

Packing Lines, Planes, etc.:

Packings in Grassmannian Spaces

John H. Conway, Ronald H. Hardin and Neil J. A. Sloane

CONTENTS

- 1. Introduction
 - 2. Grassmannian Space
 - 3. Packing Lines Through the Origin in Three Dimensions
 - 4. Packing Planes in Four Dimensions
 - 5. Packing n -Planes in Higher Dimensions
 - 6. Packing Lines in Higher Dimensions
- Acknowledgements
Electronic Availability
References

We address the question: How should N n -dimensional subspaces of m -dimensional Euclidean space be arranged so that they are as far apart as possible? The results of extensive computations for modest values of N, n, m are described, as well as a reformulation of the problem that was suggested by these computations. The reformulation gives a way to describe n -dimensional subspaces of m -space as points on a sphere in dimension $\frac{1}{2}(m-1)(m+2)$, which provides a (usually) lower-dimensional representation than the Plücker embedding, and leads to a proof that many of the new packings are optimal. The results have applications to the graphical display of multi-dimensional data via Asimov's grand tour method.

1. INTRODUCTION

Although there is a considerable literature dealing with Grassmannian spaces, exemplified by [Chow 1949; Leichtweiss 1961; Wong 1967; James and Constantine 1974; Griffiths and Harris 1978, Section 1.5; MacKenzie and Morgan 1995; Zanella 1995], the problem of finding the best packings in such spaces seems to have received little attention.

We have made extensive computations on this problem, and have found a number of putatively optimal packings. These computations have led us to conclude that the best definition of distance on Grassmannian space is the "chordal distance" defined in Section 2.

Sections 3, 4, 5, 6 discuss the problems of packing lines in \mathbb{R}^3 , planes in \mathbb{R}^4 , n -spaces in \mathbb{R}^m , and lines in \mathbb{R}^m , respectively. Our search has concentrated on packings of $N \leq 55$ subspaces of $G(m, n)$, for $m \leq 16$ and $n \leq 3$. The results are available electronically: see before the bibliography.

2. GRASSMANNIAN SPACE

Grassmannian space $G(m, n)$ is the set of all n -dimensional subspaces of real Euclidean m -dimensional space \mathbb{R}^m . It is a homogeneous space isomorphic to $O(m)/(O(n) \times O(m-n))$, and forms a compact Riemannian manifold of dimension $n(m-n)$.

We start by discussing how to define the distance between two elements of $G(m, n)$. Following [Golub and Van Loan 1989, p. 584], for example, we associate with two n -planes P and Q *principal angles* $\theta_i \in [0, \pi/2]$ and *principal vectors* $u_i \in P$ and $v_i \in Q$, for $i = 1, \dots, n$, as follows. Choose $u_1 \in P$ and $v_1 \in Q$ having length 1 and such that $u_1 \cdot v_1$ is maximal. Inductively, define $u_i \in P$ and $v_i \in Q$ having length 1 and such that $u_i \cdot v_i$ is maximal, subject to the conditions $u_i \cdot u_j = 0$ and $v_i \cdot v_j = 0$ for all $1 \leq j < i$. Then set $\theta_i = \arccos u_i \cdot v_i$.

Wong [1967] shows that the *geodesic distance* on $G(m, n)$ between P and Q is

$$d_g(P, Q) = \sqrt{\theta_1^2 + \dots + \theta_n^2}.$$

This distance function has the drawback of not being everywhere differentiable. Consider the case $n = 1$, for example, and hold one line P fixed while rotating another line Q (both passing through the origin). As the angle φ between P and Q increases from 0 to π , the principal angle θ_1 increases from 0 to $\pi/2$ and then falls to 0, and is nondifferentiable at $\pi/2$, as illustrated in Figure 1.

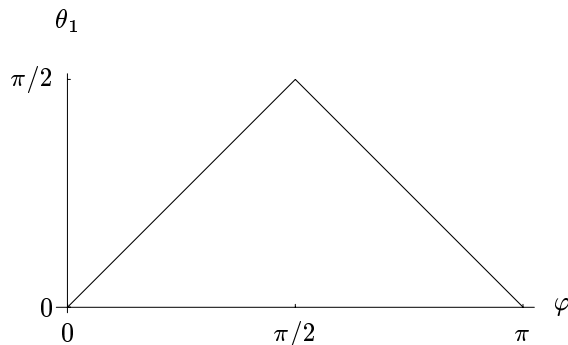


FIGURE 1. Principal angle θ_1 between two lines as the angle between them increases from 0 to π .

Although one might expect this nondifferentiability to be a mere technicality, it causes many difficulties in practice. Our optimizer software does not handle it well, especially in higher dimensions in cases when many distances fall in the neighborhood of singular points of d_g .

An alternative measure of distance, which we call the *chordal distance* for reasons to be made clear later, is given by

$$d_c(P, Q) = \sqrt{\sin^2 \theta_1 + \dots + \sin^2 \theta_n}.$$

This approximates the geodesic distance when the planes are close, has the property that its square is differentiable everywhere, and, as we shall attempt to demonstrate, has a number of other desirable features.

A third definition has been used [Asimov 1985; Golub and Van Loan 1989, p. 584], namely

$$d_m(P, Q) = \theta_n = \max_{i=1, \dots, n} \theta_i.$$

It shares the vices of the geodesic distance.

Of course, for $n = 1$ all three definitions are equivalent, in the sense that they lead to the same optimal packings.

We can now state the packing problem: given N, n, m , find a set of n -planes $P_1, \dots, P_N \in G(m, n)$ such that $\min_{i \neq j} d(P_i, P_j)$ is as large as possible, where d is either geodesic or chordal distance. That there is such a set follows from the compactness of $G(m, n)$. Since $G(m, n)$ and $G(m, m-n)$ can be identified by the correspondence induced by orthogonal complementation, we will usually assume that $n \leq m/2$.

A *generator matrix* for an n -plane $P \in G(m, n)$ is an $n \times m$ matrix whose rows span P . The orthogonal group $O(m)$ acts on $G(m, n)$ by right multiplication of generator matrices. The *automorphism group* of a subset $\{P_1, \dots, P_N\} \subset G(m, n)$ is the subset of $O(m)$ which fixes or permutes these planes.

Applying a suitable element of $O(m)$ and choosing appropriate basis vectors for the planes, we can

reduce the generator matrices of any given pair of n -planes P, Q with $n \leq m/2$ to the forms

$$\begin{bmatrix} 1 & 0 & \cdots & 0 & 0 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 & 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 1 & 0 & 0 & \cdots & 0 \end{bmatrix} \quad (2.1)$$

and

$$\begin{bmatrix} \cos \theta_1 & 0 & \cdots & 0 & \sin \theta_1 & 0 & \cdots & 0 & 0 & \cdots & 0 \\ 0 & \cos \theta_2 & \cdots & 0 & 0 & \sin \theta_2 & \cdots & 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \cos \theta_n & 0 & 0 & \cdots & \sin \theta_n & 0 & \cdots & 0 \end{bmatrix} \quad (2.2)$$

respectively, where $\theta_1, \dots, \theta_n$ are the principal angles between P and Q [Wong 1967, Theorem 2].

3. PACKING LINES THROUGH THE ORIGIN IN THREE DIMENSIONS

Our initial work on this problem was prompted by a question raised by Julian Rosenman [1992], an oncologist at the University of North Carolina School of Medicine and Computer Science, in connection with the treatment of tumors using high energy laser beams. Rosenman asked for the best way to separate N lines through a given point in \mathbb{R}^3 , or in other words for the best packings in $G(3, 1)$.

Together with W. D. Smith, we had been carrying out an extensive search for the best packings of a given number of points on S^2 , that is, *spherical codes* [Hardin et al. 1993–95; a], and we therefore modified our programs to search instead for packings of lines; packing N points in $G(m, 1)$ is the same as packing $2N$ points in S^{m-1} with the condition that all points form antipodal pairs. We omit the details of this search, since we later redid the calculations using the more general methods described in Section 4.

Table 1 lists, for each value of N from 2 to 55, the minimum distance θ_1 for the best antipodal packing of $2N$ points on S^2 that we have found. For comparison, the table also shows the minimal angle for the best known packing of $2N$ points without

the antipodal condition. We see that requiring a packing on S^2 to be antipodal is a definite handicap: only in the cases $N = 3$ and $N = 6$ do the antipodal and unrestricted packings coincide.

The table also gives the *automorphism group* of the antipodal packing, that is, the subgroup of $O(3)$ that leaves the set of points invariant. The groups are given in orbifold notation [Conway and Sloane a] and as the double cover of a rotation group. The symbol $\pm\mathcal{G}$ indicates that the group consists of the matrices $\pm M$ for $M \in \mathcal{G}$, where \mathcal{G} is a cyclic (\mathcal{C}), dihedral (\mathcal{D}), tetrahedral (\mathcal{T}), octahedral (\mathcal{O}) or icosahedral (\mathcal{I}) group. In each case the subscript gives the order of the rotation group, so the order of the automorphism group is twice this subscript.

We turn to some noteworthy features of certain entries of Table 1.

$N = 5$

The five lines are five of the six diameters of a regular icosahedron.

$N = 8$

The putative solution forms an unpleasant-looking configuration of 16 antipodal points on S^2 , with no further symmetry. The convex hull is shown on the left in Figure 2. In contrast, the putatively best packing of 16 points, shown on the right in the same figure, has a group of order 16.

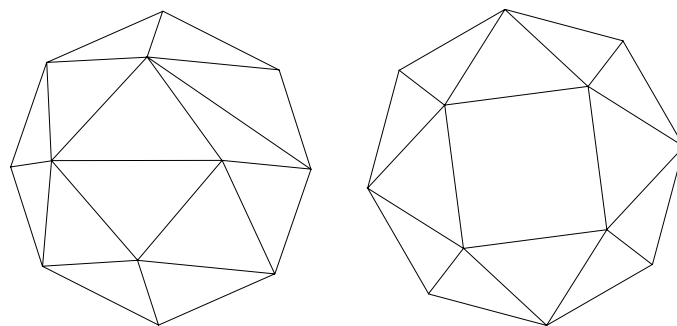


FIGURE 2. $N = 8$: Best antipodal packing known (left) and best unrestricted packing known (right) of 16 points on the sphere.

