogously, if $\pi(s-1) < \pi(s)-1$ (if $\pi(s-1) = \pi(s)-1$), then the y -coordinates of $T_{\pi(s)-1}$ (resp. of $T_{\pi(s-2)}$) have not been defined relatively to the one of $v_{\pi(s)-1}$ (resp. of $v_{\pi(s-2)}$).

We now place all these drawings together. Namely, we define a total order σ of the nodes and subtrees of T that have been individually drawn; then we can recover a y -coordinate assignment from σ by interpreting it as a *top-to-bottom* order of the subtrees (note that, in the previously described constructions, the order σ represented a *bottom-to-top* order of the subtrees), so that the bottom side of the bounding box of a subtree is one unit above the top side of the bounding box of the next subtree in σ . The order σ starts with the nodes $v_1, v_2, \dots, v_{\pi(s-2)-1}$.

- If $\pi(s-1) < \pi(s)-1$, then the order σ continues with $v_{\pi(s-2)}, \dots, v_{\pi(s-1)-1}$, with $v_{\pi(s-1)+1}, \dots, v_{\pi(s)-2}$, with $T_{\pi(s)-1}$, with $T_{\pi(s)}$, with $v_{\pi(s)-1}$ and $v_{\pi(s)}$ (which have the same y -coordinate), and with $v_{\pi(s-1)}$.
- If $\pi(s-1) = \pi(s)-1$, then the order σ continues with $T_{\pi(s-2)}$, with $T_{\pi(s)}$, with $v_{\pi(s-2)}, \dots, v_{\pi(s-1)-1}$, and with $v_{\pi(s-1)}$ and $v_{\pi(s)}$ (which have the same y -coordinate).

The order σ terminates with the nodes $v_{\pi(s)+1}, \dots, v_{k-1}$ and with the nodes of P_R in straight order. This concludes the construction of the drawing Γ . We have the following.

Lemma 13. *Suppose that $s \geq 5$. Then the strong bell-like algorithm constructs a bell-like star-shaped drawing whose height is at most n and whose width is at most $3 + \max\{2f(A), f(n-A)\}$.*

Proof. It is readily seen that Γ is star-shaped and bell-like. Most interestingly:

- If $\pi(s-1) < \pi(s) - 1$, then $v_{\pi(s-1)}$ sees all the nodes of its right-left path that are not adjacent to it. Indeed, the subpath $(v_{\pi(s-1)+1}, \dots, v_{\pi(s)-1})$ of the right-left path of $v_{\pi(s-1)}$ is represented by a straight-line segment on the vertical line $x = -\omega - 1$, which is one unit to the right of $v_{\pi(s-1)}$, so that $v_{\pi(s)-1}$ is the point of this segment with the smallest y -coordinate and is above $v_{\pi(s-1)}$; hence, this segment does not block the visibility between $v_{\pi(s-1)}$ and $v_{\pi(s)}$, which has the same y -coordinate as $v_{\pi(s)-1}$ and is to the right of it, and between $v_{\pi(s-1)}$ and $v_{\pi(s)+1}$, which is below $v_{\pi(s-1)}$. Finally, $v_{\pi(s-1)}$ sees all the nodes of the leftmost path of $T_{\pi(s)+1}$, given that the drawing of $T_{\pi(s)+1}$ is bell-like and that $v_{\pi(s-1)}$ lies to the left and above the left side and the top side of the bounding box of the drawing of $T_{\pi(s)+1}$, respectively (note that $x(v_{\pi(s-1)}) = -\omega - 2$, while $T_{\pi(s)+1}$ has x -coordinates in the range $-\omega - 1 \leq x \leq -2$).
- If $\pi(s-1) = \pi(s) - 1$, then $v_{\pi(s-2)}$ sees all the nodes of its left-right path that are not adjacent to it. Indeed, the subpath $(v_{\pi(s-2)+1}, \dots, v_{\pi(s)-1})$ of the left-right path of $v_{\pi(s-2)}$ is represented by a straight-line segment on the vertical line $x = -\omega - 2$, which is one unit to the left of $v_{\pi(s-2)}$; hence, this segment does not block the visibility between $v_{\pi(s-2)}$ and $v_{\pi(s)}$, which is to the right of $v_{\pi(s-2)}$ and below it. Finally, $v_{\pi(s-2)}$ sees all the nodes of the rightmost path of $T_{\pi(s)}$, given that the drawing of $T_{\pi(s)}$ is bell-like and is rotated by 180° , and that $v_{\pi(s-2)}$ lies to the left and below the left side and the bottom side of the bounding box of the drawing of $T_{\pi(s)}$, respectively.