N	$\min \theta_1$	$\min \theta'_1$	group	polyhedron	N	$\min \theta_1$	$\min \theta'_1$	group
2	90.0000	109.4712	*224 = $\pm \mathcal{D}_8$	square	29	27.5244	27.5564	2*7 = $\pm \mathcal{D}_{14}$
3	90.0000	90.0000	*432 = $\pm \mathcal{O}_{24}$	octahedron	30	26.9983	27.1928	2*5 = $\pm \mathcal{D}_{10}$
4	70.5288	74.8585	*432 = $\pm \mathcal{O}_{24}$	cube	31	26.4987	26.6840	5 \times = $\pm \mathcal{C}_5$
5*	63.4349	66.1468	2*5 = $\pm \mathcal{D}_{10}$	pentagonal antiprism	32	25.9497	26.2350	2* = $\pm \mathcal{C}_2$
6	63.4349	63.4349	*532 = $\pm \mathcal{J}_{60}$	icosahedron	33	25.5748	25.9474	3*2 = $\pm \mathcal{J}_{12}$
7	54.7356	55.6706	*432 = $\pm \mathcal{O}_{24}$	rhombic dodecahedron	34	25.2567	25.4638	3 \times = $\pm \mathcal{C}_3$
8*	49.6399	52.2444	\times = $\pm \mathcal{C}_1$		35	24.8702	25.1709	\times = $\pm \mathcal{C}_1$
9*	47.9821	49.5567	3 \times = $\pm \mathcal{C}_3$		36	24.5758	24.9265	3 \times = $\pm \mathcal{C}_3$
9*	47.9821	49.5567	2* = $\pm \mathcal{C}_2$		37	24.2859	24.4209	\times = $\pm \mathcal{C}_1$
10*	46.6746	47.4310	*226 = $\pm \mathcal{D}_{12}$	hexakis bi-antiprism	38	24.0886	24.1282	\times = $\pm \mathcal{C}_1$
11	44.4031	44.7402	2*5 = $\pm \mathcal{D}_{10}$		39	23.8433	23.9310	3 \times = $\pm \mathcal{C}_3$
12	41.8820	43.6908	*432 = $\pm \mathcal{O}_{24}$	rhombicuboctahedron	40	23.3293	23.5531	\times = $\pm \mathcal{C}_1$
13	39.8131	41.0377	2* = $\pm \mathcal{C}_2$		41	22.9915	23.1946	\times = $\pm \mathcal{C}_1$
14	38.6824	39.3551	\times = $\pm \mathcal{C}_1$		42	22.7075	23.0517	3 \times = $\pm \mathcal{C}_3$
15*	38.1349	38.5971	2*5 = $\pm \mathcal{D}_{10}$		43	22.5383	22.6744	2*3 = $\pm \mathcal{D}_6$
16	37.3774	37.4752	*532 = $\pm \mathcal{J}_{60}$	pentakis dodecahedron	44	22.2012	22.4679	\times = $\pm \mathcal{C}_1$
17	35.2353	35.8078	\times = $\pm \mathcal{C}_1$		45	22.0481	22.1540	2* = $\pm \mathcal{C}_2$
18	34.4088	35.1897	3 \times = $\pm \mathcal{C}_3$		46	21.8426	22.0276	\times = $\pm \mathcal{C}_1$
19	33.2115	34.2507	\times = $\pm \mathcal{C}_1$		47	21.6609	21.7221	\times = $\pm \mathcal{C}_1$
20	32.7071	33.1584	*222 = $\pm \mathcal{D}_4$		48	21.4663	21.5206	3 \times = $\pm \mathcal{C}_3$
21	32.2161	32.5064	5 \times = $\pm \mathcal{C}_5$		49	21.1610	21.3711	\times = $\pm \mathcal{C}_1$
22	31.8963	31.9834	2*3 = $\pm \mathcal{D}_6$		50	20.8922	21.0312	\times = $\pm \mathcal{C}_1$
23	30.5062	30.9592	\times = $\pm \mathcal{C}_1$		51	20.6903	20.8556	\times = $\pm \mathcal{C}_1$
24	30.1628	30.7628	3*2 = $\pm \mathcal{J}_{12}$		52	20.4914	20.6566	\times = $\pm \mathcal{C}_1$
25	29.2486	29.7530	3 \times = $\pm \mathcal{C}_3$		53	20.2685	20.4394	\times = $\pm \mathcal{C}_1$
26	28.7126	29.1948	2* = $\pm \mathcal{C}_2$		54	20.1555	20.3044	3 \times = $\pm \mathcal{C}_3$
27	28.2495	28.7169	\times = $\pm \mathcal{C}_1$		55*	20.1034	20.1110	*532 = $\pm \mathcal{J}_{60}$
28	27.8473	28.1480	\times = $\pm \mathcal{C}_1$					

TABLE 1. Summary of results about packings in $G(3, 1)$. For each N we give, rounded to four decimal places, the minimal angle θ_1 of the best packing we could find of N points in $G(3, 1)$ (that is, the best packing of N lines through the origin in \mathbb{R}^3 , or the best antipodal packing of $2N$ points on S^2), and the minimal angle θ'_1 of the best known *unconstrained* packing of $2N$ points on S^2 , taken from [Hardin et al. 1993–95]. The fourth column shows the automorphism group for the best antipodal packing, both in orbifold notation and as a double cover of a rotation group (see text for notation). When the packing corresponds to the diameters of a known polyhedron, this is also indicated. An asterisk next to the value of N refers to notes and figures starting on page 141.

The entries for $N \leq 6$ were shown to be optimal by Fejes Tóth [1965]; see also [Rosenfeld 1994]. The case $N = 7$ will be proved in Section 5. The solutions for $N \geq 8$ are the best found with over 15000 random starts with our optimizer. There is no guarantee that they are optimal, but experience with similar problems suggests that they will be hard to beat and in any case will be not far from optimal.

For $N = 1, 2, 3, 6$ the solutions are known to be unique, for $N = 4$ there are precisely two solutions [Fejes Tóth 1965; Rosenfeld 1993; Rosenfeld 1994], and for $N = 5, 7, 8$ the solutions appear to be unique. For larger values of N , however, the solutions are often not unique. For $N = 9$ lines there are two different solutions, and in the range $N \leq 30$ the solutions for 10, 22, 25, 27, 29 lines (and possibly others) contain lines that “rattle”, that is, lines that can be moved freely over a small range of angles without affecting the minimal angle.

Remark: Entries in all tables are approximated by rounding, rather than truncation.

$N = 9$

There appear to be two inequivalent solutions. The nicer one has an order-6 symmetry group, $3\times$, or $[2^+, 6^+]$ in Coxeter's notation [Coxeter and Moser 1980]; see Figure 3, top. The points lie in six parallel layers of equilateral triangles.

The second solution has group $2*$, of order 4; see Figure 3, bottom.

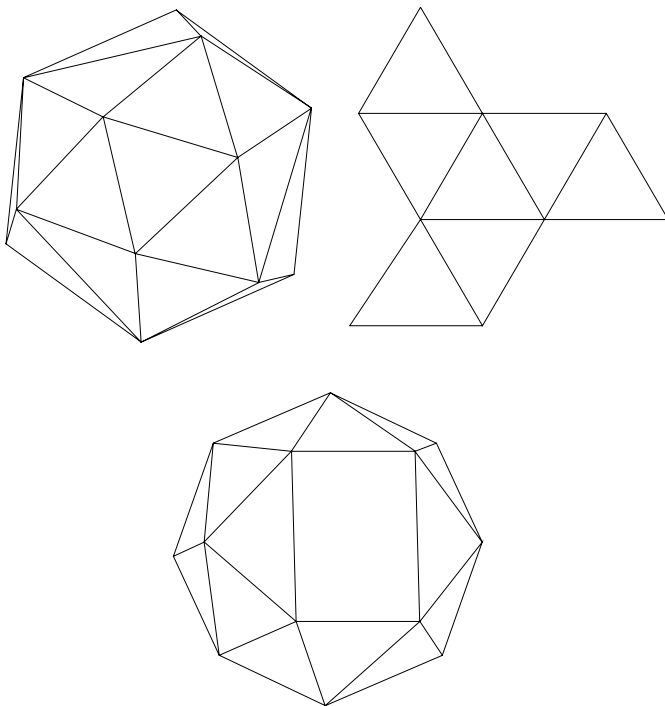


FIGURE 3. $N = 9$: Antipodal packings of 18 points with group of order 6 (top) and order 4 (bottom). In the order-6 arrangement, half the points can be located by wrapping a pinwheel of seven equilateral triangles (top right) onto the sphere, so that the edges of the spherical triangles have length 47.98213264° .

$N = 10$

This is a hexakis bi-antiprism, since it consists of a bi-(hexagonal antiprism) together with an axial line that can rattle, giving infinitely many solutions. The axis appears horizontally in Figure 4, left.

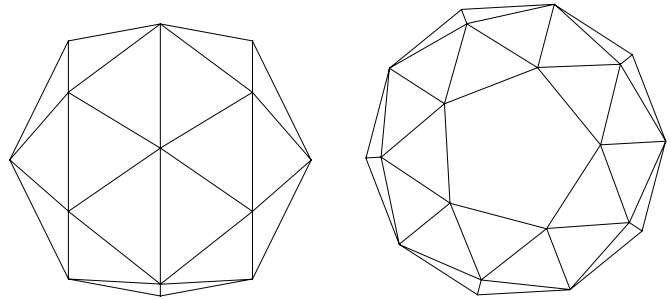


FIGURE 4. $N = 10, 15$: Best antipodal packing found for 20 points (left) and for 30 points (right).

$N = 15$

Combinatorially, this arrangement is obtained from a pentakis dodecahedron (the solution for $N = 16$) by omitting two opposite vertices, as shown in Figure 4, right. However, the angular separation is slightly greater than for $N = 16$.

$N = 55$

The 110 antipodal points can be taken to be the union of the vertex sets of a dodecahedron (20), an icosidodecahedron (30) and a truncated icosahedron (60), as shown in Figure 5. The 15 lines through the icosidodecahedral points rattle. This arrangement can be obtained from a geodesic dome or 12-fold reticulated icosahedron [Coxeter 1974] by omitting its twelve pentagonal vertices. Inci-

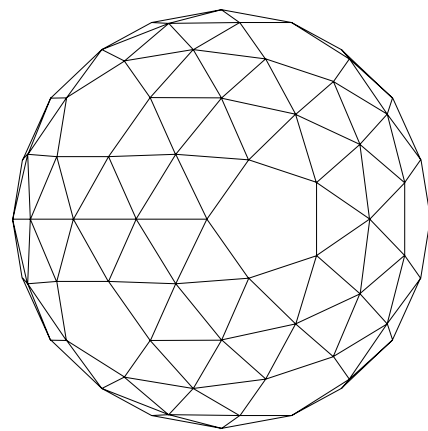


FIGURE 5. Best antipodal packing found of 110 points.

dentally, our best solution for 61 lines has a symmetry group of order 6, and is not found by placing points at the centers of the pentagonal faces of Figure 5.

Packings of lines in higher dimensional spaces will be discussed in Section 6.

4. PACKING PLANES IN FOUR DIMENSIONS

Asimov [1985] has proposed a technique called the *grand tour* for displaying multi-dimensional data on a two-dimensional computer screen. His idea was to choose a finite sequence, or tour, of two-dimensional planes that are in some sense representative of all planes, and to project the data onto each plane in turn, in the hope that the viewer will be able to notice any pattern or structure that is present. This technique has been implemented in the XGobi program [Buja and Asimov 1986; Swayne et al. 1991].

In 1993 Dianne Cook asked us if we could modify our algorithm for finding spherical codes in order to search for packings in $G(m, 2)$ for $m \geq 4$. Furthermore, for the grand tour application, there should be a Hamiltonian circuit through the planes, in which edges indicate neighboring planes. We accomplished this in the following way.

Following the methods we had used to find packings in S^d and experimental designs in different spaces [Hardin and Sloane 1992, Section 4.11; 1993; Hardin et al. a], corresponding to a set of planes $S = \{P_1, \dots, P_N\} \subseteq G(m, n)$ we define a potential

$$\Phi_c(S) = \sum_{i < j} \frac{1}{d_c(P_i, P_j) - A},$$

where A is a suitably chosen constant. There is a similar definition for Φ_g involving d_g . Initially A is set to 0 and S is a randomly chosen set of planes. We invoke the Hooke–Jeeves pattern search optimization algorithm to modify S , attempting to minimize $\Phi_c(S)$. After a fixed time (we used 100 steps of the optimizer), A is advanced halfway to the current minimal distance between the P_i , and

the process is repeated, terminating when no further improvement is obtained to the accuracy of the machine. The whole process is repeated with several thousand random starts—and also with initial configurations taken from other sources, such as subsets or supersets of other arrangements—and the best final configuration is recorded.

The partial derivatives of $\Phi_c(S)$ were found analytically, but for $\Phi_g(S)$ we calculated them by numerical differentiation.

We began by computing a table of packings of N planes in $G(4, 2)$, for $N \leq 50$, with respect to both d_c and d_g . The results for packings of $N \leq 24$ planes are summarized in Table 2.

Our understanding of these results was hindered by the fact that planes are, well, *plain*, with no

N	d_c -optimal		d_g -optimal	
	$\min d_c^2$	$\min d_g^2$	$\min d_c^2$	$\min d_g^2$
2	2.0000	4.9348	2.0000	4.9348
3	1.5000	2.1932	1.2500	2.7416
4	1.3333	1.8253	1.2000	2.6824
5	1.2500	1.9739	1.2000	2.6824
6	1.2000	2.6824	1.2000	2.6824
7	1.1667	1.6440	0.9875	2.1281
8	1.1429	1.5818	0.9700	1.9235
9	1.1231	1.5175	0.9501	1.8087
10	1.1111	1.5725	0.9764	1.7886
11	1.0000	1.2715	0.9247	1.6711
12	1.0000	1.3413	0.9204	1.6416
13	1.0000	1.2348	0.9133	1.5600
14	1.0000	1.2337	0.8933	1.5327
15	1.0000	1.2337	0.8923	1.5284
16	1.0000	1.2337	0.8904	1.5210
17	1.0000	1.2337	0.8549	1.3925
18	1.0000	1.2337	0.8504	1.3768
19	0.9091	1.1666	0.8412	1.3477
20	0.9091	1.1666	0.8351	1.3284
21	0.8684	1.0352	0.8225	1.2834
22	0.8629	1.0592	0.8046	1.2385
23	0.8451	1.0081	0.7910	1.2012
24	0.8372	0.9901	0.7812	1.1707

TABLE 2. Putatively best packings of N planes in $G(4, 2)$ with respect to the chordal (d_c) and geodesic (d_g) metrics.

distinguishing features, and when produced by the computer appear as random generator matrices referred to a random coordinate frame. However, we found that the set of principal vectors in the planes could often be used to find a coordinate system that would reveal some of the structure of the planes.

For two planes the best packing is the same for both metrics, and consists of two mutually orthogonal planes with principal angles $\theta_1 = \theta_2 = \pi/2$, so $d_c^2 = 2$ and $d_g^2 = \pi^2/2$.

For three planes the two answers are different. The best packing for chordal distance has generator matrices

$$\begin{array}{cccc} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & -\frac{1}{2} & \frac{\sqrt{3}}{2} \\ 0 & 1 & -\frac{\sqrt{3}}{2} & -\frac{1}{2} \\ 1 & 0 & -\frac{1}{2} & -\frac{\sqrt{3}}{2} \\ 0 & 1 & \frac{\sqrt{3}}{2} & -\frac{1}{2} \end{array}$$

so the principal angles are $\theta_1 = \theta_2 = \pi/3$ between each pair of planes, and $d_c^2 = \frac{3}{2}$, $d_g^2 = \frac{2}{9}\pi^2$. The best packing for geodesic distance has generator matrices

$$\begin{array}{cccc} 1 & 0 & 0 & 0 \\ 0 & -\frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ 0 & 0 & 1 & 0 \\ -\frac{1}{\sqrt{2}} & 0 & 0 & \frac{1}{\sqrt{2}} \end{array}$$

so the principal angles are $\theta_1 = \pi/6$, $\theta_2 = \pi/2$, and $d_c^2 = \frac{5}{4}$, $d_g^2 = \frac{5}{18}\pi^2$.

Postponing discussion of $N = 4$ and 5 for the moment, we consider the case of six planes, where we discovered that the answer for both metrics formed a regular simplex (although not an isoclinic configuration; compare [Wong 1961], which considers a related problem). The principal angles between every pair of planes were $\theta_1 = \arcsin 1/\sqrt{5}$ and $\theta_2 = \pi/2$. This set of planes is conveniently

described using simplicial coordinates. Let A, B, C, D, E be the vectors from the center of a regular simplex in \mathbb{R}^4 to its vertices, with $A + B + C + D + E = 0$, and write $[a, b, c, d, e]$ for $aA + bB + cC + dD + eE$. Then one of the six planes is spanned by $[1, \tau, 1, 0, 0]$ and its cyclic shifts, where $\tau = \frac{1}{2}(1 + \sqrt{5})$, and the other five planes are obtained from it by taking even permutations of these coordinates. (We later found an equally good packing with respect to chordal distance that was not a simplex with respect to geodesic distance. This is described below.)

The six planes intersect the surface of the unit ball of \mathbb{R}^4 in a remarkable link, the *hexalink*. It can be shown that, apart from the n -component unlinks and Hopf links, which exist for all n , the hexalink is the only link of circular rings in which there are orientation-preserving symmetries taking any two links to any other two. (Details will be given elsewhere.)

The discovery of this 6-vertex simplex was initially somewhat of a surprise, since $G(4, 2)$ is only a 4-dimensional manifold. It did suggest that the answer should somehow be related to the six equiangular diameters of the icosahedron, and led to the following reformulation of the problem.

We remind the reader that any element α of $SO(4)$ may be represented as $\alpha : x \mapsto \bar{l}xr$, where $x = x_0 + x_1i + x_2j + x_3k$ represents a point on S^3 and l, r are unit quaternions [Du Val 1964]. The pair $-l, -r$ represent the same α . The correspondence between α and $\pm(l, r)$ is one-to-one.

Given a plane $P \in G(4, 2)$, let α be the element of $SO(4)$ that fixes P and negates the points of the orthogonal plane P^\perp . Then $\alpha^2 = 1$, and for this α , it is easy to see that $l = l_1i + l_2j + l_3k$ and $r = r_1i + r_2j + r_3k$ are purely imaginary unit quaternions. This establishes the following result, which can be found in [Leichtweiss 1961], for example.

Theorem 4.1. *A plane $P \in G(4, 2)$ is represented by a pair $(l, r) \in S^2 \times S^2$, with $(-l, -r)$ representing the same P .*

There are simple formulas relating P and (l, r) , pointed out to us by Simon Kochen. Given (l, r) , if $l \neq -r$ then P is spanned by the vectors corresponding to the quaternions $u = 1 - lr$ and $v = l + r$. The special case when $l = r$ is even simpler: take $u = 1, v = l$. If $l = -r$, take u and v to be purely imaginary unit quaternions such that l, u, v correspond to a coordinate frame. Conversely, if P is spanned by two orthogonal unit vectors represented by quaternions u, v , then $\pm(l, r) = \pm(u\bar{v} - v\bar{u}, \bar{v}u - \bar{u}v)$.

Given two planes $P, Q \in G(4, 2)$, represented by $\pm(l, r)$ and $\pm(l', r')$, the principal angles θ_1, θ_2 between them may be found as follows. Let φ be the angle between l and l' , and let ψ be the angle between r and r' , with $0 \leq \varphi \leq \pi$ and $0 \leq \psi \leq \pi$. If $\varphi + \psi > \pi$, replace φ by $\pi - \varphi$ and ψ by $\pi - \psi$, so that $0 \leq \varphi + \psi \leq \pi$, with $\varphi \leq \psi$ (say). Then

$$\begin{aligned} \theta_1 &= \frac{1}{2}(\psi - \varphi), & d_g^2(P, Q) &= \frac{1}{2}(\psi^2 + \varphi^2), \\ \theta_2 &= \frac{1}{2}(\psi + \varphi), & d_c^2(P, Q) &= 1 - \cos \psi \cos \varphi. \end{aligned} \tag{4.1}$$

We omit the elementary proof.

A set $S = \{P_1, \dots, P_N\} \subseteq G(4, 2)$ is thus represented by a *binocular code* consisting of a set of pairs $\pm(l_i, r_i) \in S^2 \times S^2$. We call the list of $2N$ points $\pm l_i$ (which need not be distinct) the *left code* corresponding to S , and the points $\pm r_i$ the *right code*. Conversely, given two multisets $L \subseteq S^2$ and $R \subseteq S^2$, each of size $2N$ and closed under negation, and a bijection or *matching* f between them that satisfies $f(-l) = -f(l)$ for $l \in L$, we obtain a set of N planes in $G(4, 2)$.

The binocular codes for the d_c -optimal packings of 2 to 5 planes are shown in Figure 6; they can all be made to lie in the equatorial planes. Except for $N = 3$, the left and right codes are identical. For $N \leq 4$ there are repeated points.

For $N = 6$ the left and right codes consist of the twelve vertices of an icosahedron (Figure 7). Setting $\lambda = 1/\sqrt{\tau + 2}$ we can take the points to be

$$\lambda(0, \pm 1, \pm \tau), \quad \lambda(\pm \tau, 0, \pm 1), \quad \lambda(\pm 1, \pm \tau, 0). \tag{4.2}$$

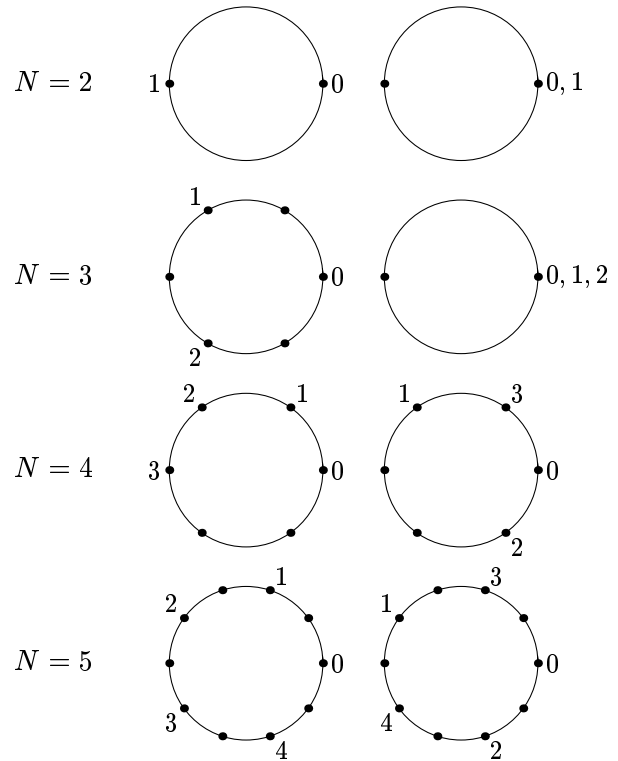


FIGURE 6. Equatorial planes showing the binocular codes describing best packings of 2 to 5 planes for chordal distance. Matching points are labeled with the same symbol. The points for $N = 3$ and $N = 5$ are vertices of the obvious regular polygons, but for $N = 4$ the coordinates are $(1, 0)$ and $\pm \frac{1}{\sqrt{3}}(1, \pm \sqrt{2})$.

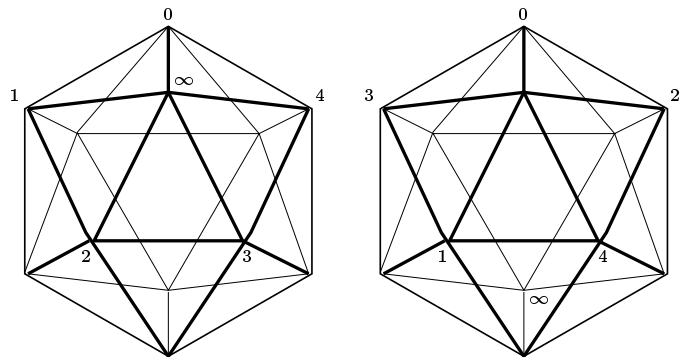


FIGURE 7. Best packing of six planes in $G(4, 2)$ with respect to both metrics. Left and right codes comprise vertices of icosahedron. Adjacent vertices in one code are matched with nonadjacent vertices in the other code.

The matching is obtained by mapping each point to its algebraic conjugate (that is, replacing $\sqrt{5}$ by $-\sqrt{5}$), and rescaling so the points again lie on a unit sphere. As already mentioned, the principal angles between each pair of these planes are $\theta_1 = \arcsin 1/\sqrt{5}$ and $\theta_2 = \pi/2$, so $d_c^2 = \frac{6}{5}$ and $d_g^2 = 2.6824$.