We remark that, if $\pi(s-1) = \pi(s) - 1$, then the algorithm constructs a flat star-shaped drawing of $T_{\pi(s-2)}$ and places this drawing so that the bottom side of its bounding box is above $v_{\pi(s-2)}$, in order to “make space” for the drawing of $T_{\pi(s)}$. On the other hand, in order to ensure the bell-like property for Γ , the construction employs a bell-like drawing of $T_{\pi(1)+1}$. Hence, we need $\pi(1) + 1$ to be smaller than $\pi(s-2)$. However, we have $\pi(1) + 1 \leq \pi(2)$ and $\pi(2) < \pi(3)$, hence $\pi(1) + 1 < \pi(s-2)$ holds true if $s \geq 5$, which is the case by hypothesis.

The height of Γ is at most n , since every grid row intersecting Γ contains a node of P or intersects a subtree of P . Concerning the width, note that Γ intersects no grid line $x = i$ with $i > 0$. Consider the smallest i such that the line ℓ with equation $x = i$ intersects $B(\Gamma)$.

- Suppose that ℓ intersects a tree among $T_1, \dots, T_{\pi(s)}$. Each of these trees lies either between the lines $x = -\omega$ and $x = -1$, or between the lines $x = -2\omega - 2$ and $x = -\omega - 3$; hence $i \geq -2\omega - 2$ and the width of Γ is at most $3 + 2\omega \leq 3 + 2f(A)$, where $\omega \leq f(A)$ holds true since every tree among $T_1, \dots, T_{\pi(s)}$ has at most A nodes and by the definition of the function $f(n)$.
- Next, suppose that ℓ intersects a tree among $T_{\pi(s)+1}, \dots, T_{k-1}$. The drawing of each of these trees has the right side of its bounding box on the line $x = -2$; also, each of these trees has at most A nodes, hence it has width at most $f(A)$. It follows that the width of Γ is at most $2 + f(A)$.
- Finally, suppose that ℓ intersects a tree among L_1, \dots, L_p . The drawing of each of these trees has the right side of its bounding box on the line $x = -2$; also, each of these trees has at most $n - A$ nodes, hence it has width at most $f(n - A)$. It follows that the width of Γ is at most $2 + f(n - A)$.

This concludes the proof of the lemma. \square

It remains to describe the strong flat algorithm for the case in which $s \geq 8$.

Strong flat algorithm with $s \geq 8$. The geometric construction for this case is *the same* as the one for the inductive case of the (non-strong) flat algorithm from Section 3.2, however the drawing algorithms which are recursively invoked by the two constructions differ; refer to Fig. 15(c).

First, every subtree of the leftmost and rightmost paths of T different from $T_{\pi(1)+1}$ is recursively drawn by means of the strong flat algorithm. Denote by C and D the left and right subtrees of $v_{\pi(1)+2}$. Bell-like star-shaped drawings of C and D are recursively constructed by means of the strong bell-like algorithm, however there is one difference in the recursive construction of these drawings. Note that the spine P of T “enters” exactly one between C and D (recall that P contains the nodes $v_{\pi(1)}, v_{\pi(1)+1}, v_{\pi(1)+2}, v_{\pi(1)+3}$, hence $v_{\pi(1)+3}$ is the root of C or D); let X be the one between C and D whose root is $v_{\pi(1)+3}$ and Y be the one between C and D whose root is different from $v_{\pi(1)+3}$. Then the strong bell-like algorithm is applied recursively for Y , while X is drawn by means of the construction of the strong bell-like algorithm with $s \geq 5$, by using the subpath of P between $v_{\pi(1)+3}$ and v_k as the spine for it (that is, the spine is not recomputed for X according to Lemma 10, but the path $(v_{\pi(1)+3}, v_{\pi(1)+4}, \dots, v_k)$ is used as spine instead). Notice that, since $\pi(1) < \pi(2) < \pi(3) < \pi(4)$, we have that $\pi(1) + 3 \leq \pi(4)$, hence the spine $(v_{\pi(1)+3}, v_{\pi(1)+4}, \dots, v_k)$ contains at least 5 switches.