There is a second set of six planes with $d_c^2 = \frac{6}{5}$, but with d_g^2 only equal to 2.0030. Here the left and right codes form the vertices of what we shall call the *antiicosahedron*, consisting of the points

$$\lambda(0, \pm 1, \pm \tau), \quad \lambda(\pm \tau, 0, \pm 1), \quad \lambda(\pm \tau, \pm 1, 0)$$

(compare (4.2)), and shown in Figure 8. Topologically this is a “parallel bi-slit cuboctahedron”, obtained by dividing two opposite square faces of a cuboctahedron into two triangles by parallel lines. The matching is this:

$$\begin{aligned} \lambda(0, \pm 1, \tau) &\leftrightarrow \lambda(0, \pm \tau, 1), \\ \lambda(\tau, 0, \pm 1) &\leftrightarrow \lambda(1, 0, \pm \tau), \\ \lambda(\pm \tau, 1, 0) &\leftrightarrow \lambda(\pm 1, \tau, 0). \end{aligned}$$

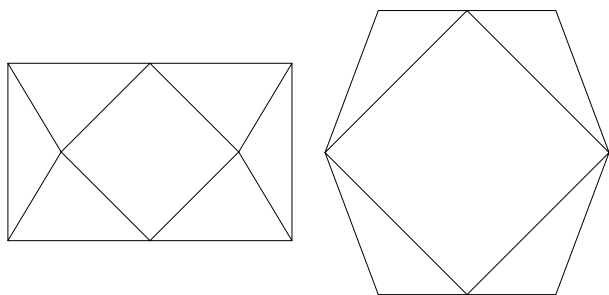


FIGURE 8. Top and side views of antiicosahedron.

Also worth mentioning are four larger putatively d_c -optimal packings found by the computer, and having 10, 18, 48 and 50 planes.

$N = 10$

For the 10-plane packing the left and right codes consist of the vertices of a decagonal prism with coordinates

$$\pm \left(\sqrt{\frac{2}{3}} \cos r\theta, \sqrt{\frac{2}{3}} \sin r\theta, \sqrt{\frac{1}{3}} \right),$$

where $\theta = \pi/5$ and $r = 0, \dots, 9$. A typical point $(\sqrt{2/3} \cos r\theta, \sqrt{2/3} \sin r\theta, \sqrt{1/3})$ in the left code is matched with

$$(-1)^r \left(\sqrt{\frac{2}{3}} \cos 3r\theta, \sqrt{\frac{2}{3}} \sin 3r\theta, \sqrt{\frac{1}{3}} \right)$$

in the right code. Then $d_c^2 = \frac{10}{9}$ and $d_g^2 = 1.5725$. The most interesting property of this configuration is that, although three sets of canonical angles occur, the chordal distance between every pair of planes is the same—this is a regular simplex!

We find it surprising that this is superior to the packing of ten planes obtained by matching the vertices of a dodecahedron to their algebraic conjugates, as shown in Figure 9.

$N = 18$

Let \mathcal{O} denote the set of vertices of a regular octahedron. The binocular code for the 18-plane packing is $\mathcal{O} \times \mathcal{O} := \{(l, r) : l, r \in \mathcal{O}\}$. Projectively, the 18 two-spaces are the edges of a desmic triple of tetrahedra [Stephanos 1879; Hudson 1905; Coxeter 1950]. (Two tetrahedra are called *desmic* if they are in perspective from four distinct points; these points then form a third tetrahedron desmic with either of the first two. The 18 edges of such a desmic triple are also the edges of a unique other desmic triple.) We were pleased to see this configuration appear, since it was already familiar in the context of quantum logic [Conway and Kochen]. This set of planes can be constructed directly by taking the planes spanned by all pairs of mutually perpendicular minimal vectors of the D_4 lattice (compare [Conway and Sloane 1996]). In this form the planes have generator matrices such as

$$\begin{bmatrix} + & + & 0 & 0 \\ 0 & 0 & + & - \end{bmatrix} \quad (12 \text{ planes}),$$

$$\begin{bmatrix} + & + & 0 & 0 \\ + & - & 0 & 0 \end{bmatrix} \quad (6 \text{ planes}).$$

Three different sets of principal angles occur: $(0, \pi/2)$, $(\pi/4, \pi/4)$, and $(\pi/2, \pi/2)$. Thus $d_c^2 = 1$ and $d_g^2 = 1.2337$. The automorphism group of this packing has structure $[3, 4, 3].2$ and order 2304.

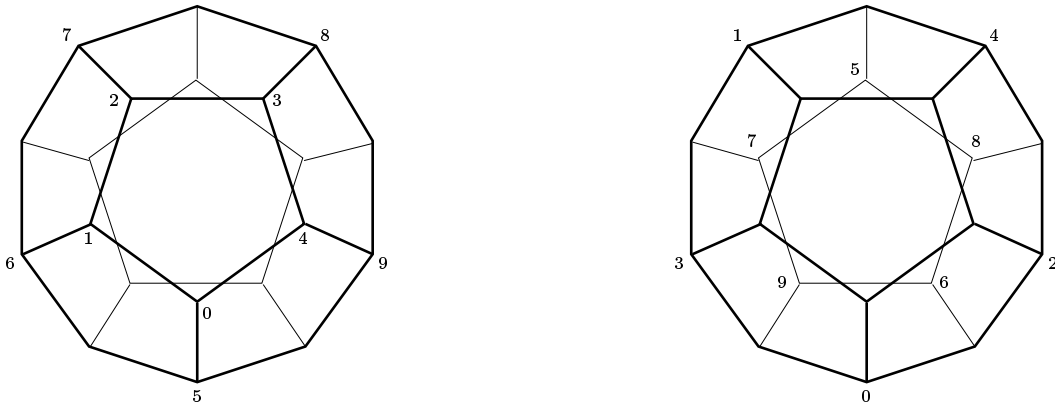


FIGURE 9. Matching of vertices of dodecahedron.

These 18 planes can also be described as the set of planes that meet the 24-cell in one of its equatorial squares.

$N = 48$ and $N = 50$

Let \mathcal{C} denote the set of vertices of a cube. Then the binocular codes for the 48- and 50-plane packings are respectively $(\mathcal{O} \times \mathcal{C}) \cup (\mathcal{C} \times \mathcal{O})$ and $(\mathcal{O} \times \mathcal{O}) \cup (\mathcal{C} \times \mathcal{C})$. For both arrangements we have $d_c^2 = \frac{2}{3}$ and $d_g^2 = 0.7576$. Both are believed to be optimal. (We mention the 48-plane packing because of its greater symmetry.)

The Matching Problem

In order to maximize the minimal chordal distance between the planes, the matching between the left and right codes should (from (4.1)) be chosen so as to minimize the maximal value of $\cos \psi \cos \varphi$. Stated informally, the matching should be such that if two points are close together on one of the spheres then the points to which they are matched should be far apart on the other sphere. In the case of the icosahedron, for example (see Figure 12), the matching sends adjacent vertices to nonadjacent vertices. There is a unique way to do this.

At this point we were tempted to see if any new record packings in $G(4, 2)$ could be obtained by taking the $2N$ antipodal points corresponding to a good N -line packing in $G(3, 1)$, and matching them with themselves in an optimal way. However, it

was not easy to see how to solve the matching problem. Fortunately David Applegate (personal communication) found that it could be reformulated as an integer programming problem, as follows.

Given an antipodal set $S = \{P_1, \dots, P_{2N}\} \subseteq S^2$, we wish to find a permutation σ of S with the property that $\sigma(-P_i) = -\sigma P_i$ for all i , and such that the minimal value of $1 - (P_i \cdot P_j)(\sigma P_i \cdot \sigma P_j)$ over $i \neq j$ is maximized. If we do the maximization by binary search, we may define $\pi(P_i, P_j) = 1$ if $\sigma P_i = P_j$, or 0 otherwise, with the constraints $\pi(P_i, P_j) = \pi(-P_i, -P_j)$,

$$\sum_{j=1}^{2N} \pi(P_i, P_j) = 1 \quad \text{for } 1 \leq i \leq 2N,$$

$$\sum_{i=1}^{2N} \pi(P_i, P_j) = 1 \quad \text{for } 1 \leq j \leq 2N,$$

and $\pi(P_i, P_j) + \pi(P_k, P_l) < 1$ for all $1 \leq i, j, k, l \leq 2N$ such that $1 - (P_i \cdot P_k)(P_j \cdot P_l) < M$. There is a feasible solution if and only if $d_c^2 \geq M$.

Applegate kindly implemented this procedure, and used it to solve the matching problem for our best packings in $G(3, 1)$ and for various polyhedra. Unfortunately no new records have yet been obtained by this method.

Best Packings for the Geodesic Metric

So far we have mostly discussed packings that attempt to maximize the minimal chordal distance

between planes. We also computed packings for the geodesic distance, and we shall now describe some of them. In general, however, they are much less symmetric than the chordal-distance packings, especially for more than 16 planes.

For $N = 4, 5$ the solutions are subsets of the 6-plane packing. For $N = 7$ the left code is a heptagonal antiprism and the right code is an equatorial 14-gon.

For $N = 12$ the binocular code is given by the set $\{\pm(l, r)\}$, where l runs through the vertices of a regular tetrahedron and r through those of an equatorial equilateral triangle.

For $N = 16$ the left and right codes are the union of two similarly oriented square prisms. For larger N the geodesic packings do not seem so interesting. For $N = 18$, for example, the best packing has no nontrivial symmetries.

Hamiltonian Paths

One further question remains to be discussed, that of arranging the planes in a circuit in such a way that adjacent planes are close together, for the grand tour application. This turned out to be a much easier problem than finding the packings. We handled it in two different ways. For configurations such as the 48-plane arrangement, where there was an obvious notion of adjacency—in this case, defining two planes to be adjacent if the principal angles are $\pi/4, \pi/4$ —we represent the packing by a graph with nodes representing the planes, and look for a Hamiltonian cycle. In less regular cases, we convert the packing into a traveling salesman problem using chordal distance to define the distance between nodes, and look for a minimal length circuit. In both cases we were able to make use of the travelling salesman programs described in [Applegate et al. 1995], which can handle 100-node graphs without difficulty. In the public archive containing our results (see Electronic Availability before the references), the files with suffix `.ham` have been arranged in cycles in this way.

The above reformulation in terms of binocular codes applies only to $G(4, 2)$; we knew from the

beginning that this case would be special, since $G(4, 2)$ is the only Grassmannian where the Riemannian metric is not unique [Leichtweiss 1961]. In the next section we describe a second reformulation that applies to the general case.

5. PACKING n -PLANES IN HIGHER DIMENSIONS

Three observations contributed to the second reformulation.

First, as can be seen in Table 2, for several examples of N -plane packings in $G(4, 2)$ the largest value of d_c^2 that we could attain was $N/(N-1)$, and in every case this was an upper bound. Further experimentation with other packings in $G(m, n)$ for $m \leq 8$ led us to guess an upper bound of

$$d_c^2 \leq \frac{n(m-n)}{m} \frac{N}{N-1}, \quad (5.1)$$

which again we could achieve for some small values of N . The form of (5.1) was suggestive of the Rankin bound for spherical codes [Conway and Sloane 1996] or the Plotkin bound for binary codes [MacWilliams and Sloane 1977].

Secondly, investigation of the 18-plane chordal-distance packing revealed that, with respect to d_c , this packing has the structure of a regular orthoplex (or generalized octahedron) with 18 vertices. Combining this with the fact that the 10-plane packing formed a regular simplex, we had strong evidence that $G(4, 2)$ should have an isometric embedding (with respect to d_c) into \mathbb{R}^9 .

Finally, a computer program was therefore written to determine the lowest dimensions into which our library of packings in $G(m, n)$ could be isometrically embedded. More precisely, for a given set of N planes in $G(m, n)$, we searched for the smallest dimension D such that there are N points in \mathbb{R}^D whose Euclidean distances coincide with the chordal distances between our planes.

The results were a surprise: it appeared that $G(m, n)$ with chordal distance could be isometrically embedded into \mathbb{R}^D , for $D = \binom{m+1}{2} - 1$, independent of n . Furthermore, the points representing

elements of $G(m, n)$ were observed to lie on a sphere of radius $\sqrt{n(m-n)}/2m$ in \mathbb{R}^D .

Aided by discussions with Colin Mallows, we soon found an explanation: just associate to each $P \in G(m, n)$ the orthogonal projection map from \mathbb{R}^m to P . If A is a generator matrix for P whose rows are orthogonal unit vectors, then the projection is represented by the matrix $\mathcal{P} = A^t A$, where t denotes transposition. \mathcal{P} is an $m \times m$ symmetric idempotent matrix, which is independent of the particular orthonormal generator matrix used to define it. Changing to a different coordinate frame in \mathbb{R}^m has the effect of conjugating \mathcal{P} by an element of $O(m)$. With the help of (2.1), we see that

$$\text{trace } \mathcal{P} = n.$$

Thus \mathcal{P} lies in a space of dimension $\binom{m+1}{2} - 1$.

Let $\|\cdot\|$ denote the L_2 -norm of a matrix, that is,

$$\|M\| = \sqrt{\sum_{i=1}^m \sum_{j=1}^m M_{ij}^2} = \sqrt{\text{trace } M^t M}.$$

if $M = (M_{ij})$ with $1 \leq i, j \leq m$. For $P, Q \in G(m, n)$, with orthonormal generator matrices $A,$

$B,$ and principal angles $\theta_1, \dots, \theta_n,$ an elementary calculation using (2.1) and (2.2) shows that

$$\begin{aligned} d_c^2(P, Q) &= n - (\cos^2 \theta_1 + \dots + \cos^2 \theta_n) \\ &= n - \text{trace } A^t A B^t B = \frac{1}{2} \|\mathcal{P} - \mathcal{Q}\|^2, \end{aligned}$$

where \mathcal{P}, \mathcal{Q} are the corresponding projection matrices.

Defining the traceless part of \mathcal{P} as $\bar{\mathcal{P}} = \mathcal{P} - (n/m)I_m,$ we have $\|\bar{\mathcal{P}}\|^2 = n(m-n)/m.$ We have thus established the following theorem.

Theorem 5.1. *Let $D = \binom{m+1}{2} - 1.$ The representation of n -planes $P \in G(m, n)$ by their projection matrices \mathcal{P} gives an isometric embedding of $G(m, n)$ into a sphere of radius $\sqrt{n(m-n)}/m$ in $\mathbb{R}^D,$ with $d_c(P, Q) = \frac{1}{\sqrt{2}} \|\mathcal{P} - \mathcal{Q}\|.$*

Thus chordal distance between planes is $\frac{1}{\sqrt{2}}$ times the straight-line distance between the projection matrices (which explains our name for this metric). The geodesic distance between the planes is $\frac{1}{\sqrt{2}}$ times the geodesic distance between the projection matrices, measured along the sphere in $\mathbb{R}^D.$

Figure 10 attempts to display the embeddings of $G(m, 0), G(m, 1), \dots, G(m, m)$ in $\mathbb{R}^{D+1}.$ Since

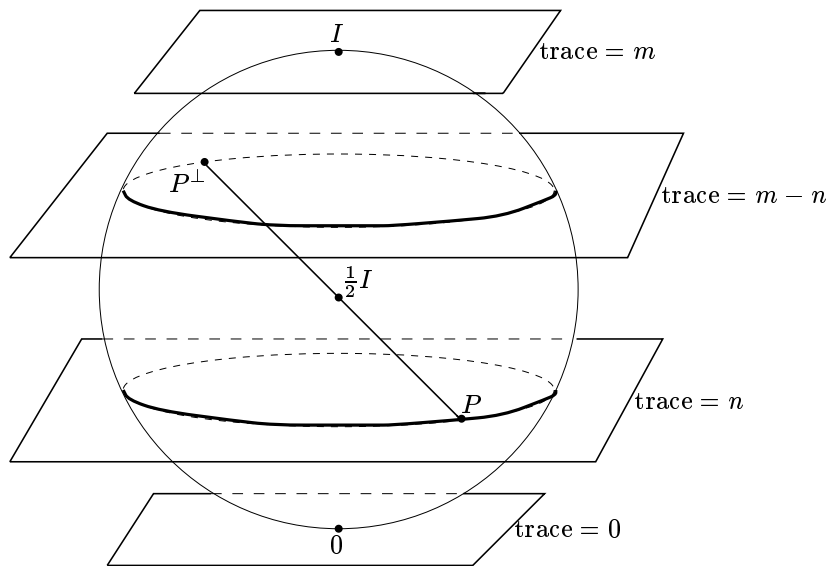


FIGURE 10. Embedding of $G(m, 0), \dots, G(m, m)$ into large sphere of radius $\frac{1}{2}\sqrt{m}$ in Euclidean space of dimension $\frac{1}{2}m(m+1).$ The space $G(m, n)$ lies on sphere of radius $\sqrt{n(m-n)}/m$ in $\mathbb{R}^D,$ where $D = \frac{1}{2}(m-1)(m+2).$

$\|\mathcal{P} - \frac{1}{2}I_m\|^2 = \frac{1}{4}m$, all the planes lie on the large sphere, centered at $\frac{1}{2}I_m$, of radius $\frac{1}{2}\sqrt{m}$. The members of $G(m, n)$ lie on the intersection of the large sphere with the plane trace $\mathcal{P} = n$, which intersection is itself a sphere in \mathbb{R}^D of radius $\sqrt{n(m-n)}/m$ centered at $\frac{n}{m}I_m$. A plane and its orthogonal complement are represented by antipodal points on the large sphere.

In contrast to this result, we briefly remark, without giving details, that there is no way to embed $G(m, n)$ into Euclidean space of any dimension so that the geodesic distance d_g on $G(m, n)$ is represented by Euclidean distance in that space. Of course the Plücker embedding, in which members of $G(m, n)$ are represented by points in projective space of dimension $\binom{m}{n} - 1$, also does not give a way to realize either d_c or d_g as Euclidean distance. (Nor does the Nash embedding theorem [Nash 1956].) Note also that the dimension of the Plücker embedding is in general much larger than the dimension of our embedding.

Since we have embedded $G(m, n)$ into a sphere of radius $\sqrt{n(m-n)}/m$ in \mathbb{R}^D , we can apply the Rankin bounds for spherical codes [Rankin 1955], and deduce:

Corollary 5.2 (The simplex bound). *For a packing of N planes in $G(m, n)$,*

$$d_c^2 \leq \frac{n(m-n)}{m} \frac{N}{N-1}. \tag{5.2}$$

Equality requires $N \leq D + 1 = \binom{m+1}{2}$, and occurs if and only if the N points in \mathbb{R}^D corresponding to the planes form a regular “equatorial” simplex.

Corollary 5.3 (The orthoplex bound). *For $N > \binom{m+1}{2}$,*

$$d_c^2 \leq \frac{n(m-n)}{m}. \tag{5.3}$$

Equality requires $N \leq 2D = (m-1)(m+2)$, and occurs if the N points form a subset of the $2D$ vertices of a regular orthoplex. If $N = 2D$ this condition is also necessary.

Lemmons and Seidel ([Lemmens and Seidel 1973b], Theorem 3.6) give a bound for equi-isoclinic packings in $G(m, n)$ which agrees with (5.2); of course our bound is more general. The case $n = 1$ of (5.2) is given in Theorem 3 of [Rosenfeld a].

We were happy to obtain confirmation of (5.1). Since d_c^2 can never exceed n , we can also write

$$d_c^2 \leq \min \left\{ n, \frac{n(m-n)}{m} \frac{N}{N-1} \right\}. \tag{5.4}$$

Corollaries 5.2 and 5.3 allow us to establish the optimality of many of our packings. In the range $m \leq 16, n \leq 3, N \leq 55$, there are over 750 cases which appear to meet (5.4) or (5.3), in the sense that the ratio of d_c^2 to the bound is greater than 0.9999999. Table 3 lists these cases for $n = 2$ and $4 \leq m \leq 10$.

However, this is not as meaningful as it at first seems. Consider Table 4, which gives the ratio of d_c^2 to the simplex bound for packings of $N = 21, \dots, 33$ planes in $G(10, 2)$. From this table it seems very likely that there exists a 27-plane pack-

m	(5.4)	(5.3)	m	(5.4)	(5.3)
4	2–8,10	11–18	8	4–21, 28	37–44
5	4–11	16,17	9	6–25	
6	3–14	22, 23	10	5–28	
7	6–18	29			

TABLE 3. Values of N for which the packings of N planes in $G(m, 2)$ appear to achieve the bounds (5.4) or (5.3).

N	ratio	N	ratio
21	0.99999999999999	28	0.99999999921354
22	1.00000000000000	29	0.99999470290071
23	0.99999999999999	30	0.99998661084736
24	0.99999999999999	31	0.99961159256647
25	1.00000000000000	32	0.99909699728979
26	0.99999999999999	33	0.99854979246655
27	1.00000000000000		

TABLE 4. Ratio of d_c^2 to the bound of Corollary 5.2 for N planes in $G(10, 2)$, rounded to 14 decimal places.

ing meeting the simplex bound, but certainly further investigation is needed to determine if there is a 28-plane simplex packing in the neighborhood of the computer's approximate solution. We have carried out such analyses in all the putative cases of equality for packing lines (see Sect. 6), for planes in $G(4, 2)$ (as already discussed) and for 70 planes in $G(8, 4)$ (see below). The other cases remain to be investigated.

In principle there is no difficulty in settling these questions. All the chordal distances between the planes are specified. So we could simply set up a (large) system of quartic equations with integer coefficients for the entries in the generator matrices, and ask if there is a real solution.

The chief difficulty in attempting to understand the computer-generated packings is that there are usually very large numbers of equally good solutions. The case of 18 planes in $G(4, 2)$ is typical in this regard. There is one exceptionally pleasing solution (described in Section 4), in which only three different pairs of principal angles occur. However, it seems that there is a roughly 29-dimensional manifold of solutions, in which a typical solution, although still having $d_c^2 = 1$, has an apparently random set of principal angles. Our investigation of this question is not yet completed.

The case of subspaces of dimension n in \mathbb{R}^{2n} or \mathbb{R}^{2n+1} is especially interesting. Table 5 summarizes the possible cases where the bounds can be achieved. It is known that the orthoplex bound cannot be achieved by 10 planes in $G(3, 2)$, while the other cases are undecided. Our computer ex-

m	n	(5.4)	(5.3)	m	n	(5.4)	(5.3)
2	1	3*	4*	6	3	21	40
3	1	6*	10	7	3	28*	54
4	2	10*	18*	8	4	36	70*
5	2	15	28				

TABLE 5. Largest values of N for which the packings of N planes in $G(m, n)$ can achieve the bounds (5.4) or (5.3). An asterisk means the bound is achieved.

periments strongly suggest that no set of 15 planes meets the simplex bound in $G(5, 2)$.

On the other hand, it is possible to find packings of 70 planes in $G(8, 4)$ meeting the bound (5.3). With a considerable amount of effort (a long story, not told here), we determined several examples, of which the following is the most symmetrical. Let the coordinates be labeled $\infty, 0, 1, \dots, 6$, and take the two 4-planes generated by the vectors

$$\begin{aligned} &\{10000000, 01000000, 00100000, 00001000\}, \\ &\{11000000, 00101000, 00010001, 00000110\}. \end{aligned} \tag{5.5}$$

From them we get 70 planes by negating any even number of coordinates, and by applying the coordinate permutations (0123456) , $(\infty 0)(16)(23)(45)$, and $(124)(365)$. The principal angles are given by $(0, 0, \pi/2, \pi/2)$, $(\pi/4, \pi/4, \pi/4, \pi/4)$, or $(\pi/2, \pi/2, \pi/2, \pi/2)$, so $d_c^2 = 2$ and $d_g^2 = \pi^2/4$ (this is not even a local optimum with respect to geodesic distance). The full group, which is transitive on the planes, is generated by the above operations and by the 8×8 Hadamard matrix

$$\frac{1}{\sqrt{8}} \begin{bmatrix} - & - & - & - & - & - & - & - \\ - & + & - & - & + & - & + & + \\ - & - & - & + & - & + & + & + \\ - & - & + & - & + & + & + & - \\ - & + & - & + & + & + & - & - \\ - & - & + & + & + & - & - & + \\ - & + & + & + & - & - & + & - \\ - & + & + & - & - & + & - & + \end{bmatrix},$$

where $-$ means -1 and $+$ means $+1$. It has shape $2^8 \mathcal{A}_8$ and order 5160960 (\mathcal{A}_n denotes an alternating group of degree n).