The remainder of the construction is the same as for the inductive case of the (non-strong) flat algorithm from Section 3.2. Indeed, the nodes of the leftmost and rightmost paths of T are assigned x -coordinate equal to 0; further, all the recursively drawn subtrees are embedded in the plane so that the left sides of their bounding boxes lie on the line $x = 1$ (the drawing of D is rotated by 180° before embedding it). Node $v_{\pi(1)+2}$ is assigned x -coordinate equal to 1 plus the maximum x -coordinate assigned to any other node in the drawing. Every node different from v_1 and $v_{\pi(1)}$ is assigned the same y -coordinate as its right or left child, depending on whether it belongs to the leftmost or rightmost path of T , respectively. Distinct subtrees are arranged vertically so that, from bottom to top, the nodes of the leftmost path of T appear first – in reverse order – and then the nodes of the rightmost path of T appear next – in straight order. Depending on whether v_2 is the left child (see Fig. 15(c) top) or the right child (see Fig. 15(c) bottom) of v_1 , we respectively have that:

- The bottom side of the bounding box of $T_{\pi(1)}$ is one unit above the top side of the bounding box of D ; the bottom side of the bounding box of D is one unit above $v_{\pi(1)}$; $v_{\pi(1)}$ is one unit above $v_{\pi(1)+1}$ and $v_{\pi(1)+2}$, which have the same y -coordinate; $v_{\pi(1)+1}$ and $v_{\pi(1)+2}$ are one unit above the top side of the bounding box of C ; and the bottom side of the bounding box of C is one unit above the top side of the bounding box of the left child of $v_{\pi(1)+1}$ and of its right subtree.
- The top side of the bounding box of $T_{\pi(1)}$ is one unit below the bottom side of the bounding box of C ; the top side of the bounding box of C is one unit below $v_{\pi(1)}$; $v_{\pi(1)}$ is one unit below $v_{\pi(1)+1}$ and $v_{\pi(1)+2}$, which have the same y -coordinate; $v_{\pi(1)+1}$ and $v_{\pi(1)+2}$ are one unit below the bottom side of the bounding box of D ; and the top side of the bounding box of D is one unit below the bottom side of the bounding box of the right child of $v_{\pi(1)+1}$ and of its left subtree.

We have the following.

Lemma 14. *Suppose that $s \geq 8$. Then the strong flat algorithm constructs a bell-like star-shaped drawing whose height is at most n and whose width is at most $5 + \max\{2f(A), f(n - A)\}$.*

Proof. It is readily seen that Γ is star-shaped and flat, and that its height is at most n . The width of the drawing is given by 2, corresponding to the grid column $x = 0$ and to the grid column containing $v_{\pi(1)+2}$, plus the width of a recursively drawn subtree. The latter is the maximum between $f(A)$ (this is the maximum width of any tree different from X that is recursively drawn) and $3 + \max\{2f(A), f(n - A)\}$, which is the maximum width of the constructed drawing of X , as given by Lemma 13. This concludes the proof of the lemma. \square

We are now ready to state the main theorem of this section.

Theorem 3. *Every n -vertex outerplanar graph admits an outerplanar straight-line drawing with area $O\left(n \cdot 2^{\sqrt{2 \log_2 n}} \sqrt{\log n}\right)$.*

Proof. Let G be an n -vertex outerplanar graph and let T be its dual tree. We apply the strong flat algorithm to T (with a parameter A that will be specified shortly), thus obtaining a drawing Γ . Lemmata 11–14 ensure that Γ is a flat star-shaped drawing with height $O(n)$. Points p_u^* and p_v^* satisfying Property 4 of a star-shaped drawing can be chosen in Γ (in fact in any flat star-shaped drawing) so that the width and the height only increase by a constant number of units. Due to this consideration and to Lemma 8, in order to conclude the proof of the theorem it only remains to argue that the width of Γ is in $O\left(2^{\sqrt{2 \log_2 n}} \sqrt{\log n}\right)$. This proof follows almost verbatim a proof by Chan [2]. Recall that we denote by $f(n)$ the maximum width of a drawing of an n -node ordered rooted binary tree constructed by means of the strong flat or bell-like algorithm.

By Lemmata 11–14 we have that $f(n) \leq \max\{8 + 2f(A), 8 + f(n - A)\}$. Iterating over the second term with the same value of A we get $f(n) \leq \max\{8 + 2f(A), 8 + f(n - A)\} \leq \max\{8 + 2f(A), 16 + f(n - 2A)\} \leq \max\{8 + 2f(A), 24 + f(n - 3A)\} \leq \dots \leq \max\{8 + 2f(A), 8(\frac{n}{A} - 1) + f(A)\} \leq 2f(A) + 8\frac{n}{A} + 8$.