A set of 28 planes in $G(7, 3)$ meeting the simplex bound can be obtained as follows. Label the coordinates $0, \dots, 6$, and let v_r^\pm have components 1 at $2^r \bmod 7$, $\pm\sqrt{2}$ at $3 \cdot 2^r \bmod 7$, and 0's elsewhere, for $r = 0, 1, 2$. Then the vectors $v_0^\pm, v_1^\pm, v_2^\pm$ (where the product of signs is even) span four planes, and the full set of 28 is found by cycling the seven coordinates.

(Note added April 1996. P. W. Shor and Sloane have recently discovered that the packing of 70 planes in $G(8, 4)$ can be generalized to a packing

of $m^2 + m - 2$ planes in $G(m, \frac{1}{2}m)$ meeting the orthoplex bound, whenever $m \geq 2$ is a power of 2; and that the packing of 28 planes in $G(7, 3)$ can be generalized to a packing of $\frac{1}{2}p(p + 1)$ planes in $G(p, \frac{1}{2}(p - 1))$ meeting the simplex bound, whenever p is a prime which is either 3 or congruent to -1 modulo 8. These constructions will be described elsewhere.)

On the other hand, in spite of much effort, we have not been able to find a set of 40 planes in $G(6, 3)$ that meet the bound. If this were possible, we would obtain $d_c^2 = 1.5$, whereas the best we have been able to achieve is 1.49977. We can get 1.5 with $N = 34$ planes, and 1.49977 with $35 \leq N \leq 40$, but only 1.4297 with 41 planes, which suggests that 1.5 might be possible with 40 planes. The discussion given earlier shows that this question could in principle be settled by seeing if a

certain set of quartic equations with integer coefficients has a real solution. One formulation leads to 500 quartic equations in 360 unknowns, so this approach seems hopeless at the present time.

It is not difficult to invent ways to construct sets of subspaces. Several examples are given below. However, many promising ideas have proved useless when confronted with the results found by our program. For this reason we have included two extensive tables of the best chordal distances that we have found. Table 6 gives d_c^2 for packings in $G(m, 2)$, with $m \leq 10$. This will serve as a standard against which readers can test their own constructions.

General Constructions

We now proceed to list some promising general constructions.

N	$m = 4$	$m = 5$	$m = 6$	$m = 7$	$m = 8$	$m = 9$	$m = 10$	N	$m = 4$	$m = 5$	$m = 6$	$m = 7$	$m = 8$	$m = 9$	$m = 10$
3	1.5000	1.7500	2.0000	2.0000	2.0000	2.0000	2.0000	27	0.8056	1.1045	1.3071	1.4606	1.5556	1.6154	1.6615
4	1.3333	1.6000	1.7778	1.8889	2.0000	2.0000	2.0000	28	0.8005	1.0989	1.2987	1.4531	1.5556	1.6118	1.6593
5	1.2500	1.5000	1.6667	1.7854	1.8750	1.9375	2.0000	29	0.7889	1.0937	1.2887	1.4286	1.5455	1.6083	1.6571
6	1.2000	1.4400	1.6000	1.7143	1.8000	1.8667	1.9200	30	0.7809	1.0875	1.2804	1.4234	1.5398	1.6049	1.6552
7	1.1667	1.4000	1.5556	1.6667	1.7500	1.8148	1.8667	31	0.7760	1.0822	1.2675	1.4167	1.5342	1.6011	1.6527
8	1.1429	1.3714	1.5238	1.6327	1.7143	1.7778	1.8286	32	0.7691	1.0766	1.2588	1.4106	1.5304	1.5978	1.6501
9	1.1231	1.3500	1.5000	1.6071	1.6875	1.7500	1.8000	33	0.7592	1.0722	1.2526	1.4038	1.5244	1.5935	1.6476
10	1.1111	1.3333	1.4815	1.5873	1.6667	1.7284	1.7778	34	0.7549	1.0671	1.2447	1.3978	1.5216	1.5911	1.6448
11	1.0000	1.3200	1.4667	1.5714	1.6500	1.7111	1.7600	35	0.7489	1.0640	1.2430	1.3915	1.5158	1.5893	1.6431
12	1.0000	1.3064	1.4545	1.5584	1.6364	1.6970	1.7455	36	0.7477	1.0596	1.2345	1.3843	1.5086	1.5885	1.6414
13	1.0000	1.2942	1.4444	1.5476	1.6250	1.6852	1.7333	37	0.7286	1.0519	1.2272	1.3784	1.5000	1.5816	1.6364
14	1.0000	1.2790	1.4359	1.5385	1.6154	1.6752	1.7231	38	0.7198	1.0462	1.2239	1.3722	1.5000	1.5768	1.6334
15	1.0000	1.2707	1.4286	1.5306	1.6071	1.6667	1.7143	39	0.7095	1.0404	1.2206	1.3663	1.5000	1.5730	1.6305
16	1.0000	1.2000	1.4210	1.5238	1.6000	1.6593	1.7067	40	0.7066	1.0355	1.2149	1.3606	1.5000	1.5695	1.6289
17	1.0000	1.2000	1.4127	1.5179	1.5937	1.6528	1.7000	41	0.6992	1.0302	1.2115	1.3575	1.5000	1.5665	1.6242
18	1.0000	1.1909	1.4048	1.5126	1.5882	1.6471	1.6941	42	0.6948	1.0256	1.2079	1.3550	1.5000	1.5639	1.6213
19	0.9091	1.1761	1.3948	1.5078	1.5833	1.6420	1.6889	43	0.6844	1.0207	1.2037	1.3449	1.5000	1.5616	1.6192
20	0.9091	1.1619	1.3888	1.5026	1.5789	1.6374	1.6842	44	0.6831	1.0159	1.2007	1.3407	1.5000	1.5588	1.6174
21	0.8684	1.1543	1.3821	1.4987	1.5750	1.6333	1.6800	45	0.6809	1.0122	1.1969	1.3354	1.4839	1.5570	1.6160
22	0.8629	1.1419	1.3333	1.4912	1.5714	1.6296	1.6762	46	0.6793	1.0078	1.1941	1.3321	1.4821	1.5480	1.6099
23	0.8451	1.1332	1.3333	1.4859	1.5680	1.6263	1.6727	47	0.6732	1.0042	1.1924	1.3265	1.4574	1.5412	1.6072
24	0.8372	1.1251	1.3326	1.4790	1.5638	1.6232	1.6696	48	0.6667	1.0001	1.1907	1.3232	1.4490	1.5353	1.6045
25	0.8275	1.1178	1.3229	1.4725	1.5594	1.6204	1.6667	49	0.6667	0.9960	1.1873	1.3209	1.4430	1.5304	1.6019
26	0.8144	1.1113	1.3151	1.4666	1.5556	1.6177	1.6640	50	0.6667	0.9910	1.1841	1.3150	1.4370	1.5257	1.6003

TABLE 6. Values of d_c^2 for best packings found of $N \leq 50$ planes in $G(m, 2)$.

(i) A skew-symmetric conference matrix of order $4a$ yields a set of $4a$ unit vectors in \mathbb{C}^{2a} with Hermitian inner products $\pm i/\sqrt{4a-1}$ [Delsarte et al. 1975, Example 5.8], hence a set of $4a$ planes in $G(4a, 2)$ with $d_c^2 = 4(2a-1)/(4a-1)$ that meet the simplex bound. (For a list of the known orders of such matrices, see [Seberry and Yamada 1992, Table 7.1].)

(ii) Use the planes defined by the n -faces of a regular m -dimensional polytope, or the Voronoi or Delaunay cells of a lattice, etc. The initial results from this idea have been disappointing. For example, the 96 two-dimensional faces of the 24-cell in \mathbb{R}^4 define 16 different planes, forming a packing with $d_c^2 = \frac{8}{9}$, inferior to the best such packing as seen in Table 6.

(iii) Use the minimal vectors in a complex or quaternionic lattice in order to obtain packings in $G(2a, 2)$ or $G(4a, 4)$. For example, the 54 minimal vectors of the lattice E_6^* , regarded as a three-dimensional lattice over the Eisenstein integers [Conway and Sloane 1996, p. 127], produce a packing of nine planes in $G(6, 2)$ that meets the simplex bound.

(iv) Restrict the search to generator matrices of 0's and 1's (as in (5.5)) or $+1$'s and -1 's, or even to rows that are blocks in some combinatorial design, or vectors in some error-correcting code (see the example in Section 6).

(v) Let C be an error-correcting code of length m over $\text{GF}(2^n)$, for example a Reed-Solomon code [MacWilliams and Sloane 1977]. If we see $\text{GF}(2^n)$ as a vector space of dimension n over $\text{GF}(2)$, each codeword yields an $n \times m$ matrix whose elements we may take to be $+1$'s and -1 's. After discarding those of rank less than n , and weeding out duplicates, we obtain a packing in $G(m, n)$. For example, the hexacode [Conway and Sloane 1996, p. 82], a code of length 6 over $\text{GF}(4)$ containing 64 codewords, produces 28 distinct planes in $G(6, 2)$ with $d_c^2 = 3/4$. Unfortunately Table 7 shows that the record is 1.2973.

(vi) Choose a group G with an m -dimensional representation, and a subgroup H of index N with an n -dimensional irreducible representation. Find an n -dimensional subspace $V \subseteq \mathbb{R}^m$ invariant under H , and take its orbit under G . Many of the conference matrix constructions of line-packings described in Section 6 are of this type (using $G = L_2(q)$).

In some cases we have also used the optimizer to search for packings with a specified group. The following is a packing of 28 planes in $G(8, 2)$ meeting the simplex bound that is an abstraction of a configuration found by the computer when searching for packings in \mathbb{R}^8 invariant under the permutation $(0)(1, 2, 3, 4, 5, 6, 7)$. Let $R : \mathbb{C}^4 \rightarrow \mathbb{R}^8$ map (v_1, v_2, v_3, v_4) to $(\text{Re } v_1, \text{Im } v_1, \text{Re } v_2, \dots, \text{Im } v_4)$, and let $\alpha = e^{2\pi i/7}$. The 28 planes are spanned by the following pairs of vectors, where k ranges from 0 to 6:

$$\begin{array}{ll} R(0, \alpha^k, \alpha^{2k}, \alpha^{4k}), & R(0, i\alpha^k, i\alpha^{2k}, i\alpha^{4k}), \\ R(1, 0, \alpha^{2k}, \alpha^{4k}), & R(i, 0, i\alpha^{2k}, -i\alpha^{4k}), \\ R(1, \alpha^k, 0, \alpha^{4k}), & R(i, -i\alpha^k, 0, i\alpha^{4k}), \\ R(1, \alpha^k, \alpha^{2k}, 0), & R(i, i\alpha^k, -i\alpha^{2k}, 0). \end{array}$$

The pattern of zeros and signs here suggests the tetracode [Conway and Sloane 1996, p. 81].

An Application: Apportioning Randomness

Here is a potential application of packings in Grassmannian spaces for use in apportioning randomness, in the sense of producing large numbers of approximately random points from a few genuinely random numbers. We illustrate using the example of 70 planes in $G(8, 4)$ described above. Let A_1, \dots, A_{70} be generator matrices for them. Suppose an exclusive resort wishes to distribute random points in \mathbb{R}^4 to its 70 guests, perhaps for use as garage door keys. Let $x = (x_1, \dots, x_8)$ be a vector of eight independent Gaussian random variates. Then the hotel would assign $y_i = A_i x^t$ to its i -th guest. By maximizing the chordal distance between the planes we have minimized the correlation between the y_i .