We now set $A = \frac{n}{2^{\sqrt{2 \log_2 n}}}$, which gives us the recurrence

$$f(n) \leq 2f\left(\frac{n}{2^{\sqrt{2 \log_2 n}}}\right) + 8 \cdot 2^{\sqrt{2 \log_2 n}} + 8.$$

We remark that the iteration with the same value of A mentioned in the computation of the recursive formula corresponds to using $A = \frac{n}{2\sqrt{2\log_2 n}}$ whenever we need to recursively draw a tree that has more than $\frac{n}{2\sqrt{2\log_2 n}}$ nodes. Once the tree size drops to $\frac{n}{2\sqrt{2\log_2 n}}$ or less, the drawing algorithms are applied recursively by recomputing the parameter A based on the actual number of nodes in the tree that has to be drawn.

It remains to solve the recurrence equation, which is done again as by Chan [2]. Namely, set $m = 2\sqrt{2\log_2 n}$, which is equivalent to $n = 2^{\frac{(\log_2 m)^2}{2}}$, and set $g(m) = f(n)$. Then

$$\begin{aligned} g(m) &\leq 2f\left(\frac{2^{\frac{(\log_2 m)^2}{2}}}{m}\right) + 8m + 8 = 2f\left(2^{\left(\frac{(\log_2 m)^2}{2} - \log_2 m\right)}\right) + 8m + 8 \\ &\leq 2f\left(2^{\left(\frac{(\log_2 m - 1)^2}{2}\right)}\right) + 8m + 8 = 2g\left(\frac{m}{2}\right) + 8m + 8. \end{aligned}$$

The inequality $g(m) \leq 2g\left(\frac{m}{2}\right) + 8m + 8$ trivially implies that $g(m) \in O(m \log m)$, and hence that $f(n) \in O(2\sqrt{2\log_2 n} \sqrt{\log n})$, which concludes the proof of the theorem. \square

We conclude the section by remarking that the function $2\sqrt{2\log_2 n} \sqrt{\log n}$ is asymptotically smaller than any polynomial function of n ; that is, for any constant $\varepsilon > 0$, it holds true that $2\sqrt{2\log_2 n} \sqrt{\log n} < n^\varepsilon$ for sufficiently large n .

4 Conclusions

In the first part of the paper we studied LR-drawings of ordered rooted binary trees. We proved that an LR-drawing with optimal width for an n -node ordered rooted binary tree can be constructed in $O(n^{1.48})$ time. It would be interesting to improve the running time to an almost-linear bound; this might however require new insights on the structure of LR-drawings. We also proved that there exist n -node ordered rooted binary trees requiring $\Omega(n^{0.418})$ width in any LR-drawing; this bound is close to the upper bound of $O(n^{0.48})$ due to Chan [2]. It seems unlikely that Chan's bound is tight (he writes "The exponent $p = 0.48$ is certainly not the best possible") and the experimental evaluation we conducted seems to confirm that; thus the quest for LR-drawings with $o(n^{0.48})$ width is a compelling research direction.

In the second part of the paper we established a strong connection between LR-drawings of ordered rooted binary trees and outerplanar straight-line drawings of outerplanar graphs. Namely we proved that, if an ordered rooted binary tree T has an LR-drawing with a certain width and area, then the outerplanar graph G whose dual tree is T has an outerplanar straight-line drawing with asymptotically the same width and area. We also proved that n -vertex outerplanar graphs admit outerplanar straight-line drawings in almost-linear area; our area upper bound is $O\left(n \cdot 2\sqrt{2\log_2 n} \sqrt{\log n}\right)$. We believe that an $O(n \log n)$ area bound cannot be achieved by only squeezing the drawing in one coordinate direction while keeping the size of the drawing linear in the other direction; hence, we find very interesting to understand whether every outerplanar graph admits an outerplanar straight-line drawing whose width and height are both sub-linear. We remark that a similar question has a negative answer for general *planar graphs* [20] and even for *series-parallel graphs*, that are graphs that exclude K_4 as a minor (and form hence a super-class of outerplanar graphs): There exist n -vertex series-parallel graphs that require $\Omega(n)$ size in one coordinate direction in any straight-line planar drawing [8].

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