N	$m = 3$	$m = 4$	$m = 5$	$m = 6$	$m = 7$	$m = 8$	$m = 9$	N	$m = 3$	$m = 4$	$m = 5$	$m = 6$	$m = 7$	$m = 8$	$m = 9$
3	90.0000	90.0000	90.0000	90.0000	90.0000	90.0000	90.0000	27	28.2495	43.5530	53.5402	61.4053	70.5288	70.5392	71.6650
4	70.5288 ^b	90.0000	90.0000	90.0000	90.0000	90.0000	90.0000	28	27.8473	43.1566	53.2602	60.5276	70.5288 ^b	70.5322	71.5794
5	63.4349 ^f	75.5225 ^d	90.0000	90.0000	90.0000	90.0000	90.0000	29	27.5244	42.6675	53.0180	60.1344	66.7780	70.5288	71.5175
6	63.4349 ^c	70.5288 ^b	78.4630 ^d	90.0000	90.0000	90.0000	90.0000	30	26.9983	42.2651	52.7812	60.0213	65.7563	70.5288	71.5175
7	54.7356 ^f	67.0213	73.3689	80.4059 ^d	90.0000	90.0000	90.0000	31	26.4987	42.0188	52.4120	60.0000	65.1991	70.5288	70.8508
8	49.6399 ^f	65.5302	70.8039	76.0578	81.7868 ^d	90.0000	90.0000	32	25.9497	41.9554	52.3389	60.0000	64.7219	70.5288	70.7437
9	47.9821 ^f	64.2619	70.5288	73.8437	78.4630	82.8192 ^d	90.0000	33	25.5748	41.4577	52.2465	60.0000	64.6231	69.3203	70.6940
10	46.6746 ^f	64.2619	70.5288 ^b	73.6935	76.3454	79.4704	83.6206 ^d	34	25.2567	40.9427	51.8537	60.0000	64.6231	69.1688	70.6512
11	44.4031	60.0000	67.2543	71.5651	75.0179	77.8695	80.6204	35	24.8702	40.7337	51.8273	60.0000	64.6231	69.0752	70.6337
12	41.8820 ^f	60.0000 ^a	67.0213	71.5651	74.1734	76.6050	79.4704	36	24.5758	40.6325	51.8273	60.0000 ^a	64.6231	69.0752 ^e	70.5864
13	39.8131	55.4646	65.7319	70.5288	73.8979	76.1645	77.9422	37	24.2859	40.4486	51.8273	57.6885	62.3797	67.7827	70.5695
14	38.6824	53.8376	65.7241	70.5288	73.8979 ^c	75.0349	77.2382	38	24.0886	40.4419	50.3677	57.1057	62.1435	67.3835	70.5571
15	38.1349 ^f	52.5016	65.5302	70.5288	71.5678	74.3318	76.5006	39	23.8433	39.6797	50.0611	56.8357	61.7057	67.1387	70.5443
16	37.3774 ^f	51.8273	63.4349 ^e	70.5288 ^b	70.9861	74.1005	75.9638	40	23.3293	39.0236 ^e	49.5978	56.0495	61.3792	66.3815	70.5288
17	35.2353	50.8870	61.2551	68.1088	70.5926	73.1371	75.9638	41	22.9915	38.5346	49.2600	55.8202	61.1630	65.9282	70.5288
18	34.4088	50.4577	61.0531	67.3744	70.5527	72.7464	75.9638 ^c	42	22.7075	38.3094	48.6946	55.6160	60.8232	65.8166	70.5288
19	33.2115	49.7106	60.0000	67.3700	70.5288	72.0756	74.4577	43	22.5383	37.7833	48.4030	55.3981	60.5193	65.2885	70.5288
20	32.7071	49.2329	60.0000 ^f	67.0996	70.5288	71.6706	74.2278	44	22.2012	37.3474	48.0955	55.1259	60.3623	65.2422	70.5288
21	32.2161	48.5479	57.2025	67.0213	70.5288	71.3521	73.7518	45	22.0481	37.1198	47.7723	54.9980	60.2282	64.7476	70.5288
22	31.8963	47.7596	56.3558	65.9052 ^e	70.5288	71.0983	73.1894	46	21.8426	36.9997	47.3753	54.9858	60.1101	64.4007	70.5288
23	30.5062	46.5104	55.5881	63.6744	70.5288	70.7720	72.7488	47	21.6609	36.5952	47.0323	54.7356	60.0433	64.1542	70.5288
24	30.1628	46.0478	55.2279	63.6122	70.5288	70.6027	72.6547	48	21.4663	36.3585	46.7105	54.5940	60.0116	63.8846	70.5288 ^b
25	29.2486	44.9471	54.8891	62.4240	70.5288	70.5490	72.3124	49	21.1610	36.1369	46.4345	54.5031	60.0000	63.4849	68.0498
26	28.7126	44.3536	54.2116	61.7377	70.5288	70.5432	72.1763	50	20.8922	36.0754	46.1609	54.3191	60.0000 ^a	63.1527	67.7426

TABLE 7. Maximal angular separation found for $N \leq 50$ lines in $G(m, 1)$. Superscript key: “a” and “b” indicate constructions from sphere packings, “c” from conference matrices, and “d” from diplo-simplices; “e” indicates a packing described below, and “f” one described in Section 3.

6. PACKING LINES IN HIGHER DIMENSIONS

Table 7 shows the maximal angular separation we have found for packings of $N \leq 50$ lines in $G(m, 1)$ for $m \leq 9$.

Table 8 shows the packings of N lines in $G(m, 1)$, for $m \leq 10$, that achieve either the simplex or orthoplex bounds. Most of them are described below.

m	N	m	N
3	3, 4, 6, 7	7	7, 8, 14, 28
4	4, 5, 11, 12	8	8, 9
5	5, 6, 10, 16	9	9, 10, 18, 46–48
6	6, 7, 16, 22	10	10, 11, 16

TABLE 8. Values of N for which the packings of N planes in $G(m, 1)$ appear to achieve either the simplex or orthoplex bounds.

As mentioned in Section 3, the best packing of 5 lines in $G(3, 1)$ is a subset of the best packing of 6 lines. Table 4 shows similar phenomena in higher dimensions. For example, the putatively best packing of 48 lines in $G(9, 1)$ is so good that we cannot do better even when up through 8 lines are omitted from it.

In the rest of this section we discuss some of the entries in Table 7 that have the largest symmetry groups.

Constructions from Lattices

Let P_1, \dots, P_a be mutually touching spheres in a d -dimensional lattice packing. If there are $2N$ further spheres in the packing, each of which touches all of P_1, \dots, P_a , their centers form a $(d - a + 1)$ -dimensional antipodal spherical code with angular

separation $\arccos(a+1)$ [Conway and Sloane 1996, p. 340, Theorem 1].

In particular, the entries with a superscript “a” in Table 7 are obtained from the centers of spheres that touch one sphere in the lattices D_4 , D_5 , E_6 and E_7 . The entries with a superscript “b” are obtained from spheres that touch two spheres in the lattices D_4 , D_5 , E_6 , E_7 , E_8 , A_9 and the nonlattice packing P_{10b} [Conway and Sloane 1996, Chapter 1, Table 1.2]. We remark the set of 28 lines in $G(7, 1)$ with angle $\arccos \frac{1}{3}$ obtained in this way from E_8 is known to be unique: see [Conway and Sloane 1996, Chapter 14, Theorem 12]. This configuration of lines is derived in a different way in [Lint and Seidel 1966].

It is interesting to compare Table 7 with the table of maximal sets of equiangular lines given in Lemmens and Seidel [Lemmens and Seidel 1973a] and Seidel [Seidel 1994]. Some arrangements appear in both tables, for example the set of 28 lines in $G(7, 1)$ just mentioned. On the other hand the difference between the tables can be seen in dimension 8. The maximal set of equiangular lines that exists in $G(8, 1)$ has size 28, with angle $\arccos 3$ ([Lemmens and Seidel 1973a], Theorem 4.6). However, Table 7 shows that there is a set of 28 lines (not equiangular) in $G(8, 1)$ with minimal angle $\arccos 3.000511\dots$. In view of the Lemmens–Seidel result (which uses the fact that in an m -dimensional equiangular arrangement of N lines with $N \geq 2m$ the secant must be an odd integer) our set of 28 lines cannot be perturbed to give an equiangular set without decreasing the minimal angle.

Constructions from Conference Matrices

It follows from [Lint and Seidel 1966, Theorem 6.3] that if a symmetric conference matrix of order $q+1 \equiv 2 \pmod{4}$ exists then there is an arrangement of $q+1$ equiangular lines in \mathbb{R}^m , $m = \frac{1}{2}(q+1)$, with $d_c^2 = (q-1)/q$, meeting the simplex bound. The corresponding entries have the superscript “c” in the table. Our program was able to find these packings for every prime power q of this form below 100 except for 49 and 81.

Constructions from Diplo-Simplices

The entries with a superscript “d” are obtained by using all the vectors of shape $\pm c(n^1, (-1)^n)$, where $c = 1/\sqrt{n(n+1)}$. In the notation of [Conway and Sloane 1996, Chap. 4], they are the minimal vectors in the translates of the root lattice A_n by the glue vectors $[1]$ and $[-1]$. They form the vertices of a diplo-simplex [Conway and Sloane 1991], and have automorphism group $2 \times A_{n+1}$. These packings also meet the simplex bound.

Constructions from Codes

Let C be a binary code of length m , size M and minimal distance d which is closed under complementation. Writing the codewords as vectors of ± 1 's, we obtain a packing of $\frac{1}{2}M$ lines in $G(m, 1)$ with $d_c^2 = 4d(m-d)/m^2$. For example, a shortened Hamming code of length 10 with $M = 32$, $d = 4$ gives a packing of 16 lines in $G(10, 1)$ meeting the simplex bound. This construction provides a rich supply of good packings. The Nordstrom–Robinson code [Forney et al. 1993; Hammons et al. 1994], for example, yields a packing of 128 lines in $G(16, 1)$ with $d_c^2 = \frac{15}{16}$.

40 lines in $G(4, 1)$

The 80 antipodal points are given by $(\xi^{\mu+1/2}, 0)$, $(0, \xi^{\nu+1/2})$, $(a\xi^{2\mu}, b\xi^{2\nu+1})$, $(a\xi^{2\mu+1}, b\xi^{2\nu})$, $(b\xi^{2\mu}, a\xi^{2\nu})$, $(b\xi^{2\mu+1}, a\xi^{2\nu+1})$, where $\xi = e^{2\pi i/8}$, $\mu, \nu = 0, \dots, 3$, $a = 2^{-1/4}$, $b = \sqrt{1-a^2}$. The group of these 80 points is the group $\frac{1}{2}(\mathcal{D}_{16} + \mathcal{D}_{16}) \cdot 2$ of order 256 (see [Conway and Sloane a]). Here \mathcal{D}_m denotes a dihedral group of order m .

22 lines in $G(6, 1)$

We use the vertices of a hemi-cube (an alternative way to describe the 16-line packing) together with the six coordinate axes.

63 and 64 lines in $G(7, 1)$

The putatively best packing of 63 lines in $G(7, 1)$ (just beyond the range of Table 7) has angular separation 60° , and is formed from the 126 minimal

vectors of the lattice E_7 . The automorphism group of this set of 126 points is the Weyl group $\mathcal{W}(E_7)$, of order $2^{10} \cdot 3^4 \cdot 5 \cdot 7$. Compare [Conway and Sloane 1996, Chapter 4, § 8.3].

The best packing found of 64 lines in $G(7, 1)$ also has an unusually large group, of order $2|\mathcal{W}(E_6)| = 2^8 \cdot 3^4 \cdot 5$. This packing can be obtained as follows. The largest gaps between the packing of 63 lines occur in the directions of the minimal vectors of the dual lattice E_7^* . Let u be such a vector, with $u = \frac{1}{2}v_6$, $v_6 \in E_7$, $v_6 \cdot v_6 = 6$. Taking a coordinate frame in which the last coordinate is in the v_6 direction, we obtain the minimal vectors of E_7 in the form $(w, 0)$, $w \in E_6$, $w \cdot w = 2$ (72 vectors), and $(x, \pm\sqrt{2/3})$, $x \in E_6^*$, $x \cdot x = \frac{4}{3}$ (54 vectors). We now adjoin $\pm\sqrt{6}$ and rescale by multiplying the last coordinate by $\sqrt{3/4}$, obtaining our final configuration of vectors $(0, \pm 3/\sqrt{2})$, $(w, 0)$, $(x, \pm 1/\sqrt{2})$, which is isomorphic to what the computer found. The rescaling has compressed the E_7 lattice in the v_6 direction until the angle between v_6 and the $(x, 1/\sqrt{2})$ vectors is the same as the minimal angle between the $(x, 1/\sqrt{2})$ and $(w, 0)$ vectors. This angle, the minimal angle in the packing, is $\arccos \sqrt{3/11} = 58.5178^\circ$.

36 lines in $G(8, 1)$

The 72 antipodal points consist of all permutations of the two vectors $c(7^2, -2^7)$ and $c(-7^2, 2^6)$, where $c = 1/\sqrt{126}$. These are the minimal vectors in the translates of the A_8 lattice by the glue vectors [2] and [-2].

The configuration of 16 lines in $G(5, 1)$ is similarly obtained from the translates of A_5 by [1], [3] and [5].

39 lines in $G(12, 1)$

Take the 13 lines of a projective plane of order 3, described by vectors of four 1's and nine 0's, and replace two of the 1's by -1's in all possible ways, obtaining 78 vectors in \mathbb{R}^{12} with angle $\arccos 4$. The group is $2 \times L_3(3)$, of order $2^5 3^3 13$.

If instead we replace any *odd* number of the 1's by -1's, we obtain a putatively optimal packing of 52 lines in $G(13, 1)$, with angle $\arccos 4$ and group $2 \times L_3(3) \cdot 2$ of order $2^6 3^3 13$.

As in all these examples, we were amazed that the program was able to discover such beautiful configurations.

ACKNOWLEDGEMENTS

We are grateful to Daniel Asimov, Andreas Buja, Dianne Cook, Simon Kochen, Warren Smith, and especially Colin Mallows for helpful discussions, and to David Applegate for help in solving the matching problem described in Section 4.

ELECTRONIC AVAILABILITY

The results of our computations are available in the netlib archive, at the address <http://netlib.att.com/math/sloane/grass>.

REFERENCES

- [Anderson 1984] T. W. Anderson, *An Introduction to Multivariate Statistical Analysis*, Wiley, New York, 2nd ed., 1984, Chap. 12.
- [Applegate et al. 1995] D. Applegate, R. Bixby, V. Chvátal and W. Cook, "Finding cuts in the TSP (a preliminary report)", DIMACS Technical Report 95-05, Rutgers University, 1995.
- [Asimov 1985] D. Asimov, "The Grand Tour: a tool for viewing multidimensional data", *SIAM J. Sci. Stat. Comput.* **6** (1985), 128–143.
- [Björck and Golub 1973] A. Björck and G. H. Golub, "Numerical methods for computing angles between linear subspaces", *Math. Comp.* **27** (1973), 579–594.
- [Buja and Asimov 1986] A. Buja and D. Asimov, "Grand Tour methods: an outline", pp. 63–67 in *Computer Science and Statistics, 17th Symposium on The Interface*, Lexington, KY, 1985 (edited by D. M. Allen), Elsevier, Amsterdam, 1986.
- [Chow 1949] W.-L. Chow, "On the geometry of algebraic homogeneous spaces", *Annals Math.* **50** (1949), 32–67.

- [Conway and Kochen] J. H. Conway and S. Kochen, *Geometry and quantum logic*, in preparation.
- [Conway and Sloane 1991] J. H. Conway and N. J. A. Sloane, "The cell structures of certain lattices", pp. 71–107 in *Miscellanea mathematica* (edited by P. Hilton, et al.), Springer, New York, 1991.
- [Conway and Sloane 1996] J. H. Conway and N. J. A. Sloane, *Sphere Packings, Lattices and Groups*, 2nd ed., Springer, New York, 1993.
- [Conway and Sloane a] J. H. Conway and N. J. A. Sloane, "The four-dimensional point groups—a revised enumeration", in preparation.
- [Coxeter 1950] H. S. M. Coxeter, "Self-dual configurations and regular graphs", *Bull. Amer. Math. Soc.* **56** (1950), 413–455.
- [Coxeter 1974] H. S. M. Coxeter, "Polyhedral numbers", pp. 25–35 in *For Dirk Struik* (edited by R. S. Cohen et al.), Reidel, Dordrecht, 1974.
- [Coxeter and Moser 1980] H. S. M. Coxeter and W. O. J. Moser, *Generators and Relations for Discrete Groups*, 4th ed., Springer, New York, 1980.
- [Delsarte et al. 1975] P. Delsarte, J. M. Goethals and J. J. Seidel, "Bounds for systems of lines, and Jacobi polynomials", *Philips Research Reports* **30** (1975), 91–105.
- [Du Val 1964] P. Du Val, *Homographies, Quaternions and Rotations*, Oxford Univ. Press, 1964.
- [Fejes Tóth 1965] L. Fejes Tóth, "Distribution of points in the elliptic plane", *Acta Math. Acad. Sci. Hungar.* **16** (1965), 437–440.
- [Forney et al. 1993] G. D. Forney, Jr., N. J. A. Sloane, and M. D. Trott, "The Nordstrom-Robinson code is the binary image of the octacode", pp. 19–26 in *Coding and Quantization*, DIMACS/IEEE, 1992 (edited by R. Calderbank, et al.), Amer. Math. Soc., Providence, 1993.
- [MacKenzie and Morgan 1995] H. Gluck, D. MacKenzie and F. Morgan, "Volume-minimizing cycles in Grassmann manifolds", *Duke Math J.* **79** (1995), 335–404.
- [Golub and Van Loan 1989] G. H. Golub and C. F. Van Loan, *Matrix Computations*, 2nd ed., Johns Hopkins Univ. Press, Baltimore, 1989.
- [Griffiths and Harris 1978] P. Griffiths and J. Harris, *Principles of Algebraic Geometry*, Wiley, New York, 1978.
- [Hammons et al. 1994] A. R. Hammons, Jr., P. V. Kumar, A. R. Calderbank, N. J. A. Sloane, and P. Solé, "The \mathbb{Z}_4 -Linearity of Kerdock, Preparata, Goethals and Related Codes", *IEEE Trans. Information Theory* **40** (1994), 301–319.
- [Hardin and Sloane 1992] R. H. Hardin and N. J. A. Sloane, "Operating manual for Gosset: A general-purpose program for constructing experimental designs", 2nd ed., Statistics Research Report 106, AT&T Bell Laboratories, 1992; also DIMACS Technical Report 93–51, Rutgers University, 1993.
- [Hardin and Sloane 1993] R. H. Hardin and N. J. A. Sloane, "A new approach to the construction of optimal designs", *J. Statistical Planning and Inference* **37** (1993), 339–369.
- [Hardin et al. 1993–95] R. H. Hardin, N. J. A. Sloane and W. D. Smith, Tables of spherical codes in dimensions 3, 4, 5, <http://netlib.att.com/math/sloane/packings>. The tables are based on our own calculations, with additional packings provided by D. A. Kottwitz and J. Buddenhagen, and are believed to contain the best packings known with $N \leq 130$ points in dimensions 3, 4 and 5.
- [Hardin et al. a] R. H. Hardin, N. J. A. Sloane, and W. D. Smith, *Spherical Codes*, in preparation.
- [Hooke and Jeeves 1961] R. Hooke and T. A. Jeeves, "'Direct search' solution of numerical and statistical problems", *J. Assoc. Comput. Math.* **8** (1961), 212–229.
- [Hudson 1905] R. W. H. T. Hudson, *Kummer's Quartic Surface*, Cambridge Univ. Press, 1905.
- [James and Constantine 1974] A. T. James and A. G. Constantine, "Generalized Jacobi polynomials as spherical functions of the Grassmann manifold", *Proc. London Math. Soc.* **29** (1974), 174–192.
- [Leichtweiss 1961] K. Leichtweiss, "Zur Riemannschen Geometrie in Grassmannschen Mannigfaltigkeiten", *Math. Zeit.* **76** (1961), 334–366.
- [Lemmens and Seidel 1973a] P. W. H. Lemmens and J. J. Seidel, "Equiangular lines", *J. Algebra* **24** (1973), 494–512.

- [Lemmens and Seidel 1973b] P. W. H. Lemmens and J. J. Seidel, “Equi-isoclinic subspaces of Euclidean space”, *Konink. Ned. Akad. Wet.* **A76** (1973), 98–107.
- [Lint and Seidel 1966] J. H. van Lint and J. J. Seidel, “Equilateral point sets in elliptic geometry”, *Proc. Kon. Nederl. Akad. Wet.* **A69** (1966), 335–348.
- [MacWilliams and Sloane 1977] F. J. MacWilliams and N. J. A. Sloane, *The Theory of Error-Correcting Codes*, Elsevier, Amsterdam, 1977.
- [Nash 1956] J. Nash, “The imbedding problem for Riemannian manifolds”, *Annals Math.* **63** (1956), 20–63.
- [Rankin 1955] R. A. Rankin, “The closest packing of spherical caps in n dimensions”, *Proc. Glasgow Math. Assoc.* **2** (1955), 139–144.
- [Rosenfeld 1993] M. Rosenfeld, Problem No. 10293, *Amer. Math. Monthly* **100** (1993), 291.
- [Rosenfeld 1994] M. Rosenfeld, “How wide can you spread your chopsticks?” *Congressus Numerantium* **102** (1994), 29–31.
- [Rosenfeld a] M. Rosenfeld, “In praise of the Gram matrix”, preprint.
- [Rosenmann 1992] J. Rosenman, “The rotation group and cancer treatment”, Electronic message posted to sci.math (Internet newsgroup), Oct. 29, 1992.
- [Seberry and Yamada 1992] J. Seberry and M. Yamada, “Hadamard matrices, sequences, and block designs”, pp. 431–560 in *Contemporary Design Theory* (edited by J. H. Dinitz and D. R. Stinson), Wiley, New York, 1992.
- [Seidel 1994] J. J. Seidel, “Discrete non-Euclidean geometry”, Chapter 21 in *Handbook of Incidence Geometry* (edited by F. Buekenhout), North-Holland, Amsterdam, 1994.
- [Stephanos 1879] C. Stephanos, “Sur les systèmes desmiques de trois tétraèdres”, *Bull. Sci. Math.* **3** (1879), 424–456.
- [Swayne et al. 1991] D. F. Swayne, D. Cook and A. Buja, “XGobi: Interactive dynamic graphics in the X window system with a link to S”, pp. 1–8 in *ASA Proceedings Section on Statistical Graphics*, Amer. Stat. Assoc., Alexandria, VA, 1991.
- [Wong 1961] Y.-C. Wong, “Isoclinic n -Planes in Euclidean $2n$ -Space, Clifford Parallels in Elliptic $(2n - 1)$ -Space, and the Hurwitz Matrix Equations”, *Memoirs Amer. Math. Soc.* **41**, 1961.
- [Wong 1967] Y.-C. Wong, “Differential geometry of Grassmann manifolds”, *Proc. Nat. Acad. Sci. USA* **47** (1967), 589–594.
- [Zanella 1995] C. Zanella, “Embeddings of Grassmann spaces”, *J. Geometry* **52** (1995), 193–201.

John H. Conway, Department of Mathematics, Princeton University, Fine Hall, Washington Road, Princeton, NJ 08544 (conway@math.princeton.edu)

Ronald H. Hardin, Mathematical Sciences Research Center, AT&T Research, 600 Mountain Avenue, Murray Hill, NJ 07974 (rhh@research.att.com)

Neil J. A. Sloane, Mathematical Sciences Research Center, AT&T Research, 600 Mountain Avenue, Murray Hill, NJ 07974 (njas@research.att.com) — Corresponding author

Received December 12, 1995; accepted in revised form April 12, 1996